

Chapter 7 problems, due Wed. Oct 31

7-3 Recall  $x = \sqrt{\frac{\hbar}{2m\omega}} (A + A^\dagger)$

where  $A|n\rangle = \sqrt{n}|n-1\rangle$

and  $A^\dagger|m\rangle = \sqrt{m+1}|m+1\rangle$

The eigenstates  $|n\rangle$  are orthonormal.

The matrix elements of  $x$

$$\langle n|x|m\rangle = \sqrt{\frac{\hbar}{2m\omega}} \langle n|A + A^\dagger|m\rangle$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left\{ \underbrace{\langle n| \sqrt{m} |m-1\rangle}_{\sqrt{m} \delta(n, m-1)} + \underbrace{\langle n| \sqrt{m+1} |m+1\rangle}_{\sqrt{m+1} \delta(n, m+1)} \right\}$$

(by orthonormality)

$$= \sqrt{\frac{\hbar}{2m\omega}} \left\{ \sqrt{m} \delta(n, m-1) + \sqrt{m+1} \delta(n, m+1) \right\}$$

Note that  $\langle n|x|m\rangle = 0$  unless  $n = m \pm 1$ .

7-4 Recall  $p = -i\sqrt{\frac{m\omega\hbar}{2}} (A - A^\dagger)$

By the same method as problem 7-3, the matrix elements of  $p$  are

$$\langle n|p|m\rangle = -i\sqrt{\frac{m\omega\hbar}{2}} \left\{ \sqrt{m} \delta(n, m-1) - \sqrt{m+1} \delta(n, m+1) \right\}.$$

7-5

(2)

$$\begin{aligned} \langle m | p_x | n \rangle &= \sum_{k=0}^{\infty} \langle m | p | k \rangle \langle k | x | n \rangle \\ &= \sum_{k=0}^{\infty} (-i) \sqrt{\frac{m\omega\hbar}{2}} \sqrt{\frac{\hbar}{2m\omega}} \\ &\quad \left\{ \sqrt{k} \delta(m, k-1) - \sqrt{k+1} \delta(m, k+1) \right\} \quad \text{using result of 7-4} \\ &\quad \left\{ \sqrt{n} \delta(k, n-1) + \sqrt{n+1} \delta(k, n+1) \right\} \quad \text{using result of 7-3} \end{aligned}$$

Identity :  $\sum_k \underbrace{\delta(k, a)}_{\text{unless } k=a} \delta(k, b) = \delta(a, b)$

unless  $k=a$  so  $\sum_k$  reduces to 1 term.

i.  $\langle m | p_x | n \rangle$

$$\begin{aligned} &= \frac{\hbar}{2i} \left\{ \sqrt{m+1} \sqrt{n} \delta(m+1, n-1) + \sqrt{m+1} \sqrt{n+1} \delta(m+1, n+1) \right. \\ &\quad \left. - \sqrt{m} \sqrt{n} \delta(m-1, n-1) - \sqrt{m} \sqrt{n+1} \delta(m-1, n+1) \right\} \end{aligned}$$

7-6  $\langle m | x | n \rangle = \sum_{k=0}^{\infty} (-i) \sqrt{\frac{m\omega\hbar}{2}} \sqrt{\frac{\hbar}{2m\omega}}$

$$\left\{ \sqrt{k} \delta(m, k-1) + \sqrt{k+1} \delta(m, k+1) \right\} \left\{ \sqrt{n} \delta(k, n-1) - \sqrt{n+1} \delta(k, n+1) \right\}$$

$$= \frac{\hbar}{2i} \left\{ \sqrt{m+1} \sqrt{n} \delta(m+1, n-1) - \sqrt{m+1} \sqrt{n+1} \delta(m+1, n+1) \right.$$

$$\left. + \sqrt{m} \sqrt{n} \delta(m-1, n-1) - \sqrt{m} \sqrt{n+1} \delta(m-1, n+1) \right\}$$

(3)

7-7 Now compute  $\langle m | [p, x] | n \rangle$

$$= \langle m | px | n \rangle - \langle m | xp | n \rangle \leftarrow (\text{these are from firm problems 7-5 and 7-6})$$

$$= \frac{\hbar}{2i} \left\{ 0 + 2\sqrt{m+1} \sqrt{n+1} \delta(m+1, n+1) \right. \\ \left. - 2\sqrt{m} \sqrt{n} \delta(m-1, n-1) + 0 \right\}$$

Note that  $\delta(m+1, n+1) = \delta(m-1, n-1) = \delta(m, n)$ .

