

Lecture 5 1/28/04 Lie Algebras

def. If it is possible to put a matrix representation into block-diagonal form, it is a Reducible Representation. If not, then it is an IR Reducible Representation, IRR.

$$\Pi^{(n)}(g_i) = \Pi^{(m)}(g_i) \oplus \Pi^{(k)}(g_i)$$

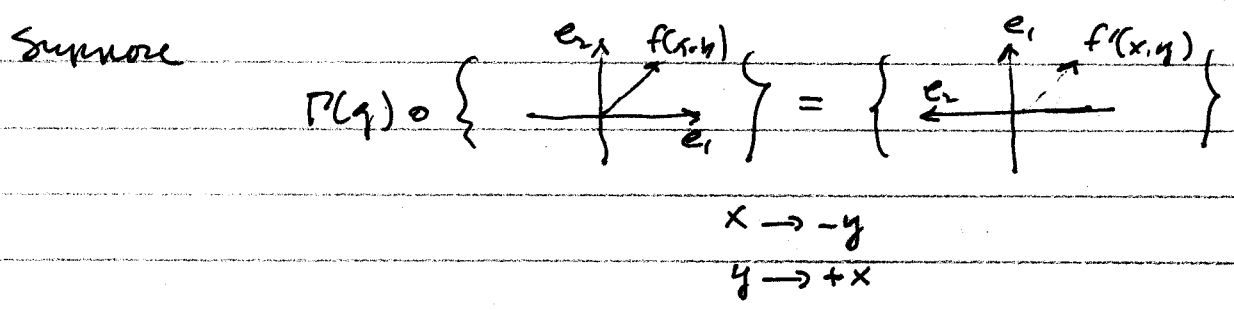
problem - similarity transformation

The connection with quantum mechanics comes from operators on functions - including basis functions in function spaces.

Define - $f(x,y) \Rightarrow f(|x\rangle) \rightarrow f'(|x\rangle) = \Gamma(g) f(|x\rangle) = f[|x_i\rangle (\Gamma^{-1}(g))^{ij}]$

complicated... $f_i(|x\rangle)$
a vector space
another vector space.

Get different functions (f') when a transformation on coordinates ($|x\rangle$) is done



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So, if $f(x, y) = x + y$. Then transformation on $|x\rangle$ gives $f'(x, y) = -y + x$
 || new function of old
 || coordinates

which odd inverse notation?

suppose $\Gamma(b) f(|x\rangle) = f[\Gamma^{-1}(b)|x\rangle] = g(|x\rangle)$

$$\begin{aligned} \Gamma(a)\Gamma(b) f(|x\rangle) &= \Gamma(a) f[\Gamma^{-1}(b)|x\rangle] \\ &= \Gamma(a) g(|x\rangle) \\ &= g[\Gamma^{-1}(a)|x\rangle] \end{aligned}$$

$$\begin{aligned} &= f[\Gamma^{-1}(b)\Gamma^{-1}(a)|x\rangle] \\ &= f\{[\Gamma(a)\Gamma(b)]^{-1}|x\rangle\} \end{aligned}$$

$$= f(ab) f(|x\rangle)$$

so the operations in function space have the same multiplication table as the group elements themselves

For every set of operators, a space exists which is spanned by a set of functions, so that an operator on one one \rightarrow a linear combination of the others.

$$\begin{aligned} \phi_i &\rightarrow \phi'_i = \Gamma(g) \phi_i(|x\rangle) \\ &= \phi_j \Gamma(g)^j_i \\ &\quad \uparrow \\ &\quad \text{analogous to } |e_j\rangle \end{aligned}$$

so, need $\Gamma^{-1}(g_i)|x\rangle$ for each group element

As usual $|e_i\rangle \rightarrow |e_i'\rangle = \Gamma |e_i\rangle$

vectors: $|x\rangle = |e_i\rangle x^i$ original basis
 $= |e_j'\rangle x^{j'}$ transformed basis...
 $= \Gamma |e_j\rangle x^{j'}$ new components.
 new functions, original basis

So, components are related $x^i = \Gamma^i_j x^{j'}$
 or $x^{j'} = \Gamma^{-1} x$

Consider D_3 ...

$$\Gamma(a) = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \quad (= \Gamma^{-1}(a))$$

need to find out $\Gamma f(|x\rangle)$ by.

