

functional bases: $\in \mathbb{L}^2(a, b)$ can be constructed which could be countably infinite:

could be

orthonormal: $(\eta^{(i)}, \eta^{(j)}) = \int_a^b \eta^{(i)*}(x) \eta^{(j)}(x) dx$

$$\langle \eta^{(i)} | \eta^{(j)} \rangle = \delta_{ij}$$

expand - "spectral decomposition"

$$f(x) = \sum_{i=1}^{\infty} \eta^{(i)}(x) \xi_{[\eta]}^i(x) \quad *$$

↑
countably ∞

One can imagine forming the "best" representation of a vector $\in \mathbb{L}^2(a, b)$ - in the sense of the RHS of * converging to the LHS of *.

Form 'mean free error'

$$M = \int_a^b \left| f(x) - \sum_{i=1}^n \eta^{(i)}(x) \xi_{[\eta]}^i \right|^2 dx \quad \text{drop } [\eta]$$

$$= \int_a^b |f(x)|^2 dx - \int_a^b \sum_i \xi^{*i}(x) \eta^{(i)}(x) \xi^i dx$$

$$- \int_a^b \sum_i \eta^{(i)*}(x) \xi_i^*(x) dx$$

$$+ \int \sum \sum \eta^{(j)*}(x) \eta^{(i)}(x) \xi^{*j} \xi_i dx$$

$$= N_f - \sum_i \left[(f, \eta^{(i)}) \xi^i + (\eta^{(i)}, f) \xi_i^* - \xi_i^* \xi^i \right]$$

find extremum

$$\frac{dM}{d\xi^i} = 0 = (\eta^{(i)}, \xi) - \xi^i$$

$$\text{so } \xi^i = (\eta^{(i)}, \xi)$$

and coefficients are best represented \rightarrow like "best fit"

$$\xi^i = \int_a^b \eta^{*(i)}(x) \xi(x) dx \quad \downarrow \quad \text{familiar.}$$

XI. Completeness, essentially says that $M \rightarrow 0$ as $n \rightarrow \infty$

or

$$\lim_{n \rightarrow \infty} \int_a^b \left| \xi - \sum_{i=1}^n \eta^{(i)} \xi^i \right|^2 dx \rightarrow 0 \quad \text{"in a Cauchy sense"}$$

V, VI, III, III, IV, V, VI constitute the definition of a Hilbert space

$$\begin{aligned} \xi(x) &= \sum_{i=1}^n \eta^{(i)}(x) \xi_{[i]}^i \\ &= \sum_i \eta^{(i)}(x) \int_a^b \eta^{*(i)}(x') \xi(x') dx' \\ &= \int_a^b \underbrace{\left\{ \sum_i \eta^{(i)}(x) \eta^{*(i)}(x') \right\}}_{\text{III}} \xi(x') dx' \\ &\quad \text{f}(x, x') \end{aligned}$$

$$\xi(x) = \int_a^b f(x, x') \xi(x') dx' \quad \text{defines the Dirac } \delta \text{ function.}$$

Completeness/closure: $\sum_{i=1}^{\infty} \eta^{(i)}(x) \eta^{*(i)}(x') = \delta(x-x')$

The whole field came about as a series of lectures by Hilbert in 1925-1927... von Neumann was his post doc.

functional analysis \longleftrightarrow ~~vector~~ linear algebra.

Named Hilbert Space by Courant in famous books (of lecture series)

Most of the famous square-integrable functions in physics are basis functions in a Hilbert Space — H_n, P_n, C_n, L_n — etc.

Many are not square-integrable as they are defined over $[-\infty, +\infty] \rightarrow$ integral transforms. \int_a^b not defined.

like Fourier:

$$\left. \begin{aligned} g(p) &= \sqrt{1/2\pi} \int_{-\infty}^{\infty} dx f(x) e^{-ipx/\hbar} \\ f(x) &= \sqrt{1/2\pi} \int_{-\infty}^{\infty} dp g(p) e^{ipx/\hbar} \end{aligned} \right\} \text{via } \Sigma$$

"basis": $\eta_p(x) = \sqrt{1/2\pi} e^{-ipx/\hbar}$

$$\left. \begin{aligned} g(p) &= \int_{-\infty}^{\infty} dx \eta_p(x) f(x) \\ f(x) &= \int_{-\infty}^{\infty} dp \eta_p^*(x) g(p) \end{aligned} \right\} \sqrt{1/2\pi} \int_{-\infty}^{\infty} \eta_p(x) dx = \delta(x)$$

completeness $\int dp \eta_p(x) \eta_p^*(x) = \int \frac{dp}{2\pi} e^{-ip(x-x')/\hbar} \equiv \delta(x-x')$

So, notation for 'function vectors.'

