



# Physics for Scientists & Engineers 2

Spring Semester 2005

Lecture 30

## Review

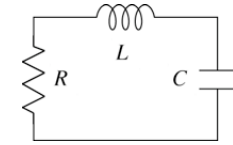


- If we have a single loop RLC circuit, the charge in the circuit as a function of time is given by

$$q = q_{\max} e^{-\frac{Rt}{2L}} \cos(\omega t + \phi)$$

- Where

$$\omega = \sqrt{\omega_0^2 - \left(\frac{R}{2L}\right)^2} \quad \omega_0 = \frac{1}{\sqrt{LC}}$$



- The energy stored in the capacitor as a function of time is given by

$$U_E = \frac{q_{\max}^2}{2C} e^{-\frac{Rt}{L}} \cos^2(\omega t + \phi)$$

## Review (2)



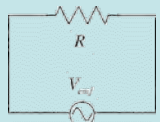
- Time-varying emf

$$V_{emf} = V_{\max} \sin \omega t$$

- Time-varying emf  $V_R$  with resistor

$$i_R = \frac{V_R}{R} = I_R \sin \omega t$$

Resistance



- Time-varying emf  $V_C$  with capacitor

$$X_C = \frac{1}{\omega C} \quad i_C = \frac{V_C}{X_C} \sin(\omega t + 90^\circ)$$

Capacitive Reactance



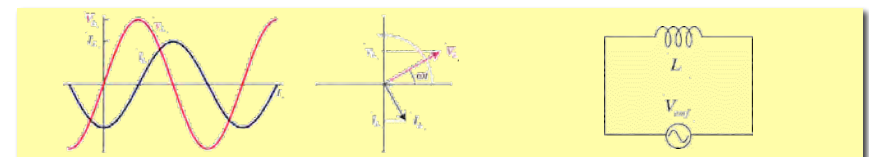
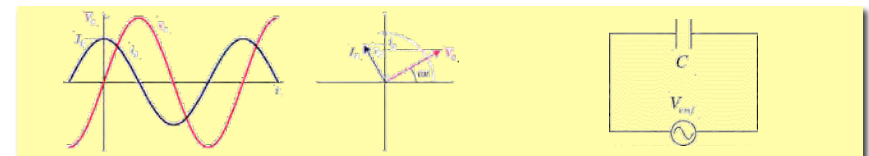
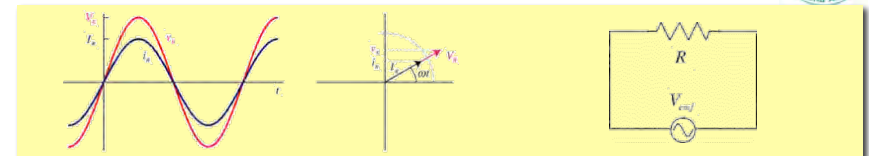
- Time-varying emf  $V_L$  with inductor

$$X_L = \omega L \quad i_L = \frac{V_L}{X_L} \sin(\omega t - 90^\circ)$$

Inductive Reactance



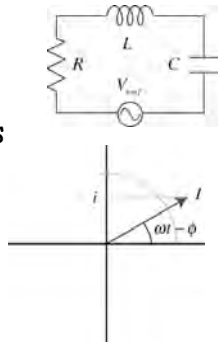
## Review (3)



## Series RLC Circuit



- Consider a single loop circuit that has a resistor, a capacitor, an inductor, and a source of time-varying emf
- We can describe the time-varying currents in these circuit elements using a phasor  $I$
- The projection of  $I$  on the vertical axis represents the current flowing in the circuit as a function of time
  - The angle of the phasor is given by  $\omega t - \phi$
- We can also describe the voltage in terms of a phasor  $V$
- The time-varying currents and voltages in the circuit can have different phases



## Series RLC Circuit (2)

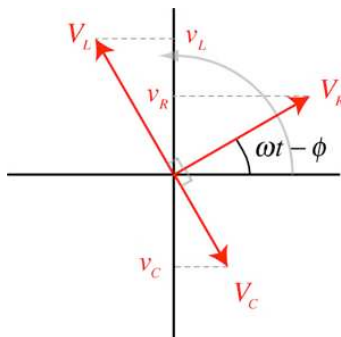


- We can describe the current flowing in the circuit and the voltage across the various components
  - Resistor**
    - The voltage  $v_R$  and current  $i_R$  are in phase with each other and the voltage phasor  $v_R$  is in phase with the current phasor  $I$
  - Capacitor**
    - The current  $i_C$  leads the voltage  $v_C$  by  $90^\circ$  so that the voltage phasor  $v_C$  will have an angle  $90^\circ$  less than  $I$  and  $v_R$
  - Inductor**
    - The current  $i_L$  lags behind the voltage  $v_L$  by  $90^\circ$  so that voltage phasor  $v_L$  will have an angle  $90^\circ$  greater than  $I$  and  $v_R$

