Lecture 23: Heisenberg Uncertainty Principle

Phy851 Fall 2009



Heisenberg Uncertainty Relation

 Most of us are familiar with the Heisenberg Uncertainty relation between position and momentum:

$$\Delta x \, \Delta p \ge \frac{\hbar}{2}$$

- How do we know this is true?
- Are the similar relations between other operators?



<u>Variance</u>

 The uncertainties are also called `variances' defined as
<A>→C+(A)+

- Note that the variance is state-dependent
- What does it tell us about our state?
 - Consider a distribution *P*(a),
 - The average of the distribution is:

$$\overline{a} = \sum_{a} P(a) a$$

- To estimate the *width* of the distribution we might consider the square of the distance from the mean: $d^2(a) = (a - \overline{a})^2$

The average of this quantity is

$$\overline{d^{2}}(a) = \sum_{a} P(a) \left(a^{2} - 2a\overline{a} + \overline{a}^{2} \right)$$
$$= \overline{a^{2}} - 2\overline{a}^{2} + \overline{a}^{2}$$
$$= \overline{a^{2}} - \overline{a}^{2}$$
$$d_{rms} := \sqrt{\overline{d^{2}}} = \sqrt{\overline{a^{2}} - \overline{a}^{2}}$$
$$\Delta a = \sqrt{\left\langle A^{2} \right\rangle - \left\langle A \right\rangle^{2}}$$

Incompatible Observables

- For an observable A, the only way you can have $\Delta a = 0$ is if you are in an eigenstate of A
- Consider two incompatible observables, A and B: $[A,B] = M \neq 0$
- We cannot have ΔA=0 and ΔB=0 at the same time
 - Then we would have a simultaneous eigenstate of A and B
- So what is the best we can do?
- To derive the Heisenberg Uncertainty for X and P relation, let us first introduce

$$X' = X - \langle X \rangle I$$
$$P' = P - \langle P \rangle I$$

$$\begin{bmatrix} X', P' \end{bmatrix} = \begin{bmatrix} X, P \end{bmatrix}$$

$$\left\langle X^{\prime 2} \right\rangle = \ddot{A}x^{2}$$
$$\left\langle P^{\prime 2} \right\rangle = \ddot{A}p^{2}$$



<u>Geometric Proof of Uncertainty</u> <u>Relation</u>

• Let: $|\phi\rangle := (X' + i\lambda P')\psi\rangle$

 λ is an arbitrary real number

 $|\psi\rangle$ is an arbitrary state

• For any λ and $|\psi\rangle$ we must have: $\langle \phi | \phi \rangle \ge 0$

$$\left\langle \psi \left| X^{\prime 2} \right| \psi \right\rangle - i\lambda \left\langle \psi \left| P^{\prime} X^{\prime} \right| \psi \right\rangle + i\lambda \left\langle \psi \left| X^{\prime} P^{\prime} \right| \psi \right\rangle + \lambda^{2} \left\langle \psi \left| P^{\prime 2} \right| \psi \right\rangle \ge 0$$

$$\langle P'^2 \rangle \lambda^2 + \langle i [X', P'] \rangle \lambda + \langle X'^2 \rangle \ge 0$$

 $\begin{bmatrix} X', P' \end{bmatrix} = \begin{bmatrix} X, P \end{bmatrix}$ $\begin{pmatrix} X'^2 \end{pmatrix} = \Delta x^2$ $\begin{pmatrix} P'^2 \end{pmatrix} = \Delta p^2$

$$\Delta p^{2} \lambda^{2} + \left\langle i [X, P] \right\rangle \lambda + \Delta x^{2} \ge 0$$



$\frac{\text{Parabolas}}{\Delta p^2 \lambda^2 + \left\langle i [X, P] \right\rangle \lambda + \Delta x^2 \ge 0}$

 Consider a general quadratic polynomial with real coefficients:

$$f(\lambda) = a\lambda^2 + b\lambda + c$$

Its graph is a parabola – If a>0 it opens up: k f(n) < 0b not alloved $\lambda_{\min} = -$ The minimum is at: 2aThe minimum value is: $f(\lambda_{\min}) = c - \frac{b^2}{4a}$ So $f(\lambda) \ge 0$ requires: $f(\lambda_{\min}) \ge 0 \implies ac \ge \frac{b^2}{4a}$ $\Delta x^{2} \Delta p^{2} \ge \frac{\left\langle i[X,P]\right\rangle^{2}}{4} \longrightarrow \Delta x \Delta p \ge \frac{\hbar}{2}$

Generalized Uncertainty Relations

• Note that only at the very end did we make use of the specific form of the commutator:

$$[X, P] = i\hbar$$

 This means that our result is valid in general for any two observables:

$$\Delta a^2 \Delta b^2 \ge \frac{\langle i[A,B] \rangle^2}{4} \implies \Delta a \Delta b \ge \frac{|\langle [A,B] \rangle|}{4}$$

• Consider angular momentum operators:

$$[L_x, L_y] = i\hbar L_z$$
$$\Delta l_x \Delta l_y \ge \frac{\hbar}{2} |\langle L_z \rangle|$$

- In General, the Heisenberg Lower limit depends on the state.
- X and P are special in that all states have the same limit.
- The Uncertainty relation is not as useful in the more general cases