$$\Gamma^{-1}(a) |x\rangle = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x^1 \\ x^2 \end{pmatrix} = \begin{pmatrix} x^{1'} \\ x^{2'} \end{pmatrix} = \begin{pmatrix} -x^1 \\ x^2 \end{pmatrix}$$

So... functions. $f(x, y) \rightarrow \Gamma(a) f(x, y) = f'(\begin{matrix} -x \\ y \end{matrix})$
 $-x, y$

eg. if $f(x, y) = x^2 \rightarrow f'(|x\rangle) = x^2$

PROBLEM for $\Gamma^{(2)}$ start out w/ $f(|x\rangle) = y \equiv f_1$
 generate space under D_3

lets move ---

LIE GROUPS

We could have characterized the finite groups this way:

$$G = \{g_1, g_2, g_3, \dots\}$$

$$g_k = g_i \circ g_j$$

- fix j and vary i through the whole group.
- then, k runs through the whole group.

→ like dependent and independent variables.

So, the multiplication table could be thought of as a functional relationship

$$g_k = f(g_i, g_j)$$

Suppose the group element index is allowed to become continuous

$$g_i \rightarrow g(\alpha)$$

where one could define "continuous" in the usual way $g(\alpha)$ and $g(\alpha')$ are 'near' if $|\alpha - \alpha'|$ is smaller than anything.

Such a group is the group of rotations, of which C_3 is a subgroup.

Same rules:

Suppose we have a single parameter α which can take on different values $\alpha', \alpha'', \alpha''', \dots$

1. $g(\alpha) \circ g(\alpha') = g(\alpha'')$ "group property" — closure
2. $g(\alpha) \circ [g(\alpha') \circ g(\alpha'')] = [g(\alpha) \circ g(\alpha')] \circ g(\alpha'')$
3. $\exists \alpha^0 \in G \rightarrow g(\alpha) \circ g(\alpha^0) = g(\alpha^0) \circ g(\alpha) = g(\alpha)$
4. $\forall \alpha \exists \tilde{\alpha} \rightarrow g(\alpha) \circ g(\tilde{\alpha}) = g(\alpha^0)$

The group property says.

$$\alpha'' = f(\alpha, \alpha')$$

This is a 1 parameter continuous group

↑
effectively, the multiplication table

In general there can be multi-parameter groups.

$$\alpha, \beta, \gamma, \delta, \epsilon, \dots \quad \text{or} \quad \alpha^1, \alpha^2, \alpha^3 \quad \text{or} \quad \alpha^r \quad \text{or} \quad \vec{\alpha}$$

if $\sigma = r \Rightarrow r$ -parameter continuous group.

If $\alpha^{\sigma''} = \varphi^{\sigma}(\vec{\alpha}; \vec{\alpha}') = \varphi^{\sigma}(\alpha^1, \alpha^2, \dots, \alpha^r; \alpha'^1, \alpha'^2, \dots, \alpha'^r)$

and φ^{σ} are analytic, differentiable in both arguments to all orders -- then the group is an "r-parameter Lie Group" after Sophus Lie (1842-1909) who did the essential work in collaboration with Felix Klein in the 1870's.

(These are little used (in practical terms) analogues to ergodicity and compactness...)

Consider the first continuous group $\rightarrow \mathbb{R}_2$, the group of rotations in 2 dimensions.

It's Abelian (~~is~~)

$$\begin{array}{c} \beta \\ \swarrow \quad \searrow \\ \alpha \\ \uparrow \quad \downarrow \\ \beta \end{array} = \begin{array}{c} \alpha \\ \swarrow \quad \searrow \\ \beta \\ \uparrow \quad \downarrow \\ \alpha \end{array}$$

parameter ranges $0 < \alpha < 2\pi$ and additive
 $\Gamma(\gamma) = \Gamma(\alpha) \circ \Gamma(\beta) \Rightarrow \gamma = \alpha + \beta$

Because it's Abelian, its IRR are 1d.

Representation:

Need, function $\Gamma(\alpha) \Rightarrow \Gamma(\alpha + \beta) = \Gamma(\alpha) \Gamma(\beta)$
 and $\Gamma'(\alpha) = \Gamma'(\alpha) \Gamma(0)$

The obvious solution: $\Gamma(\alpha) = e^{\alpha \Gamma'(0)}$

So that Γ be continuous and periodic $\Gamma(x) = \Gamma(x + 2\pi \cdot n)$
 $\Rightarrow \Gamma'(0)$ must be an imaginary integer.