Discrete basis: $|\xi(x)\rangle = \sum_{i=1}^N |\eta^{(i)}(x)\rangle \sum_{[i]}^i$

Continuum basis: $|\xi(x)\rangle = \int_{\Omega_x} d\omega |\delta_x(\omega)\rangle \sum_{[\omega]}(\omega)$

and for continuum basis:

A Completeness: $\int_{\Omega_x} dx |\delta_x(\omega)\rangle \langle \delta_x(\omega')| = \delta(\omega - \omega')$

B Orthonormality: $\langle \delta_x(\omega) | \delta_x(\omega') \rangle = \delta(\omega - \omega')$

and discrete basis:

A Completeness: $\sum_{i=1}^N |\eta^{(i)}(x)\rangle \langle \eta^{(i)}(x')| = \delta(x - x')$

B Orthonormality: $\langle \eta^{(j)} | \eta^{(i)} \rangle = \delta^j_i$

Consider a basis function $\eta_p(x)$

$$\eta_p(x) = \sqrt{\frac{1}{2\pi}} e^{ipx}$$

Assign a Hilbert vector to it $|p\rangle$ such that

$$\langle p' | p \rangle = \int dx \eta_{p'}^*(x) \eta_p(x) \quad (= \langle \eta_{p'}(x) | \eta_p(x) \rangle)$$

$$= \int dx e^{-ip'x} e^{ipx} \left(\frac{1}{2\pi}\right) = \delta(p' - p)$$

Can pass functions between canonically conjugate quantities using $|\eta_p(x)\rangle$

$$\phi(x) = \int dp \tilde{\phi}(p) \eta_p(x)$$

$$\tilde{\phi}(p) = \int dx \phi(x) \eta_p^*(x)$$

Expand an arbitrary state vector:

$$|\xi\rangle = \int dp' |p'\rangle \tilde{\xi}(p') \quad \text{spectral expansion}$$

from $\langle p|\xi\rangle = \int dp' \langle p|p'\rangle \tilde{\xi}(p')$

$$\langle p|\xi\rangle = \int dp' \delta(p-p') \tilde{\xi}(p') = \tilde{\xi}(p)$$

projective of ^{abstract} ~~arbitrary~~ ξ "along" a basis function $|p\rangle$
 \uparrow
 H.S.

\nearrow
 get function of p

So,

$$|\xi\rangle = \int dp' |p'\rangle \langle p'|\xi\rangle$$

(like $|\xi\rangle = |e_k\rangle \langle e_k|\xi\rangle$)
 before

Do it again -- another continuum basis $\int_{x'} (x) = \delta(x-x')$
 w) H.S. vector assignment $|x'\rangle$

normalize

$$\langle x'' | x' \rangle = \int dx \int_{x''}^* (x) \int_{x'} (x)$$

$$= \int dx \delta(x-x'') \delta(x-x')$$

$$= \delta(x''-x') \Rightarrow \text{no existing}$$

norm --
 not square
 integrable

Can still expand

some function.

$$|\xi\rangle = \int dx' |x'\rangle F_{\xi}(x')$$

$$\langle p | \xi \rangle = \int dx' \langle p | x' \rangle F_{\xi}(x') = \hat{\xi}(p) \text{ from before.}$$

$$\text{so } \langle p | x' \rangle = \int dx \eta_p^*(x) \int_{x'} (x)$$

$$= \int dx \eta_p^*(x) \delta(x-x')$$

$$= \eta_p^*(x') \quad \text{or} \quad \langle x | p \rangle = \eta_p(x)$$

So... continuing

$$\langle p | \xi \rangle = \int dx' \eta_p^*(x') F_{\xi}(x') \stackrel{\text{still}}{=} \hat{\xi}(p)$$

so... $F_{\xi}(x')$ is the F.T. of $\hat{\xi}$ ov. $\Rightarrow \xi(x')$

Now $|\xi\rangle = \int dx' |x'\rangle \xi(x')$

expanding in terms of the configuration basis

$$\begin{aligned}\langle x | \xi \rangle &= \int dx' \langle x | x' \rangle \xi(x') \\ &= \int dx' \delta(x-x') \xi(x')\end{aligned}$$

$$\langle x | \xi \rangle = \xi(x)$$

↙ H.S.
projection of abstract vector, ξ , along configuration space basis \rightarrow FUNCTION OF x .