## Series RLC Circuit (3)



- The voltage phasors for an RLC circuit are shown below

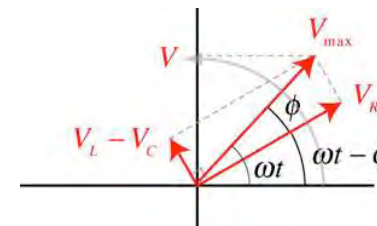


- The instantaneous voltages across each of the components are represented by the projections of the respective phasors on the vertical axis

## Series RLC Circuit (4)



- Kirchhoff's loop rules tells that the voltage drops across all the devices at any given time in the circuit must sum to zero, which gives us
 
$$V - v_R - v_C - v_L = 0 \Rightarrow V = v_R + v_C + v_L$$
- The voltage  $V$  can be thought of as the projection of the vertical axis of the phasor  $V_{\max}$  representing the time-varying emf in the circuit as shown below



- In this figure we have replaced the sum of the two phasors  $V_L$  and  $v_C$  with the phasor  $V_L - v_C$

## Series RLC Circuit (5)



- The sum of the two phasors  $V_L - V_C$  and  $V_R$  must equal  $V_{\max}$  so

$$V_{\max}^2 = V_R^2 + (V_L - V_C)^2$$

- Now we can put in our expression for the voltage across the components in terms of the current and resistance or reactance

$$V_{\max}^2 = (IR)^2 + (IX_L - IX_C)^2$$

- We can then solve for the current in the circuit

$$I = \frac{V_{\max}}{\sqrt{R^2 + (X_L - X_C)^2}}$$

- The denominator in the equation is called the **impedance**

$$Z = \sqrt{R^2 + (X_L - X_C)^2}$$

- The impedance of a circuit depends on the frequency of the time-varying emf

## Series RLC Circuit (6)



- The current flowing in an alternating current circuit depends on the difference between the inductive reactance and the capacitive reactance
- We can express the difference between the inductive reactance and the capacitive reactance in terms of the phase constant  $\phi$
- This phase constant is defined as the phase difference between voltage phasors  $V_R$  and  $V_L - V_C$

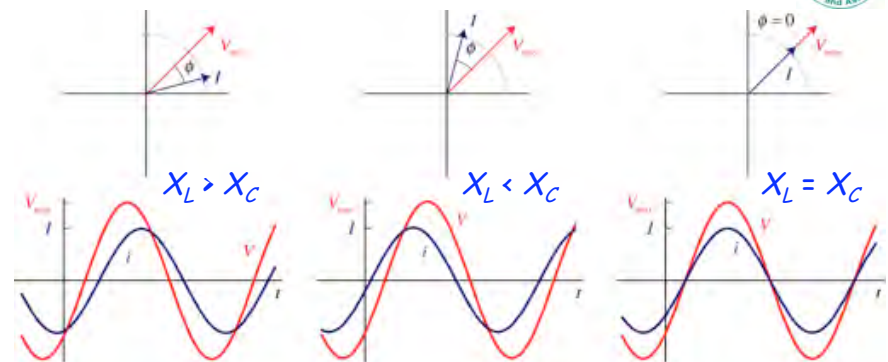
$$\phi = \tan^{-1}\left(\frac{V_L - V_C}{V_R}\right) = \tan^{-1}\left(\frac{X_L - X_C}{R}\right)$$

## Series RLC Circuit (7)



- Thus we have three conditions for an alternating current circuit
  - For  $X_L > X_C$ ,  $\phi$  is positive, and the current in the circuit will lag behind the voltage in the circuit
    - This circuit will be similar to a circuit with only an inductor, except that the phase constant is not necessarily  $90^\circ$
  - For  $X_L < X_C$ ,  $\phi$  is negative, and the current in the circuit will lead the voltage in the circuit
    - This circuit will be similar to a circuit with only a capacitor, except that the phase constant is not necessarily  $-90^\circ$
  - For  $X_L = X_C$ ,  $\phi$  is zero, and the current in the circuit will be in phase with the voltage in the circuit
    - This circuit is similar to a circuit with only a resistance
    - When  $\phi = 0$  we say that the circuit is in **resonance**

