

Lecture 19

Chapter 29 Magnetic Fields

Review

- Force due to a magnetic field is

$$\vec{F}_B = q\vec{v} \times \vec{B}$$

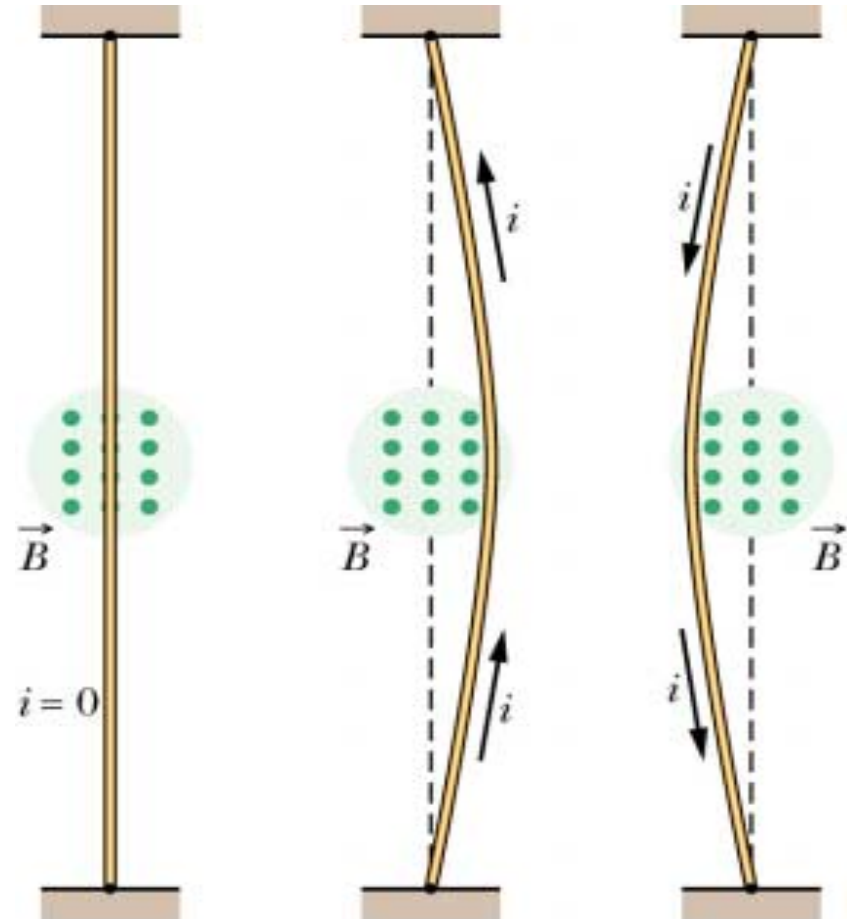
- Charged particles moving with $v \perp$ to a B field move in a circular path with radius, r

$$r = \frac{mv}{qB}$$

- Cyclotrons and synchrotrons

Review

- Demonstrated that a wire carrying current in a B field will feel a force
 - Wire jumped into (out of) horseshoe magnet when current was applied
- Change either direction of current or B field, reverses force on wire



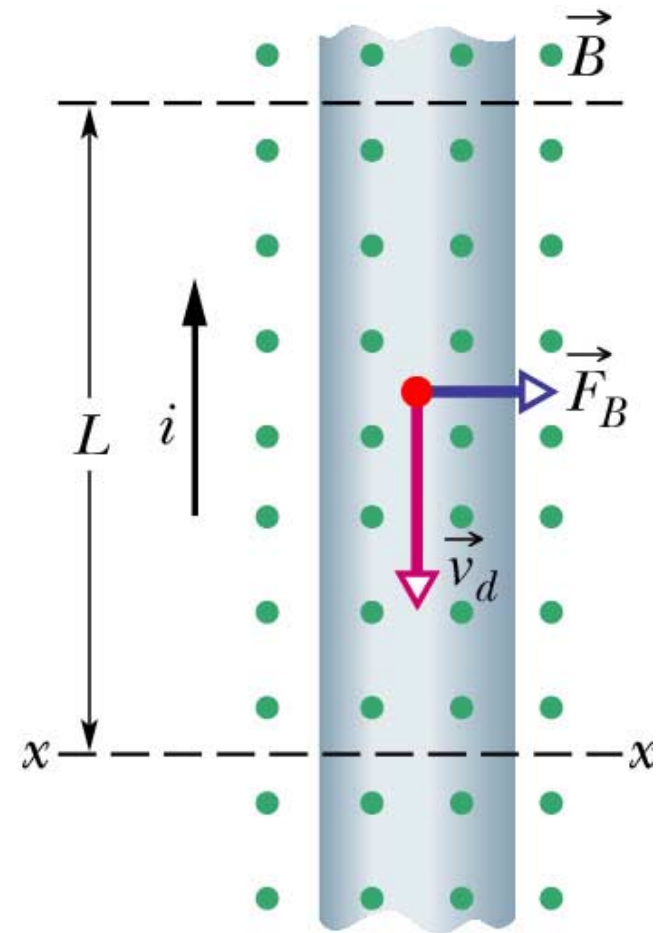
Magnetic Fields (47)