Define $m \equiv i \Gamma'(0)$ $m = 0, \pm 1, \pm 2 \dots$

so

$$\Gamma(x) = e^{-imx}$$

It's naturally unitary and orthogonal

$$\int_0^{2\pi} \Gamma^{(m)}(\alpha) \Gamma^{(m')}(\alpha) d\alpha = 2\pi \delta^{mm'}$$

The notion of class is -- elements are in the same class if they have the same value of the parameter.

Basis vectors? - can choose $|e_1\rangle$ and $|e_2\rangle$

So,

$$\begin{aligned} R_3(\alpha) |e_1\rangle &= \cos\alpha |e_1\rangle + \sin\alpha |e_2\rangle \\ R_3(\alpha) |e_2\rangle &= -\sin\alpha |e_1\rangle + \cos\alpha |e_2\rangle \end{aligned} \quad \left. \vphantom{\begin{aligned} R_3(\alpha) |e_1\rangle \\ R_3(\alpha) |e_2\rangle \end{aligned}} \right\} \text{mix.}$$

but

$$\text{and } R_3(\alpha) (|e_1\rangle \pm i |e_2\rangle) = e^{\mp i\alpha} (|e_1\rangle \pm i |e_2\rangle)$$

So this means that

$|f_{\pm}\rangle \equiv |e_1\rangle \pm i |e_2\rangle$ transform according to the IRR of R_2 w/ $m = \pm 1$

Suppose we have a function of polar coordinates $\psi(r, \theta)$ in the plane,

$$\begin{aligned} \psi(r, \theta) &\rightarrow \psi'(r, \theta') = \Gamma[R_3(\alpha)\psi(r, \theta)] \\ &= \psi(r, R_3^{-1}\theta) = \psi(r, \theta - \alpha) \end{aligned}$$

So,

$\psi(r, \theta) = \psi(r) e^{im\theta}$ with transform according to the $\Gamma^{(m)}(\alpha)$ IRR of R_2 .

We can expand an arbitrary function into components, each of which transform according to a specific IRR of R_2 :

$$\psi(r, \theta) = \sum_{m=-\infty}^{\infty} \psi_m(r) e^{im\theta} \quad \text{of course, a Fourier expansion.}$$

where

$$\psi_m(r) = \frac{1}{2\pi} \int_0^{2\pi} \psi(r, \alpha) e^{-im\alpha} d\alpha$$

Another group is related, The group of translations in 1d T_1

$$x \rightarrow x + \alpha$$

same rule, same basis functions, and IRR.

$$\Gamma^{(k)}(\alpha) = e^{-ik\alpha} \quad \text{except}$$

$0 < \alpha < \infty$ and k is not integer.

STILL have same concerns: action of G on functions, of
 many coordinates \rightarrow function spaces and coordinate
 spaces.

a group element.

Now... γ depends on $\vec{\alpha} = \{\alpha^1, \alpha^2, \dots, \alpha^r\} \Rightarrow \gamma_{\vec{\alpha}}$

Choose a basis $\Gamma(\gamma_{\vec{\alpha}}) | \eta_i \rangle \xi^i = | \eta_i \rangle \xi^{i'}$

$$| \eta_i \rangle \Gamma(\gamma_{\vec{\alpha}})^i_k \xi^k = | \eta_i \rangle \xi^{i'}$$

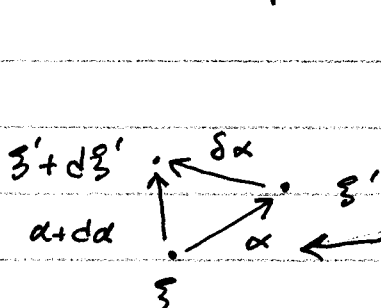
so

$$\begin{aligned} \xi^i &\rightarrow \xi^{i'} = \Gamma(\gamma_{\vec{\alpha}})^i_k \xi^k \\ &= F^i(\xi^1, \xi^2, \dots, \xi^n; \alpha^1, \alpha^2, \dots, \alpha^r) \end{aligned}$$

Differentiability is the key.