$\langle x | \xi \rangle =$ wavefunction in coordinate space

$\langle p | \xi \rangle =$ wavefunction in momentum space.

\rightarrow The essence of Dirac's Representation Theory... how he connected the discrete energy-transition description of Heisenberg to the continuous picture of Schrödinger

An important part of the story is the linking of dynamical variables to suitable operators.

Copenhagen view about how state vectors can be transformed:

1) continuously, through dynamics.

2) discontinuously, through measurement.

1) is understood to be a mapping $|\beta\rangle \xrightarrow{M} |\alpha\rangle$

ie $M|\beta\rangle = |\alpha\rangle \rightarrow$ always linear operators in QM. XII.

XIII. Operator self-adjoint or Hermitian if

$$M = M^\dagger \quad \text{where} \quad (M^\dagger)^i_j = (M^j_i)^*$$

~~\Rightarrow~~

and unitary if $MM^\dagger = M^\dagger M = \mathbb{1}$

XIV For the following relationship

$$A|\alpha_{(i)}\rangle = |\alpha_{(j)}\rangle \delta^j_i a(i) \rightarrow \text{no sum.}$$

$$= |\alpha_{(i)}\rangle a(i)$$

\uparrow eigenvalue of its eigenvector.

A matrix representation for linear operators is efficient —

Consider:

$$|\alpha\rangle = |\eta_{(i)}\rangle \alpha_{[\eta]}^i$$

$$|\beta\rangle = |\eta_{(j)}\rangle \beta_{[\eta]}^j$$

} 2 vectors, same basis.

Connect them through a mapping —

$$|\alpha\rangle \rightarrow |\beta\rangle = M|\alpha\rangle$$

$$|\eta_{(i)}\rangle \beta_{[\eta]}^j = M |\eta_{(i)}\rangle \alpha_{[\eta]}^i$$

from $\langle \eta^k | \beta \rangle = \langle \eta^k | M | \eta_i \rangle \alpha_{[\eta]}^i$ *

$$\langle \eta^k | \eta_j \rangle \beta_{[\eta]}^j = \underbrace{\langle \eta^k | M | \eta_i \rangle}_{\text{a complex number depending on 2 indices} \rightarrow \text{a matrix.}}$$

$$\delta_j^k \beta_{[\eta]}^j = \beta_{[\eta]}^k = M^k_i \alpha_{[\eta]}^i$$

This defines the "matrix element" $M^k_i = \langle \eta^k | M | \eta_i \rangle$

↑
an abstract object

a

representative of M in η basis.

How about for a continuous basis.

$$|z\rangle = \int d\alpha |\delta(\alpha)\rangle \sum_{[\alpha]} (\alpha) = |y_i\rangle \sum_{[y]}^i$$

$$|J\rangle = \int d\beta |\delta(\beta)\rangle \sum_{[\beta]} (\beta) = |y_j\rangle \sum_{[y]}^j$$

$$\begin{aligned} \text{D: } \langle J | M | z \rangle &= \sum_{i,j} \langle J | y_i \rangle \langle y_i | M | y_j \rangle \langle y_j | z \rangle && \text{Completeness} \\ &= \sum_{i,j} \int_{[\alpha]}^* M_{[y]j}^i \sum_{[y]}^j \end{aligned}$$

$$\begin{aligned} \text{C: } \langle J | M | z \rangle &= \int d\alpha \int d\beta \langle J | \delta(\alpha) \rangle \langle \delta(\alpha) | M | \delta(\beta) \rangle \langle \delta(\beta) | z \rangle \\ &= \int d\alpha \int d\beta \int_{[\alpha]}^* (\alpha) \sum_{[\beta]} (\beta) \langle \delta(\alpha) | M | \delta(\beta) \rangle \end{aligned}$$