- Consider wire of length, L
- Conduction electrons drift past plane xx in time, t

$$t = \frac{L}{v_d}$$

- Amount of charge, q , passing through plane xx is then

$$q = it = i \frac{L}{v_d}$$



Magnetic Fields (48)

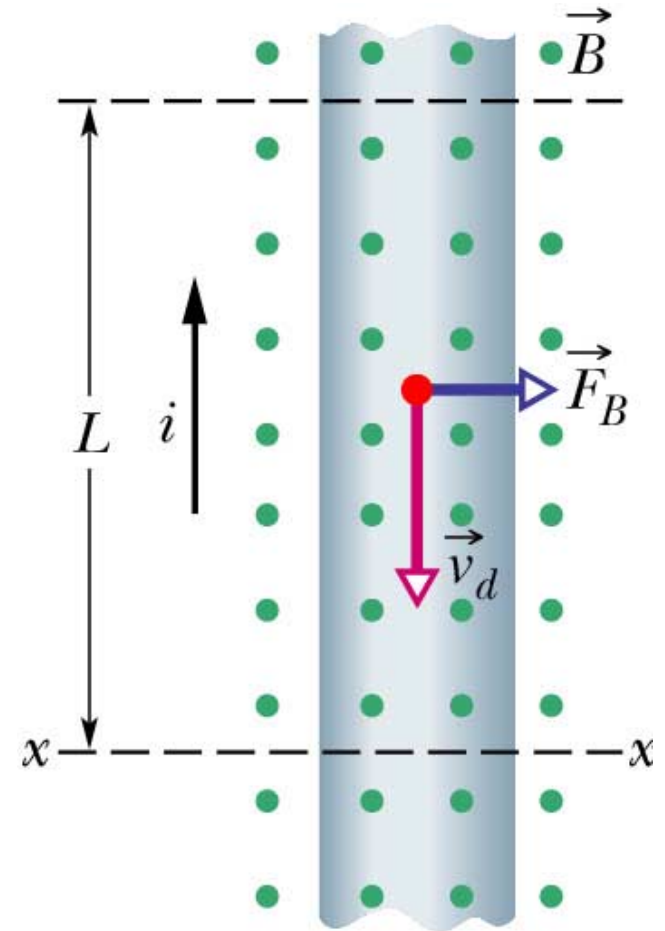
$$q = it = i \frac{L}{v_d}$$

- Substitute this for q in

$$\vec{F}_B = q\vec{v} \times \vec{B}$$

- Velocity is drift velocity, v_d

$$\vec{F}_B = qv_d B \sin \phi = \frac{iLv_d}{v_d} B \sin \phi$$



Magnetic Fields (49)

