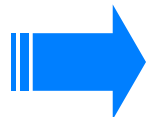


Lecture 26:
Angular Momentum II

Phy851 Fall 2009



The Angular Momentum Operator

- The angular momentum operator is defined as:

$$\vec{L} = \vec{R} \times \vec{P}$$

- It is a vector operator:

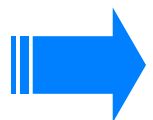
$$\vec{L} = L_x \vec{e}_x + L_y \vec{e}_y + L_z \vec{e}_z$$

- According to the definition of the cross-product, the components are given by:

$$L_x = YP_z - ZP_y$$

$$L_y = ZP_x - XP_z$$

$$L_z = XP_y - YP_x$$



Commutation Relations

- The commutation relations are given by:

$$[L_x, L_y] = i\hbar L_z$$

$$[L_y, L_z] = i\hbar L_x$$

$$[L_z, L_x] = i\hbar L_y$$

- These are not definitions, they are just a consequence of $[X,P]=i\hbar$
- Any three operators which obey these relations are considered as 'generalized angular momentum operators'
- Compact notation:

$$[L_j, L_k] = i\hbar \varepsilon_{jkl} L_l$$

Summation over l is implied

'Levi Cevita tensor'

ε_{jkl} {

- 0 if any two indices are the same
- 1 cyclic permutations of x,y,z (or 1,2,3)
- 1 cyclic permutations of z,y,x (or 3,2,1)



Simultaneous Eigenstates

- In the HW will see that:

$$[L^2, L_x] = 0$$

$$[L^2, L_y] = 0$$

$$[L^2, L_z] = 0$$

- Where:

$$L^2 = L_x^2 + L_y^2 + L_z^2$$

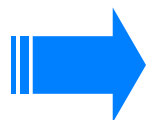
- This means that simultaneous eigenstates of L^2 and L_z exist

- Let:

$$L^2 |a, b\rangle = a |a, b\rangle$$

$$L_z |a, b\rangle = b |a, b\rangle$$

- We want to find the allowed values of a and b .



Algebraic solution to angular momentum eigenvalue problem

- In an analogy to what we did for the Harmonic Oscillator, we now define raising and lowering operators:

$$L_+ = L_x + iL_y$$

$$L_- = L_x - iL_y$$

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- Lets consider the action of L_+ first:

recall our approach for SHO: $A^\dagger A(A^\dagger|\epsilon\rangle) = (\epsilon + 1)(A^\dagger|\epsilon\rangle)$

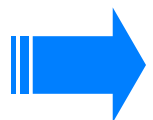
$$L_z(L_+|a,b\rangle) = L_z L_x|a,b\rangle + iL_z L_y|a,b\rangle$$

$$[L_z, L_x] = i\hbar L_y \quad \rightarrow \quad L_z L_x = i\hbar L_y + L_x L_z$$

$$[L_z, L_y] = -i\hbar L_x \quad \rightarrow \quad L_z L_y = -i\hbar L_x + L_y L_z$$

$$\begin{aligned} L_z(L_+|a,b\rangle) &= i\hbar L_y|a,b\rangle + L_x L_z|a,b\rangle + \hbar L_x|a,b\rangle + iL_y L_z|a,b\rangle \\ &= (L_x + iL_y)L_z|a,b\rangle + \hbar(L_x + iL_y)|a,b\rangle \end{aligned}$$

$$L_z(L_+|a,b\rangle) = (b + \hbar)L_+|a,b\rangle$$



Ladder Argument

$$L_z(L_+|a,b\rangle) = (b + \hbar)L_+|a,b\rangle$$

- Conclusion: if $|a,b\rangle$ is an eigenstate of L_z with eigenvalue b , then there is also an eigenstate $|a,b+\hbar\rangle$ with eigenvalue $b+\hbar$

- Thus we can say:

$$L_+|a,b\rangle = C_{+ab}|a,b+\hbar\rangle$$

- Similarly, we can readily show that:

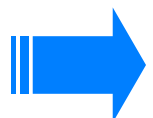
$$L_z(L_-|a,b\rangle) = (b - \hbar)L_-|a,b\rangle$$

- So that we must have also:

$$L_-|a,b\rangle = C_{-ab}|a,b-\hbar\rangle$$

- This allows us to say:

1. If $|a,b\rangle$ exists, then $|a,b+\hbar\rangle$ exists or $C_{+ab}=0$
2. If $|a,b\rangle$ exists, then $|a,b-\hbar\rangle$ exists or $C_{-ab}=0$