Thus

$$\langle m | [p, x] | n \rangle = \frac{\hbar}{2i} \left\{ 2(n+1) - 2n \right\} \delta(m, n) \\ = \frac{\hbar}{i} \delta(m, n) \quad \underline{\text{as claimed.}}$$

7-13 Equation (7-63) is the equation of motion of an operator,

$$\frac{dB}{dt} = \frac{i}{\hbar} [H, B]. \quad (7-63)$$

Consider  $H = \frac{p^2}{2m} + mgx$ . Then

$$\frac{dx}{dt} = \frac{i}{\hbar} [H, x] = \frac{i}{\hbar} \left\{ \frac{1}{2m} [p^2, x] + mg [x, x] \right\} \\ \stackrel{!!}{=} 0$$

$$[p^2, x] = ppx - pxp + pxp - xpp$$

$$= p \underbrace{[p, x]}_{\hbar/i} + \underbrace{[p, x]}_{\hbar/i} p = \frac{2\hbar}{i} p$$

$$\frac{dx}{dt} = \frac{i}{\hbar} \frac{1}{2m} \frac{2\hbar}{i} p = \frac{p}{m}$$

$$\boxed{\frac{dx}{dt} = \frac{p}{m}} \quad (1)$$

and

$$\begin{aligned} \frac{dp}{dt} &= \frac{i}{\hbar} \left\{ \frac{1}{2m} [p^2, p] + mg [x, p] \right\} \\ &\quad \text{||} \quad \text{||} \\ &= \frac{i}{\hbar} mg \text{ it} = -mg \end{aligned}$$

$$\boxed{\frac{dp}{dt} = -mg} \quad (2)$$

The solution of (2) is

$$\boxed{p(t) = p(0) - mg t.}$$

Then (1) becomes  $\frac{dx}{dt} = \frac{p(0)}{m} - gt$  which

has the solution

$$\boxed{x(t) = x(0) + \frac{p(0)}{m} t - \frac{1}{2} g t^2}.$$

7-14

The Hamiltonian is  $H = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2 - e \Sigma z$ .

The first equation of motion is

$$\frac{dx}{dt} = \frac{i}{\hbar} [H, x] = \frac{p}{m}. \quad (1)$$

The second equation of motion is

$$\frac{dp}{dt} = \frac{i}{\hbar} [H, p] = \frac{i}{\hbar} \left\{ \frac{1}{2} m \omega^2 [x^2, p] - e \Sigma [x, p] \right\}$$

Note  $[x, p] = i\hbar$

$$[x^2, p] = \underbrace{xxp - xpx}_{x[x, p]} + \underbrace{xpx - pxp}_{[x, px]x} = 2i\hbar x$$

(5)

$$\therefore \frac{dp}{dt} = \frac{i}{\hbar} \left\{ \frac{m\omega^2}{2} 2itx - eEit \right\}$$

$$\frac{dp}{dt} = -m\omega^2 x + eE \quad (2)$$

Equations (1) and (2) are same as classical eqs.

Solution. Note that

$$\frac{d^2x}{dt^2} = \frac{1}{m} \frac{dp}{dt} \stackrel{\text{by (1)}}{=} -\omega^2 x + \frac{eE}{m} \stackrel{\text{by (2)}}{=}$$

The solution of this inhomogeneous linear equation is

$$x(t) = A \cos \omega t + B \sin \omega t + \frac{eE}{m\omega^2}$$

(The third term is the "particular solution") where A and B are constant operators determined from the initial conditions. Also,

$$p(t) = m \frac{dx}{dt} = -m\omega A \sin \omega t + m\omega B \cos \omega t$$

Initial values

$$x(0) = A + \frac{eE}{m\omega^2} \Rightarrow A = x(0) - \frac{eE}{m\omega^2}$$

$$p(0) = m\omega B \Rightarrow B = \frac{p(0)}{m\omega}$$

So 
$$x(t) = x(0) \cos \omega t + \frac{p(0)}{m\omega} \sin \omega t + \frac{eE}{m\omega^2} (1 - \cos \omega t)$$

Comment: At unequal times

$$[x(t_1), x(t_2)] = [x(0) \cos \omega t_1 + \frac{p(0)}{m\omega} \sin \omega t_1, x(0) \cos \omega t_2 + \frac{p(0)}{m\omega} \sin \omega t_2]$$

$$= \frac{2t_1}{m\omega} \cos \omega t_1 \sin \omega t_2 - \frac{2t_2}{m\omega} \sin \omega t_1 \cos \omega t_2$$

$$= \frac{2t_1}{m\omega} \sin [\omega(t_2 - t_1)].$$