$$\vec{F}_B = iL\vec{B} \sin \phi$$

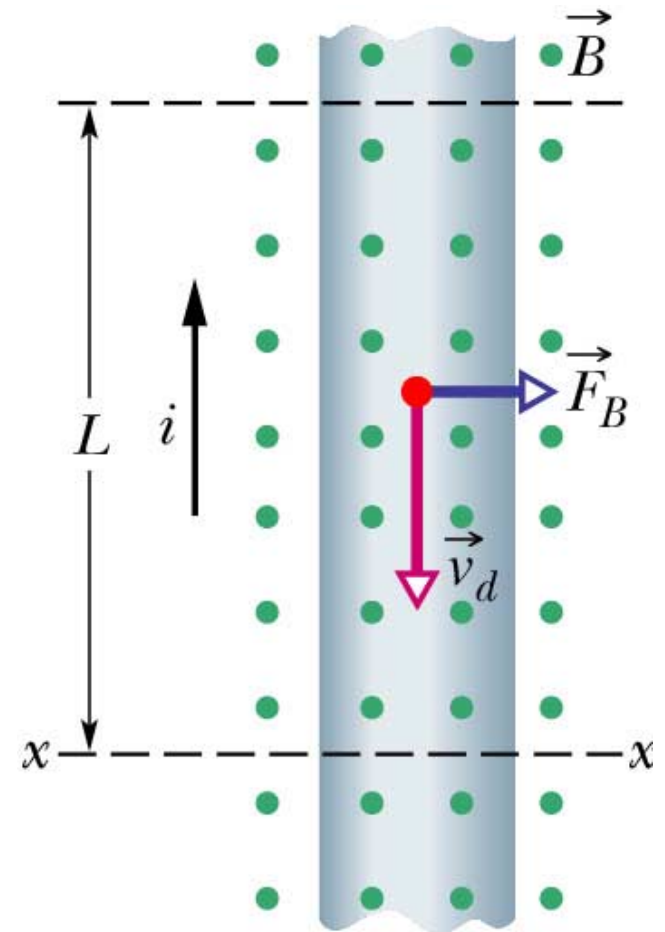
- Force on a current is

$$\vec{F}_B = i\vec{L} \times \vec{B}$$

- Vector L points along wire in the direction of the current

- Force on a single charge is

$$\vec{F}_B = q\vec{v} \times \vec{B}$$



Magnetic Fields (50)

- Checkpoint #5 – What is the direction of the B field so F_B is maximum?

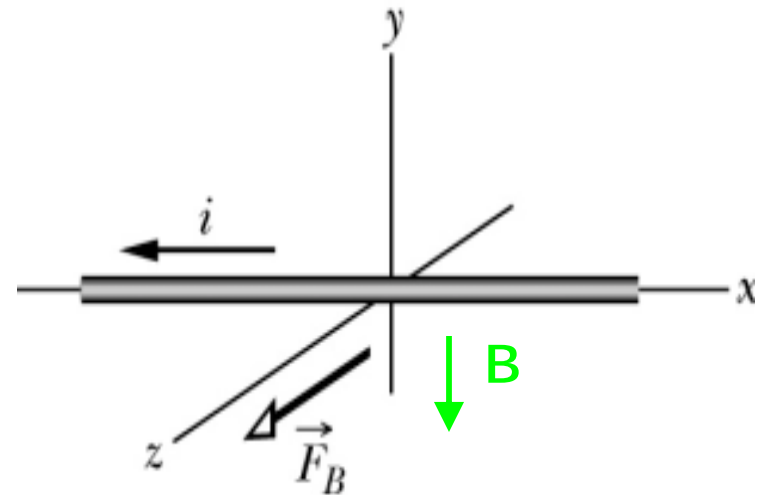
$$\vec{F}_B = i\vec{L} \times \vec{B} = iLB \sin \phi$$

- Where's the maximum?

$$\sin \phi = 1, \phi = 90$$

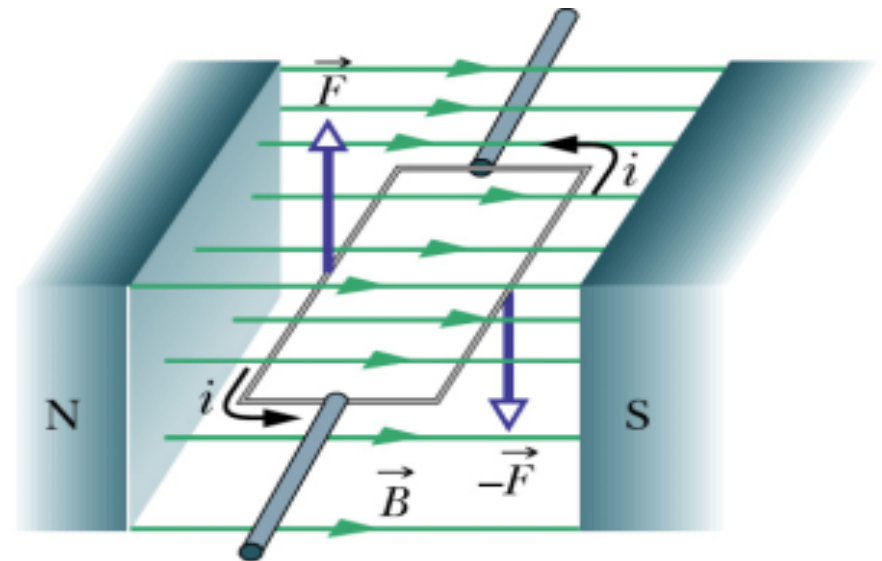
- What's the direction of B ? Use right-hand rule

B points in $-y$



Magnetic Fields (51)