(Hammermesh) $\xi^i = F^i(\vec{\xi}; \vec{\alpha})$

α takes points from $\xi \rightarrow \xi'$



But can also differentially
 go from $\xi \rightarrow \xi' + d\xi'$ through
 $\alpha + d\alpha \rightarrow$ because of the
 anelasticity of ξ .

can get to $\xi' + d\xi'$ 2 ways. Can also get there from ξ'
 by going ^{through} $\delta\alpha$ which
 is very close to ϕ .

$$F(\xi; \alpha + d\alpha) = \xi' + d\xi'$$

and

$$F(\xi'; \delta\alpha) = \xi' + d\xi'$$

$$\begin{aligned} d\xi' &= F(\xi'; \delta\alpha) - \xi' \\ &= F(\xi'; \delta\alpha) - F(\xi'; 0) \end{aligned}$$

or

$$d\xi' = \left[\frac{\partial F(\xi; \alpha)}{\partial \alpha} \right]_{\alpha=0} \delta\alpha \quad \star$$

for generally a set of ξ and α ,

$$d\xi^i = \sum_{\sigma} \left[\frac{\partial F^i(\vec{\xi}; \vec{\alpha})}{\partial \alpha^{\sigma}} \right]_{\vec{\alpha}=0} \delta\alpha^{\sigma}$$

(coordinate label Latin, parameter Greek)

call
$$u_{\sigma}^i(\vec{\xi}) \equiv \left[\frac{\partial F^i(\vec{\xi}; \vec{\alpha})}{\partial \alpha^{\sigma}} \right]_{\vec{\alpha}=0}$$

so,
$$d\xi^i = u_{\sigma}^i(\vec{\xi}) \delta \alpha^{\sigma}$$

Likewise for parameters -- related through the group property

$$g(\alpha) = g(\alpha') \circ g(\alpha'')$$

$$\alpha = \varphi(\alpha' \dots \alpha^{r'}; \alpha'' \dots \alpha^{r''})$$

let $\vec{\alpha} = \{\alpha\}$ $\vec{\beta} = \{\alpha'\}$ $\vec{\epsilon} = \{\alpha''\}$

$$g(\vec{\alpha}) = g(\vec{\beta}) \circ g(\vec{\epsilon})$$

or.
$$\alpha^{\sigma} = \varphi^{\sigma}(\vec{\beta}; \vec{\epsilon})$$

which says
$$\alpha^{\sigma} + d\alpha^{\sigma} = \varphi^{\sigma}(\alpha' \dots \alpha^{r'}; \delta \alpha' \dots \delta \alpha^{r'})$$

The differentiability of the groups \Rightarrow can be treated as an analytic function of v variables.

$$d\alpha^{\sigma} = \sum_{p=1}^r \left[\frac{\partial \varphi^{\sigma}(\vec{\alpha}; \vec{\beta})}{\partial \beta^p} \right]_{\vec{\beta}=0} \delta \alpha^p$$

|||

$$= V_{\rho}^{\sigma}(\vec{\alpha}) \delta \alpha^{\rho}$$

$$V_{\rho}^{\sigma}(0) = \delta_{\rho}^{\sigma}$$

The inverse exists $V^\sigma_\rho \Lambda^\rho_\tau = \delta^\sigma_\tau$

so $\Lambda^\rho_\tau d\alpha^\tau = \Lambda^\rho_\tau V^\sigma_\rho \delta\alpha^\tau = \delta^\sigma_\tau \delta\alpha^\tau$

$$\Lambda^\rho_\tau d\alpha^\tau = \delta\alpha^\rho$$

Then vector change is

$$d\xi^i = u^i_\sigma(\vec{\xi}) \Lambda^\sigma_\rho(\vec{\alpha}) d\alpha^\rho$$

or $\frac{d\xi^i}{d\alpha^\rho} = u^i_\sigma(\vec{\xi}) \Lambda^\sigma_\rho(\vec{\alpha})$ (1)

the rate of change of ξ wrt α from $\xi=0$ when $\alpha=0$

The effect of group on function

$$T(\delta_\mu) f(\vec{\xi}) = f'(\vec{\xi}) = f(\vec{\xi}')$$

since $f(\vec{\xi}') = f(\vec{\xi} + \delta\vec{\xi}) \xrightarrow{\text{limit}} \frac{\partial f(\vec{\xi})}{\partial \xi^i} d\xi^i + f(\vec{\xi})$

so

$$f(\vec{\xi}') - f(\vec{\xi}) = \Delta f(\vec{\xi}) = \frac{\partial f(\vec{\xi})}{\partial \xi^i} d\xi^i = df(\vec{\xi})$$
 (2)