XV. Products of operators \rightarrow other operators.

$$A |y_i\rangle = |y_j\rangle A^j_i$$

$$B |y_n\rangle = |y_u\rangle B^k_n$$

$$AB |y_n\rangle = (A |y_u\rangle) B^k_n = |y_j\rangle A^j_k B^k_n$$

$$AB |y_n\rangle = |y_j\rangle (AB)^j_n$$

arranged for matrix
multiplication \sum_k .

$$\begin{aligned} \text{note: } BA |y_n\rangle &= B |y_u\rangle A^k_n = |y_m\rangle B^m_k A^k_n \\ &= |y_m\rangle (BA)^m_n \end{aligned}$$

not necessarily = AB

Consider another change of basis. - 2 different bases.

$$|\delta_i\rangle = |\eta_k\rangle M^k_i$$

$$|\eta_i\rangle = |\delta_j\rangle (M^{-1})^j_i$$

and an ^{single} arbitrary operator.

$$A|\delta_i\rangle = |\delta_n\rangle A^n_{[r]i}$$

$$A|\eta_m\rangle = |\eta_p\rangle A^p_{[r]m}$$

How are ~~they~~ related the representatives $A_{[r]}$ and $A_{[r]}$ related?

$$A|\delta_i\rangle = |\delta_n\rangle A^n_{[r]i} = |\eta_n\rangle M^n_k A^k_{[r]i}$$

and

$$A|\delta_i\rangle = A|\eta_j\rangle M^j_i = |\eta_p\rangle A^p_{[r]j} M^j_i$$

so, for a given k $M^n_k A^n_{[r]i} = A^k_{[r]j} M^j_i$

Since bases are O.N., and M^{-1} exists.

PROBLEM

$$(M^{-1})^l_k M^k_n = \delta^l_n$$

$$\delta^l_n A^n_{[r]i} = (M^{-1})^l_k A^k_{[r]j} M^j_i$$

$$\rightarrow A^l_{[r]i} = (M^{-1})^l_k A^k_{[r]j} M^j_i$$

$$\text{or } A_{(r)} = M^{-1} A_{(r)} M = M^t A_{(r)} M$$

a Similarity Transformation

Leave bases alone and transfer the vectors.

$$|\beta\rangle = O|\alpha\rangle$$

$$A|\alpha\rangle = |\alpha'\rangle$$

$$A|\beta\rangle = |\beta'\rangle$$

what operator maps $\alpha' \rightarrow \beta'$?

$$|\alpha\rangle = A^{-1}|\alpha'\rangle$$

$$|\beta'\rangle = A|\beta\rangle = AO|\alpha\rangle$$

$$= (AOA^{-1})|\alpha'\rangle = \cancel{AOA^{-1}} O'|\alpha'\rangle$$

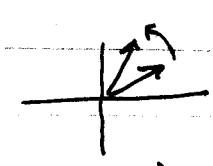
so

$$O' = AOA^{-1}$$

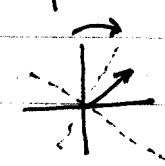
conjugate space of
similarity transformation.

→ always confusing...
the issue between

Active rotations



Passive rotations



Dynamical quantities are continuous parameters..

↓ assumption of QM
operators.

remember.

$$D: \quad A|\eta_i\rangle = |\eta_j\rangle \delta^j_i \alpha(i) \quad \text{no sum.}$$

$$\langle \eta^k | A | \eta_i \rangle = \langle \eta^k | \eta_j \rangle \delta^j_i \alpha(i)$$

$$A^k_i = \delta^k_j \delta^j_i \alpha(i)$$

$$\rightarrow \delta^i_k A^k_i = \delta^i_k \delta^k_j \delta^j_i \alpha(i)$$

$$= \delta^i_j \delta^j_i \alpha(i)$$

$$A^i_i = \alpha(i) \rightarrow \text{diagonal.}$$

$$C: \quad \text{coordinate rep.} \quad \langle x | \zeta \rangle = \psi_\zeta(x) \quad \text{coord w.f.}$$

↓ H.S. state vector
 $|x\rangle$

operator related to x .

$$\hat{X} |\psi_\zeta(x)\rangle = |\psi_\zeta(x)\rangle x \quad \text{or}$$

$$\hat{X} |x\rangle = |x\rangle x$$

$$\langle x' | \hat{X} | x \rangle = \langle x' | x \rangle x = \delta(x' - x) x$$

"diagonal"

this
choice.