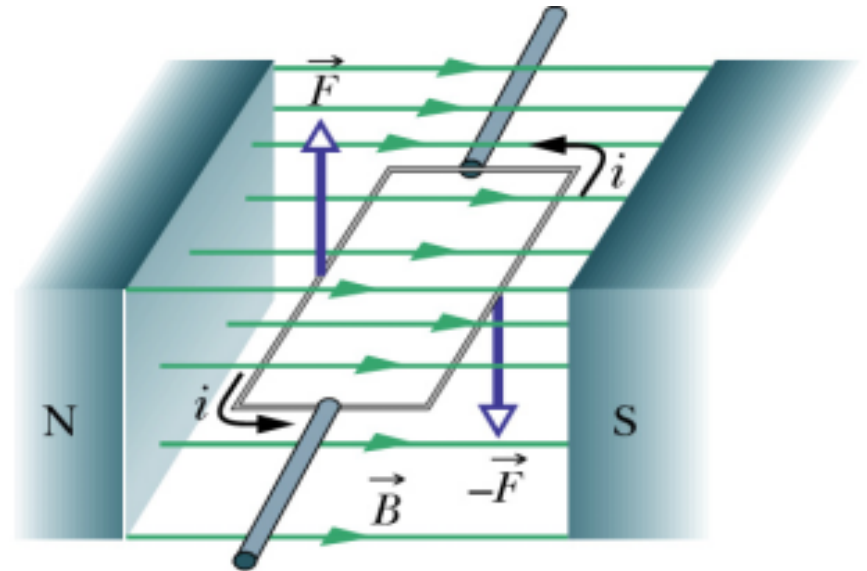
- What happens if we put a loop of wire carrying a current in a B field ?
- F_B on opposite sides of the loop produce a torque on the loop causing it to rotate



Magnetic Fields (52)

- Calculate the net force on the loop by vector sum of forces acting on each side
- For short sides of loop, i is \parallel to B so $F_B = 0$
- For long sides of loop, i is \perp to B so $F_B = iLB$, let length of long side $L = a$ so

$$\vec{F}_B = iaB$$

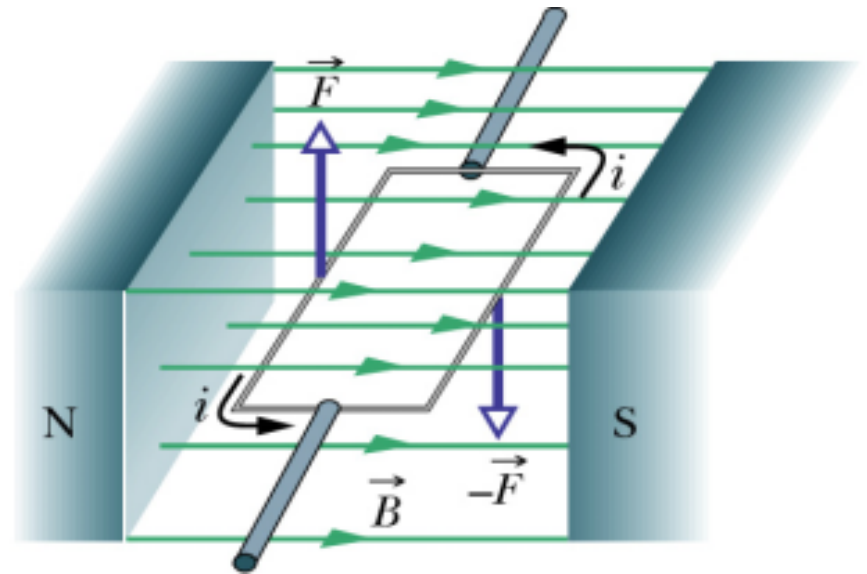


$$\vec{F}_B = i\vec{L} \times \vec{B} = iLB\sin\phi$$

Magnetic Fields (53)