(1) & (2) and $\delta\xi$ is as $\alpha \rightarrow 0$

$$df(\vec{\xi}) = \frac{\partial f(\vec{\xi})}{\partial \xi^i} u^i_\sigma(\vec{\xi}) \delta\alpha^\sigma$$

rearrange

$$df = \delta \alpha^\sigma u_\sigma^i(\vec{z}) \frac{\partial}{\partial z^i} f(\vec{z})$$

$$\equiv \delta \alpha^\sigma X_\sigma f(\vec{z}) \Rightarrow \underline{\underline{f(\vec{z}') = f(\vec{z}) + \delta \alpha^\sigma X_\sigma f(\vec{z})}}$$

defining $X_\sigma \equiv u_\sigma^i \frac{\partial}{\partial z^i}$ as

the Infinitesimal Generators - where

u_σ^i describes how coordinates infinitesimally change wrt infinitesimal change in parameters.

For $f = z^i$

$$\begin{aligned} \Gamma(\gamma) z^i &= z'^i = z^i + dz^i \\ &= z^i + \delta \alpha^\sigma X_\sigma z^i \\ &= z^i + u_\sigma^i \frac{\partial z^i}{\partial z^j} \delta \alpha^\sigma \end{aligned}$$

$$= z^i + u_\sigma^i \delta \alpha^\sigma \quad \text{which is where we started}$$

So, let's imagine a functional basis which transforms under this group.

The operator $1 + \delta x^\sigma X_\sigma$ is close to ^{the identity.} ~~unity~~

So, the group operation on an arbitrary function:

$$\begin{aligned}\Gamma(\delta_{\vec{a}}) f(\vec{z}) &= f(\vec{z}) + \delta x^\sigma X_\sigma f(\vec{z}) \\ &= (1 + \delta x^\sigma X_\sigma) f(\vec{z})\end{aligned}$$

Consider 2 successive operations.

$$\begin{aligned}\Gamma(\delta_{\vec{a}}) \Gamma(\delta_{\vec{b}}) &= (1 + \delta \alpha^\sigma X_\sigma) (1 + \delta \beta^\rho X_\rho) \\ &= 1 + \delta \beta^\rho X_\rho + \delta \alpha^\sigma X_\sigma + \mathcal{O}(\delta \alpha \delta \beta) \\ &= 1 + \delta \beta^1 X_1 + \delta \beta^2 X_2 + \dots + \delta \alpha^1 X_1 + \delta \alpha^2 X_2 + \dots \\ &= 1 + \underbrace{(\delta \beta^\sigma + \delta \alpha^\sigma)}_{\delta \epsilon^\sigma} X_\sigma \\ &\quad \delta \epsilon^\sigma \rightarrow \text{additive property of parameters}\end{aligned}$$

$$\Gamma(\delta_{\vec{c}}) = 1 + \delta \epsilon^\sigma X_\sigma = \Gamma(\delta_{\vec{a}}) \Gamma(\delta_{\vec{b}})$$

Group property.

Let α be only a small $\delta\beta$

$$\Gamma(\vec{\alpha})\Gamma(\vec{\beta}) = \Gamma(\vec{\alpha} + \vec{\beta})$$

$$\Gamma(\delta\vec{\beta})\Gamma(\vec{\beta}) = \Gamma(\delta\vec{\beta} + \vec{\beta})$$

$$(1 + \delta\beta^\sigma X_\sigma)\Gamma(\vec{\beta}) = \Gamma(\vec{\beta}) + \delta\beta^\sigma X_\sigma \Gamma(\vec{\beta}) = \Gamma(\vec{\beta} + \delta\vec{\beta})$$

$$\frac{\Gamma(\vec{\beta} + \delta\vec{\beta}) - \Gamma(\vec{\beta})}{\delta\beta^\sigma} = X_\sigma \Gamma(\vec{\beta})$$

$$\lim_{\delta\beta^\sigma \rightarrow 0} \frac{d\Gamma(\vec{\beta})}{d\beta^\sigma} = X_\sigma \Gamma(\vec{\beta})$$

$$\frac{d\Gamma}{\Gamma} = X_\sigma d\beta^\sigma$$

which is an operator equation that can be formally solved...