Establishing Some Lower Bounds

- Starting from:

$$L_x = YP_z - ZP_y$$

- It follows that

$$\begin{aligned} L_x^\dagger &= P_z^\dagger Y^\dagger - Z^\dagger P_y^\dagger \\ &= P_z Y - Z P_y \\ &= Y P_z - P_y Z \\ &= L_x \end{aligned}$$

- Which makes sense because L_x is an observable
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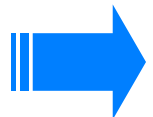
- Therefore, we have:

$$\begin{aligned} \langle a, b | L_x^2 | a, b \rangle &= \langle a, b | L_x^\dagger L_x | a, b \rangle \\ &= |L_x | a, b \rangle|^2 \end{aligned}$$

- Result:

$$\langle a, b | L_x^2 | a, b \rangle \geq 0$$

$$\langle a, b | L_y^2 | a, b \rangle \geq 0$$



The Trick

- We note that:

$$L^2 - L_z^2 = L_x^2 + L_y^2$$

$$\langle a, b | (L^2 - L_z^2) | a, b \rangle = \langle a, b | L_x^2 | a, b \rangle + \langle a, b | L_y^2 | a, b \rangle$$

- This means that:

$$\langle a, b | (L^2 - L_z^2) | a, b \rangle \geq 0$$

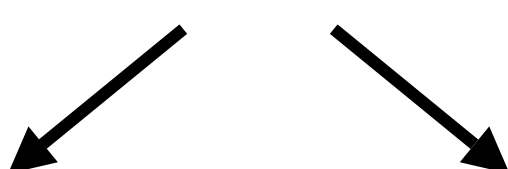
- By definition, we have:

$$(L^2 - L_z^2) | a, b \rangle = (a - b^2) | a, b \rangle$$

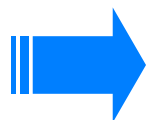
- Combining the two gives us:

$$a - b^2 \geq 0$$

$$a \geq b^2$$


$$a \geq 0$$

$$-\sqrt{a} \leq b \leq \sqrt{a}$$



The conclusion

$$a \geq 0$$

$$-\sqrt{a} \leq b \leq \sqrt{a}$$

- Conclusion:
 1. There is a b_{\min} for every allowed a
 2. There is a b_{\max} for every allowed a

$$-\sqrt{a} \leq b_{\min}(a) \quad b_{\max}(a) \leq \sqrt{a}$$

- Thus we must have:

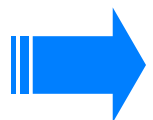
$$L_+ |a, b_{\max}(a)\rangle = 0$$

- So that no states with higher b can exist
- Which requires:

$$C_{+ab_{\max}(a)} = 0$$

- Similarly,

$$C_{-ab_{\min}(a)} = 0$$



Just a Little Further to Go...

$$C_{+ab_{\max}(a)} = 0 \quad C_{-ab_{\min}(a)} = 0$$

- If we have:

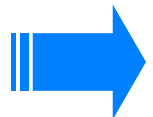
$$L_+ |a, b_{\max}(a)\rangle = 0$$

- Then we must have:

$$L_- L_+ |a, b_{\max}(a)\rangle = 0$$

-
- But:

$$\begin{aligned} L_- L_+ &= (L_x - iL_y)(L_x + iL_y) \\ &= L_x^2 + iL_x L_y - iL_y L_x + L_y^2 \\ &= L^2 - L_z^2 - \hbar L_z \\ &= L_x^2 + L_y^2 + i[L_x, L_y] \end{aligned}$$



Starting to see the light at the end of the tunnel...

$$L_- L_+ = L^2 - L_z^2 - \hbar L_z$$

$$L_- L_+ |a, b_{\max}(a)\rangle = 0$$

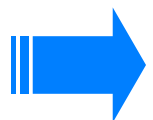
- This means:

$$(L^2 - L_z^2 - \hbar L_z) |a, b_{\max}\rangle = 0$$

$$(a - b_{\max}^2 - \hbar b_{\max}) |a, b_{\max}\rangle = 0$$

$$a - b_{\max}^2 - \hbar b_{\max} = 0$$

$$a = b_{\max}^2(a) - \hbar b_{\max}(a)$$



Not quite done yet...

$$L_- L_+ |a, b_{\max}(a)\rangle = 0 \quad \rightarrow \quad a = b_{\max}^2(a) - \hbar b_{\max}(a)$$

- Similarly, we can show that:

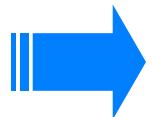
$$L_+ L_- |a, b_{\min}(a)\rangle = 0$$

- Which together with:

$$\begin{aligned} L_+ L_- &= (L_x + iL_y)(L_x - iL_y) \\ &= L_x^2 - iL_x L_y + iL_y L_x + L_y^2 \\ &= L_x^2 + L_y^2 - i[L_x, L_y] \\ &= L^2 - L_z^2 + \hbar L_z \end{aligned}$$