- Force is in opposite directions for long sides of the loop
- Forces don't cancel because they don't share a common line of action
- Instead produce have a net torque and the loop rotates

$$\vec{F}_B = iaB$$

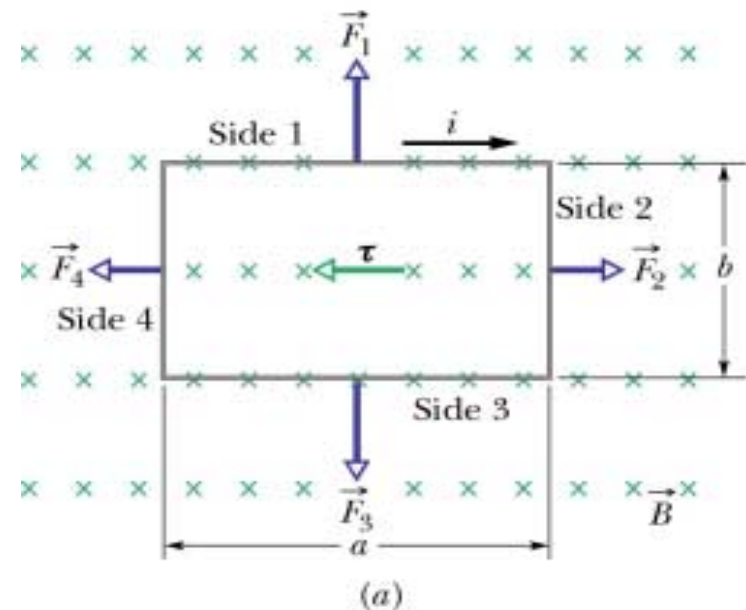
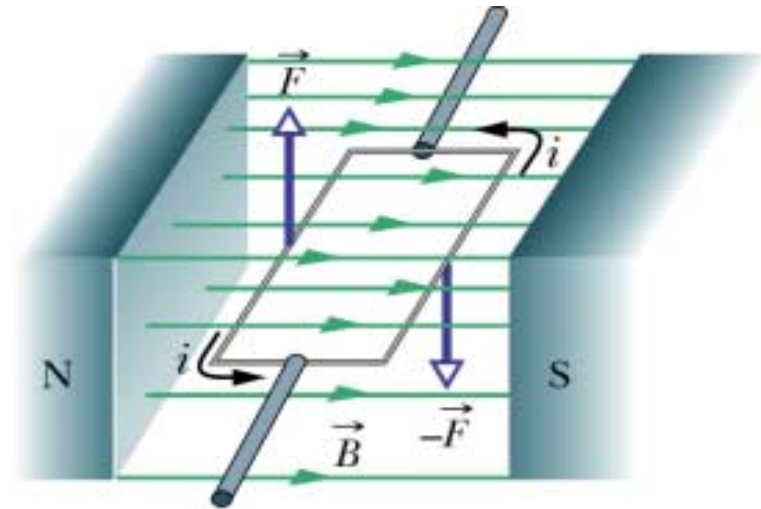


Magnetic Fields (54)

- Now rotate loop slightly so short sides are no longer \parallel to B
- **Short sides:**
 - $F_B \neq 0$ instead

$$\vec{F}_B = i\vec{L} \times \vec{B} = iLB \sin \phi$$

- Equal but opposite F_B s
- Cancel each other since common line of action through center of loop

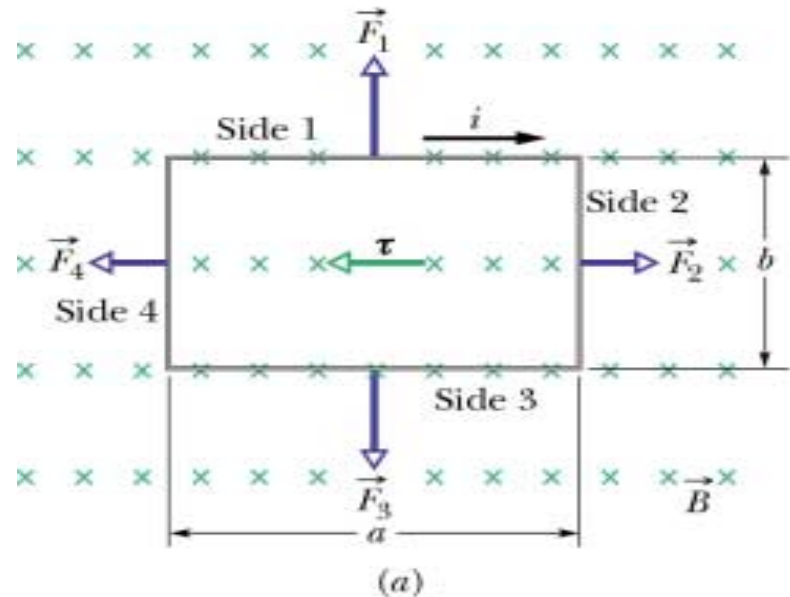
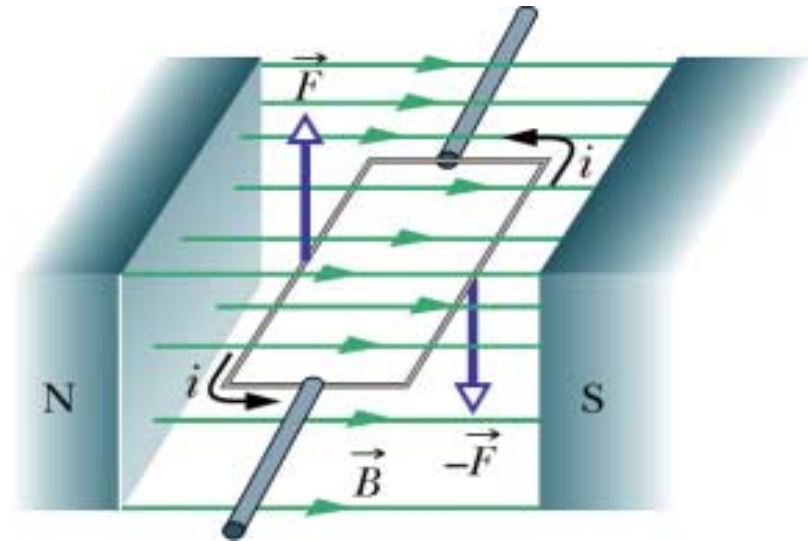