$$\Gamma(\vec{\beta}) = e^{X_\sigma \beta^\sigma}$$

Imagine dividing the parameters into small pieces,

$$\vec{\beta} = \vec{\theta}/n \quad \Gamma(\vec{\beta}) = e^{X_\sigma \theta^\sigma/n}$$

and let n be very large

$$\Gamma(\theta/n) = \lim_{n \rightarrow \infty} e^{X_\sigma \theta^\sigma/n} = 1 + X_\sigma \theta^\sigma/n$$

Putting many of them together

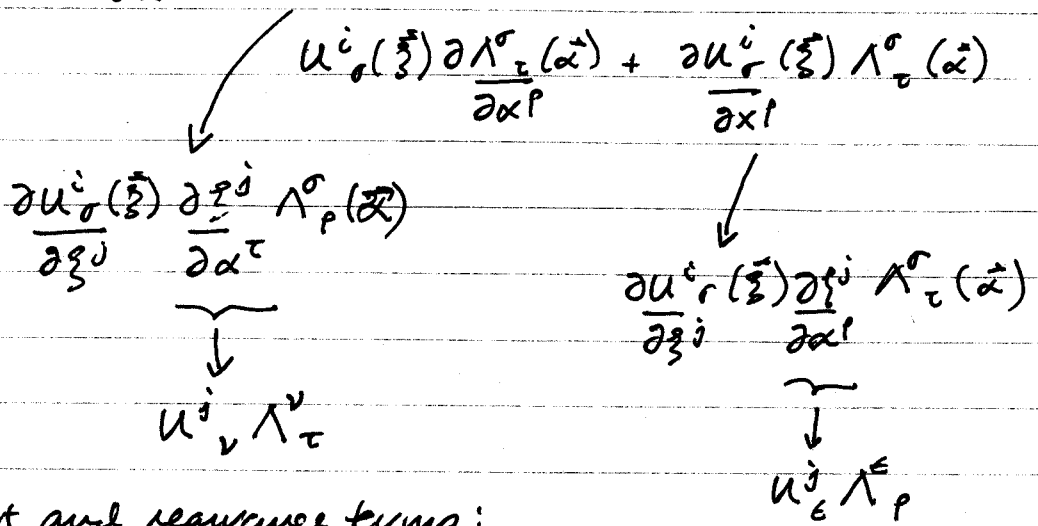
$$\Gamma(\theta/n)\Gamma(\theta/n)\dots = (1 + X_\sigma \theta^\sigma/n)^n = e^{X_\sigma \theta^\sigma}$$

So, the finite transformation Θ can be thought of as a build-up of infinitesimal transformations Θ/u where $u \rightarrow \infty$

Go back to
$$\frac{\partial \xi^i}{\partial \alpha^p} = u^i_r(\vec{\xi}) \Lambda^{\sigma}_p(\vec{\alpha})$$

Demand
$$\frac{\partial^2 \xi^i}{\partial \alpha^\tau \partial \alpha^p} = \frac{\partial^2 \xi^i}{\partial \alpha^p \partial \alpha^\tau} \Rightarrow \text{arbitrariness w.r.t } \alpha.$$

$$u^i_r(\vec{\xi}) \frac{\partial \Lambda^{\sigma}_p(\vec{\alpha})}{\partial \alpha^\tau} + \frac{\partial u^i_r(\vec{\xi})}{\partial \alpha^\tau} \Lambda^{\sigma}_p(\vec{\alpha}) =$$



collect and rearrange terms:

$$u^j_v \frac{\partial u^i_r}{\partial \xi^j} \Lambda^{\nu}_\tau \Lambda^{\sigma}_p - u^j_e \frac{\partial u^i_r}{\partial \xi^j} \Lambda^{\epsilon}_p \Lambda^{\sigma}_\tau = u^i_r \left(-\frac{\partial \Lambda^{\sigma}_p}{\partial \alpha^\tau} + \frac{\partial \Lambda^{\sigma}_\tau}{\partial \alpha^p} \right)$$