- Gives us:

$$a = b_{\min}^2(a) + \hbar b_{\min}(a)$$



Keep moving forward...

$$a = b_{\max}(a)(b_{\max}(a) + \hbar)$$

$$a = b_{\min}(a)(b_{\min}(a) - \hbar)$$

- From $a=a$ we get:

$$b_{\max}^2(a) + \hbar b_{\max}(a) = b_{\min}^2(a) - \hbar b_{\min}(a)$$

$$b_{\min}^2(a) - \hbar b_{\min}(a) - b_{\max}^2(a) - \hbar b_{\max}(a) = 0$$

- The solution is:

$$b_{\min} = \frac{1}{2} \left(\hbar \pm \sqrt{\hbar^2 + 4b_{\max}^2 + 4\hbar b_{\max}} \right)$$

$$b_{\min} = \frac{1}{2} \left(\hbar \pm (\hbar + 2b_{\max}) \right)$$

$\swarrow +$

$$b_{\min} = \hbar + b_{\max}$$

$\swarrow -$

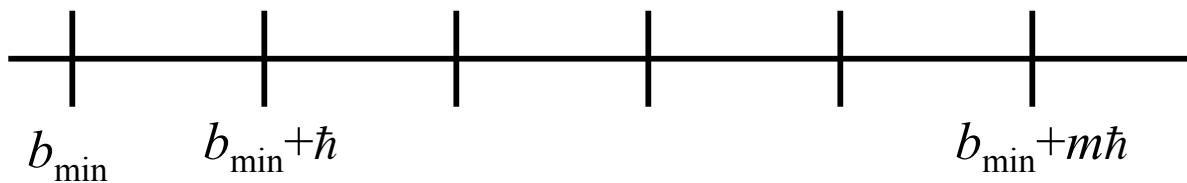
$$b_{\min} = -b_{\max}$$

$$b_{\min} < b_{\max}$$



Ladder Termination Requirement

- MAIN POINT SO FAR:
 - For a given a , $b_{\min}(a)$ and $b_{\max}(a)$ are the only b values from which the lowering/raising operators do not create new states.
- So we can build a ladder by starting at b_{\min} and acting with L_+ to create a new state at $b_{\min} + \hbar$, etc...



- The only way the ladder will terminate is if we have

$$b_{\max} = b_{\min} + N\hbar$$

- For some integer N

- With $b_{\min} = -b_{\max}$, this leads to: $2b_{\max} = N\hbar$

$$b_{\max} = \frac{N}{2}\hbar$$

- This means that the maximum z-component of angular momentum must always be a half-integer **or** whole integer times \hbar



Quantization of angular momentum

- Lets replace b_{\max} with the symbol $\ell \rightarrow \ell = N/2$.
- The allowed eigenvalues of L_z are then:

$$b = m\hbar; \quad m = -\ell, -\ell + 1, -\ell + 2, \dots, +\ell$$

- From the condition:

$$a = b_{\max}(a)(b_{\max}(a) + \hbar)$$

- We see that the corresponding eigenvalue of L^2 is:

$$a = \hbar\ell(\hbar\ell + \hbar)$$

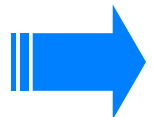
$$a = \hbar^2\ell(\ell + 1)$$

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- Conclusion:
 - We can relabel the states as: $|a, b\rangle \rightarrow |\ell, m\rangle$

- Then we have:

$$L^2|\ell, m\rangle = \hbar^2\ell(\ell + 1)|\ell, m\rangle$$

$$L_z|\ell, m\rangle = \hbar m|\ell, m\rangle$$



The FINAL SLIDE

- Now we have:

$$(L_+)^{\dagger} = L_-$$

$$|L_+|a,b\rangle|^2 = |C_{+ab}|^2$$

$$\begin{aligned} |L_+|a,b\rangle|^2 &= \langle a,b|L_-L_+|a,b\rangle \\ &= a - b^2 - \hbar b \end{aligned}$$

$$C_{+ab} = \sqrt{a - b^2 - \hbar b}$$

- Likewise:

$$C_{-ab} = \sqrt{a - b^2 + \hbar b}$$

$$a = \hbar^2 \ell(\ell + 1)$$

$$b = \hbar m$$

$$L_{\pm}|\ell, m\rangle = \hbar \sqrt{\ell(\ell + 1) - m(m \pm 1)}|\ell, m \pm 1\rangle$$