Magnetic Fields (55)

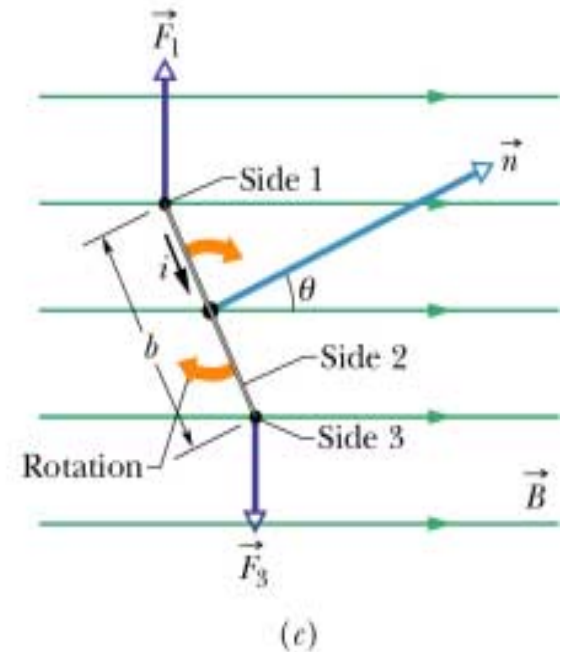
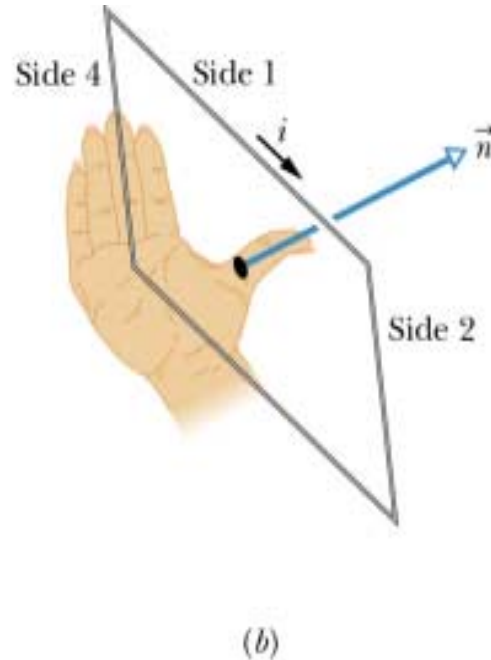
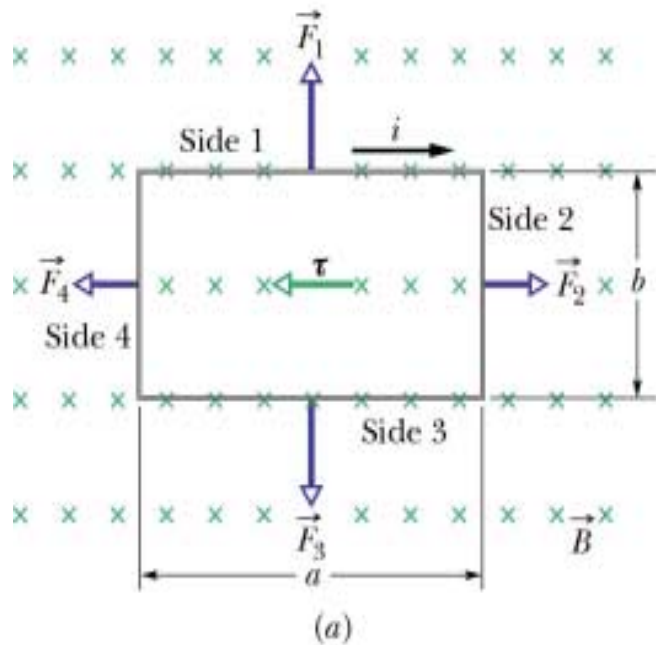
- Now rotate loop slightly so short sides are no longer \parallel to B
- Long sides:
 - i is still $\perp B$ so