$$\text{Likewise} \quad \hat{P} |\psi_\zeta(p)\rangle = |\psi_\zeta(p)\rangle p$$

$$\hat{P} |p\rangle = |p\rangle p$$

$$\text{and have} \quad \langle p' | p \rangle = \delta(p - p')$$

Consider abstract state vector $|\xi\rangle$

complex numbers —

$$P|\xi\rangle = \int dx P|x\rangle \langle x|\xi\rangle$$

$$= \int dx P|x\rangle \psi_\xi(x)$$

$$\langle x'|P|\xi\rangle = \int dx \underbrace{\langle x'|P|x\rangle}_{\text{what's this...}} \psi_\xi(x)$$

$$\langle x'|P|x\rangle = \int dp \langle x'|P|p\rangle \langle p|x\rangle$$

$$= \int dp p \langle x'|p\rangle \langle p|x\rangle$$

since $\langle x|p\rangle = \psi_p(x)$
 $\langle p|x'\rangle = \psi_p^*(x')$

$$\langle x'|P|x\rangle = \int dp p \frac{e^{-ip(x'-x)}}{2\pi} \quad \text{note}$$

diff of δ :

$$\frac{d}{dx} \delta(x'-x) = -i \int dp p \frac{e^{-ip(x'-x)}}{2\pi}$$

so

$$\langle x'|P|x\rangle = +i \frac{d}{dx} \delta(x'-x) \equiv \delta'(x'-x)$$

So, $\langle x'|P|x\rangle = \int dx i \delta'(x'-x) \psi_\xi(x)$

integrate by parts

$$\int_{-\infty}^{\infty} f(x) \delta'(x) dx = \left. f(x) \delta(x) \right|_{-\infty}^{\infty} - \int_{-\infty}^{\infty} f'(x) \delta(x) dx$$

$\begin{matrix} \infty & & \infty \\ \text{"} & \leftarrow & \text{"} \\ 0 & & f'(\infty) \end{matrix}$

again

So

$$\langle x' | P | \psi \rangle = i \int dx \delta'(x' - x) \psi_3(x)$$

$$= -i \psi_3'(x')$$

$$= -i \frac{d}{dx} \psi_3(x')$$

So the representation of the momentum operator in the coordinate representation is

$$P = -i \frac{d}{dx}$$

Back to group theory, now armed with linear algebra

def. A representation of a group G is a mapping of the elements of G on to a group of Linear Operators defined in a linear vector space, V .

$$G = \{ e, a, b, \dots \}$$

$\downarrow \quad \downarrow \quad \downarrow$

map is faithful

$$H = \{ \Gamma(e), \Gamma(a), \Gamma(b), \dots \}$$

So, if we have $ab=c \Rightarrow \Gamma(a)\Gamma(b) = \Gamma(c)$ under whatever multiplication rule is operative for V .

Now, we can provide a mathematical realization for the Δ namely basis vectors on which the Γ within V .

Transformation properties:

$$|x\rangle \rightarrow |x'\rangle = \Gamma|x\rangle$$

g
arbitrary, abstract.

Let $|x'\rangle = |e'_j\rangle x^{j'}$

$|x\rangle = |e_i\rangle x^i$

So $|x'\rangle = \Gamma|e_i\rangle x^i$

~~$|e'_j\rangle x^{j'}$~~

again

$$|x'\rangle = \Gamma |e_i\rangle x^i = |e_j'\rangle x^{j'}$$

$$= |e_j\rangle \Gamma^j_i x^i$$

which implies a
matrix representation
for Γ

So, the components are

$$x^{j'} = \Gamma^j_i x^i$$

$$\begin{pmatrix} x_1' \\ x_2' \\ \vdots \end{pmatrix} = \begin{pmatrix} \Gamma^1_1 & \Gamma^1_2 & \dots \\ \vdots & \vdots & \ddots \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \vdots \end{pmatrix}$$

Usually the row/column designation is for components --
but also can be used for bases.

$$|e\rangle = (e_1, e_2, \dots)$$

Then,

$$|x\rangle = |e_{(i)}\rangle x^i \quad \text{can be written}$$

vector

$$|x\rangle = \vec{x} = (|e_1\rangle |e_2\rangle |e_3\rangle) \begin{pmatrix} x^1 \\ x^2 \\ x^3 \end{pmatrix} \quad \left\{ \text{another vector.} \right.$$