multiply by $V^{\tau}_p V^{\rho}_\eta$

$$u^j \frac{\partial u^i}{\partial z^j} V^\sigma_p V^\tau_\eta \Lambda^\nu_\sigma \Lambda^\rho_\eta - u^j \frac{\partial u^i}{\partial z^j} V^\sigma_p V^\tau_\eta \Lambda^\sigma_\rho \Lambda^\rho_\tau = () u^i V^\sigma_p V^\tau_\eta$$

$$u^j_p \frac{\partial u^i}{\partial z^j} - u^j_\eta \frac{\partial u^i}{\partial z^j} = \left(\frac{\partial \Lambda^\sigma_\tau}{\partial \alpha^p} - \frac{\partial \Lambda^\sigma_\rho}{\partial \alpha^\tau} \right) V^\sigma_p V^\tau_\eta u^i_\sigma = C^\sigma_{\eta\tau} u^i_\sigma$$

operate by $\frac{\partial}{\partial z^i}$ from the right.

$$u^j_p \frac{\partial}{\partial z^j} u^i_\eta \frac{\partial}{\partial z^i} - u^j_\eta \frac{\partial}{\partial z^j} u^i_p \frac{\partial}{\partial z^i} = C^\sigma_{\eta\tau} u^i_\sigma \frac{\partial}{\partial z^i}$$

recognize the infinitesimal generators $X_\sigma = u^k_\alpha \frac{\partial}{\partial z^k}$ and ... tadaah!

$$X_p X_\eta - X_\eta X_p = C^\sigma_{\eta\tau} X_\sigma$$

$$[X_p, X_\eta] = C^\sigma_{\eta\tau} X_\sigma \quad \text{Lie Algebra}$$

↑
called "Structure Constants"

Fundamental Theorem of Lie: everything you need to know about a Lie Group is in the algebra satisfied by the generators

- ⇒ Structure constants completely determine the group
- ⇒ don't need the multiplication table

consider T_1 -- the 1-dimensional shift

$$\xi \xrightarrow{T_1} \xi' = a\xi + b$$

steps -- need parameter value of zero to represent no change

$$\xi \rightarrow \xi' = (1 + \alpha)\xi + \alpha_2$$

so, the infinitesimal transformation is

$$\begin{aligned} \xi' &= \xi + d\xi = (1 + \delta\alpha_1)\xi + \delta\alpha_2 \\ &= \xi + \delta\alpha_1 \xi + \delta\alpha_2 \\ \delta\xi &= \xi' - \xi = \delta\alpha_1 \xi + \delta\alpha_2 \end{aligned}$$

remember that $\delta\xi^i = U^i_\sigma \delta\alpha^\sigma$

or

$$\begin{aligned} \xi' &= U^i_\sigma \delta\alpha^\sigma && \text{only have } i=1 \\ & && \text{for 1d} \\ &= U^1_1 \delta\alpha^1 + U^1_2 \delta\alpha^2 \end{aligned}$$

so, we can recognize

$$U^1_1 = \xi \text{ and } U^1_2 = 1$$

and can construct the generators

$$X_\sigma = U^i_\sigma \frac{\partial}{\partial \xi^i} \Rightarrow X_1 = U^1_1 \frac{\partial}{\partial \xi^1} = \xi \frac{\partial}{\partial \xi^1}$$

$$X_2 = U^1_2 \frac{\partial}{\partial \xi^1} = \frac{\partial}{\partial \xi^1}$$

so, need to operate on something

$$\begin{aligned}
 [X_1, X_2] F &= \xi \frac{\partial}{\partial z'} \frac{\partial}{\partial z'} F - \frac{\partial}{\partial z'} \xi' \frac{\partial}{\partial z'} F \quad \text{drop } \xi' \\
 &= \xi \frac{\partial^2 F}{\partial z'^2} - \frac{\partial F}{\partial z} - \xi \frac{\partial^2 F}{\partial z'^2} \\
 &= -\frac{\partial F}{\partial z} = -X_2 F
 \end{aligned}$$

so: $[X_1, X_2] = -X_2$ is the Lie Algebra for \mathfrak{g}_1
and the structure constants are

$$\begin{aligned}
 c_{12}^1 &= 0 = c_{21}^1 \\
 c_{12}^2 &= -1 = -c_{21}^2
 \end{aligned}$$