$$\vec{F}_B = i\vec{L} \times \vec{B} = iLB$$

$$\vec{F}_B = iaB$$



Magnetic Fields (56)



- Define **normal vector, n** \perp to loop
- Use right-hand rule to find direction of n
 - Fingers curl in direction of i , thumb points in direction of n

Magnetic Fields (57)

- Torque is defined as

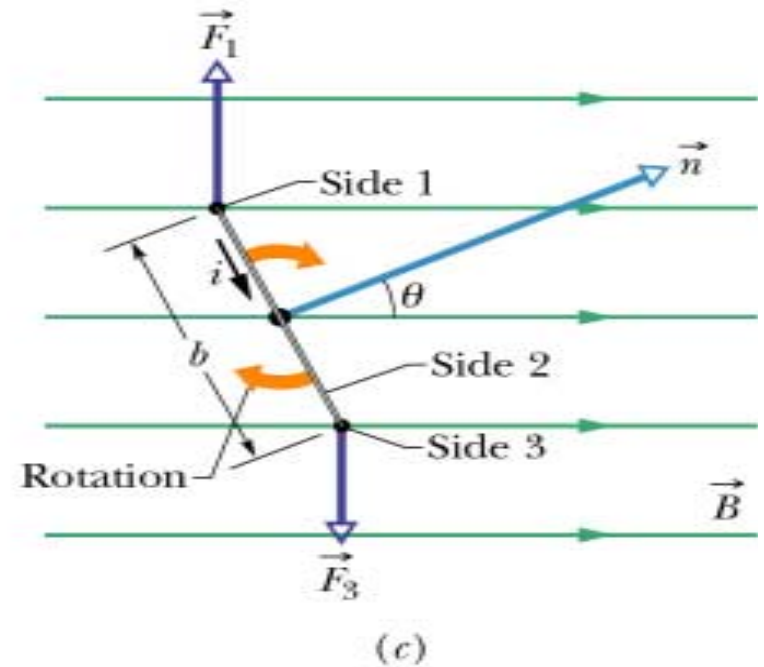
$$\tau = r_{\perp} F$$

- To find torque need to know the moment arm, r_{\perp}

$$r_{\perp} = \frac{b}{2} \sin \theta$$

- Torque for one side is

$$\tau = iaB \frac{b}{2} \sin \theta$$



Magnetic Fields (58)