↓ one object.

$$= \cancel{e_1 x^1 + e_2 x^2 + e_3 x^3}$$

$$= |e_{(1)}\rangle e^j_1 x^1 + |e_{(2)}\rangle e^j_2 x^2$$

The Γ can also be used to transform the bases -- the
coordinate system.

$$|e_i\rangle \rightarrow |e_j'\rangle = \Gamma |e_i\rangle = |e_j\rangle \Gamma^j_i \quad \text{coordinates -}$$

So,

$$|x'\rangle = |e_j\rangle x^{j'} = |e_j\rangle \Gamma^j_i x^i$$

$$= |e_i'\rangle x^i$$

} components
2 different
descriptions.

notice that the locations of the Γ^i_j are slightly different from what one expects, for basis transformation

$$|e'_1\rangle = |e_1\rangle \Gamma^1_1 + |e_2\rangle \Gamma^2_1$$

$$|e'_2\rangle = |e_1\rangle \Gamma^1_2 + |e_2\rangle \Gamma^2_2$$

→ off-diagonal reversed from the transformation of the vector, rather than coordinate system. Difference is between ↶ and ↷ of active vs. passive rotation

$$|x'\rangle = \Gamma |e_j\rangle x^j = |e_j\rangle \Gamma^j_i x^i$$

$$\begin{aligned} x^1 &= \Gamma^1_1 x'^1 + \Gamma^1_2 x'^2 \\ x^2 &= \Gamma^2_1 x'^1 + \Gamma^2_2 x'^2 \end{aligned}$$

The elements of Γ can be found by the inner product

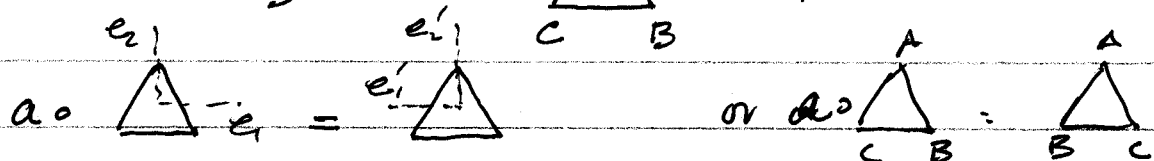
$$\begin{aligned} |e'_i\rangle &= |e_j\rangle \Gamma^j_i \\ \langle e^k | e'_i \rangle &= \langle e^k | e_j \rangle \Gamma^j_i \\ &= \delta^k_j \Gamma^j_i = \Gamma^k_i \end{aligned}$$

$$|e'\rangle = \Gamma |e\rangle$$

$$\langle e | e' \rangle = \langle e | \Gamma | e \rangle \text{ so } \Gamma^k_i = \langle e^k | \Gamma | e_i \rangle$$

more specifically, $\Gamma^k_i(q) = \langle e^k | \Gamma(q) | e_i \rangle$

So... back to D_3



$$\text{or.} \quad \begin{aligned} e_1 &\rightarrow e'_1 = -e_1 \\ e_2 &\rightarrow e'_2 = e_2 \end{aligned} \quad \left\{ \begin{array}{l} \Gamma(a) e_1 = -e_1 \\ \Gamma(a) e_2 = e_2 \end{array} \right.$$

calculate them

$$\Gamma(a)'_1 = \langle e'_1 | \Gamma(a) | e_1 \rangle = - \langle e'_1 | e_1 \rangle = -1$$

$$\Gamma(a)'_2 = \langle e'_1 | \Gamma(a) | e_2 \rangle = \langle e'_1 | e_2 \rangle = 0 = \Gamma(a)'_1$$

$$\Gamma(a)'_2 = \langle e'_2 | \Gamma(a) | e_2 \rangle = \langle e'_2 | e_2 \rangle = 1$$

So, we have $\Gamma^{(2)}(a) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}$

which is a 2 dimensional representation of D_3 .

So, $|e'_i\rangle = \Gamma(a) |e_i\rangle$ becomes.

$$(\overline{e_1, e_2}) =$$

$$|e'_i\rangle = |e_j\rangle \Gamma^j_i(a)$$

$$= (e_1, e_2) \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} = (-e_1, e_2) = (e'_1, e'_2)$$

The others follow similarly.

PROBLEM \rightarrow rest of 2d and 1d.

\rightarrow IRR example