- Total torque is sum of torques for each long side

$$\tau = iaB \frac{b}{2} \sin \theta + iaB \frac{b}{2} \sin \theta$$

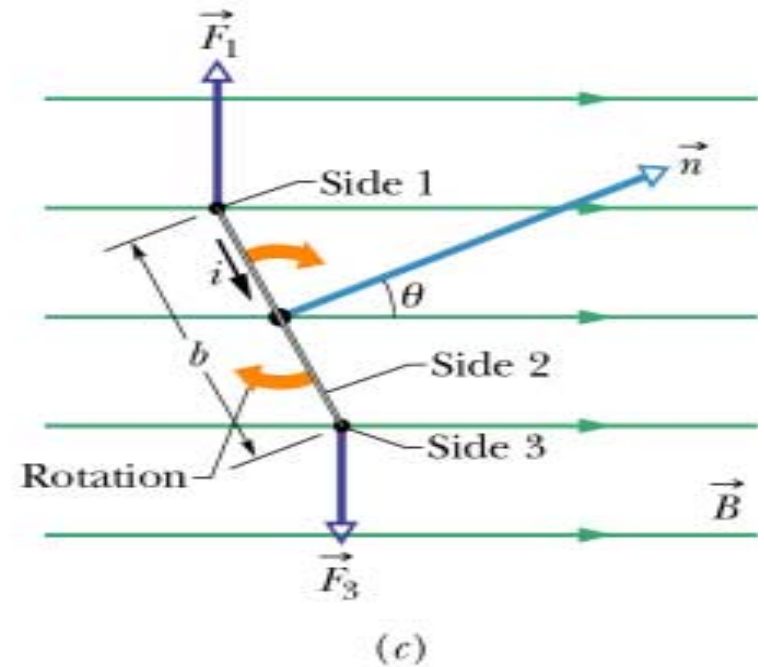
$$\tau = iabB \sin \theta$$

- Area of loop is

$$A = ab$$

so

$$\tau = iAB \sin \theta$$



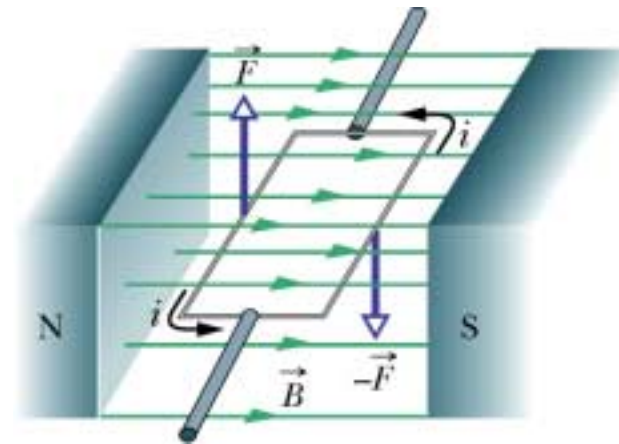
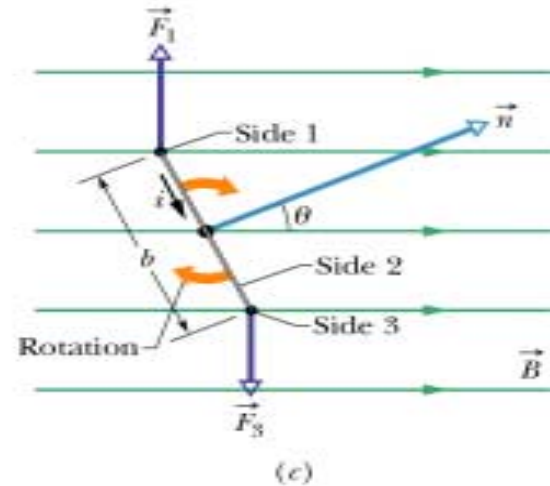
Magnetic Fields (59)

- Torque tends to rotate loop so to align n with B field
- Electric motor – oscillate polarity of B field to keep loop spinning
- Torque for single loop

$$\tau = iAB \sin \theta$$

- Replace single loop with coil of N loops or turns

$$\tau' = N\tau = (NiA)B \sin \theta$$



Magnetic Fields (60)

- Define the **magnetic dipole moment** to be

$$\mu = NiA$$

- Torque becomes

$$\tau = \mu B \sin \theta = \vec{\mu} \times \vec{B}$$

- Analogous to

$$\tau = \vec{p} \times \vec{E}$$

- A magnetic dipole in a magnetic field has a **magnetic potential energy, U**

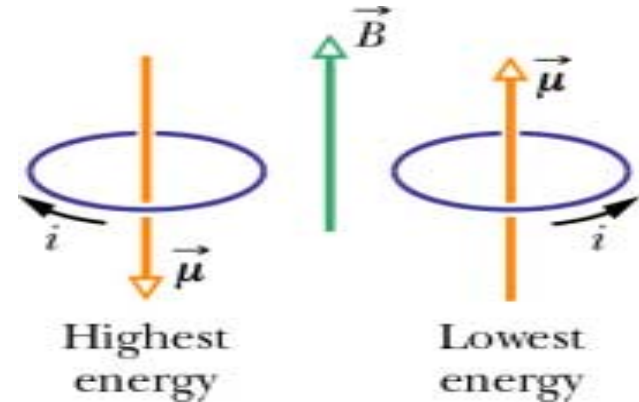
$$U = -\vec{\mu} \cdot \vec{B}$$

- Analogous to

$$U = -\vec{p} \cdot \vec{E}$$

Magnetic Fields (61)

- Magnetic dipole has lowest (highest) energy when μ is lined up with (directed opposite) the B field



$$U = -\vec{\mu} \cdot \vec{B} = -\mu B \cos \theta \quad \tau = \mu B \sin \theta = \vec{\mu} \times \vec{B}$$

- Checkpoint #6 – Rank, greatest first
- A) Magnitude of torque on dipole

All same

- B) Potential energy of dipole

1 & 4 tie, then 2 & 3 tie