## Series RLC Circuit (8)



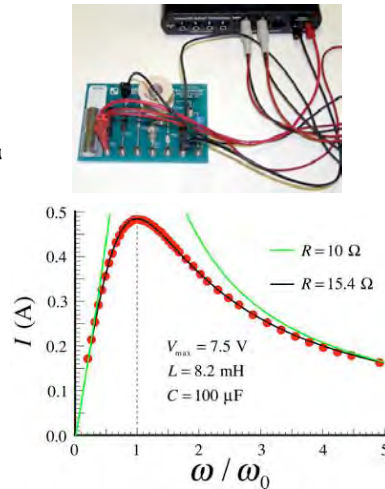
- For  $X_L = X_C$  and  $\phi = 0$  we get the maximum current in the circuit and we can define a resonant frequency

$$\omega L - \frac{1}{\omega C} = 0 \Rightarrow \omega_0 = \frac{1}{\sqrt{LC}}$$

## Real-life RLC Circuit (2)



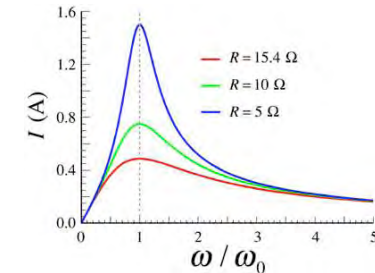
- Let's study a real-life circuit
  - $R = 10 \Omega$
  - $L = 8.2 \text{ mH}$
  - $C = 100 \mu\text{F}$
  - $V_{\text{max}} = 7.5 \text{ V}$
- We measure the current in the circuit as a function of the frequency of the time-varying emf
- We see the correct resonant frequency (peak at  $\omega/\omega_0 = 1$ )
  - $L$  and  $C$  must be accurate
- However, our formula for the current (green line) using  $R = 10 \Omega$  does not agree with the measurements
  - We must use  $R = 15.4 \Omega$ 
    - The inductor has a resistance even at resonance



## Resonant Behavior of RLC Circuit



- The resonant behavior of an  $RLC$  circuit resembles the response of a damped oscillator
- Here we show the calculated maximum current as a function of the ratio of the angular frequency of the time varying emf divided by the resonant angular frequency, for a circuit with  $V_{\text{max}} = 7.5 \text{ V}$ ,  $L = 8.2 \text{ mH}$ ,  $C = 100 \mu\text{F}$ , and three resistances
- One can see that as the resistance is lowered, the maximum current at the resonant angular frequency increases and there is a more pronounced resonant peak



## Energy and Power in RLC Circuits



- When an  $RLC$  circuit is in operation, some of the energy in the circuit is stored in the electric field of the capacitor, some of the energy is stored in the magnetic field of the inductor, and some energy is dissipated in the form of heat in the resistor
- The energy stored in the capacitor and inductor do not change in steady state operation
- Therefore the energy transferred from the source of emf to the circuit is transferred to the resistor
- The rate at which energy is dissipated in the resistor is the power  $P$  given by
- The average power is given by

$$P = i^2 R = (I \sin(\omega t - \phi))^2 R = I^2 R \sin^2(\omega t - \phi)$$

$$\langle P \rangle = \frac{1}{2} I^2 R = \left( \frac{I}{\sqrt{2}} \right)^2 R$$

## Energy and Power (2)



- We define the root-mean-square (rms) current to be  $I_{\text{rms}} = \frac{I}{\sqrt{2}}$
- So we can write the average power as  $\langle P \rangle = I_{\text{rms}}^2 R$
- We can make similar definitions for other time-varying quantities
  - rms voltage:  $V_{\text{rms}} = \frac{V}{\sqrt{2}}$
  - rms time-varying emf:  $V_{\text{max,rms}} = \frac{V_{\text{max}}}{\sqrt{2}}$
- The currents and voltages measured by an alternating current ammeter or voltmeter are rms values
- For example, we normally say that the voltage in the wall socket is 110 V
- This rms voltage would correspond to a maximum voltage of  $\sqrt{2} \cdot 110 \text{ V} \approx 156 \text{ V}$

## Energy and Power (3)



- We can then re-write our formula for the current as

$$I_{rms} = \frac{V_{max,rms}}{Z} = \frac{V_{max,rms}}{\sqrt{R^2 + \left(\omega L - \frac{1}{\omega C}\right)^2}}$$

- Which allows us to express the average power dissipated as

$$\langle P \rangle = I_{rms}^2 R = \frac{V_{max,rms}}{Z} \cdot I_{rms} R = I_{rms} V_{max,rms} \frac{R}{Z}$$

- We can relate the phase constant to the ratio of the maximum value of the voltage across the resistor divided by the maximum value of the time-varying emf

$$\cos \phi = \frac{V_R}{V_{max}} = \frac{IR}{IZ} = \frac{R}{Z} \Rightarrow \langle P \rangle = I_{rms} V_{rms} \cos \phi$$

- We can see that the maximum power is dissipated when  $\phi = 0$
- We call  $\cos(\phi)$  the power factor

## Transformers



- When using or generating electrical power, high currents and low voltages are desirable for convenience and safety
- When transmitting electric power, high voltages and low currents are desirable
  - The power loss in the transmission wires goes as  $P = I^2 R$
  - Assume we have 500 MW of power to transmit
  - If we transmit at 750 kV, the current would be 667 A
  - If the resistance of the power lines is 200  $\Omega$ , the power dissipated in the power lines is 89 MW
    - 18% loss
  - Suppose we transmit at 375 kV instead
    - 75% loss
- The ability to raise and lower alternating voltages is useful in everyday life

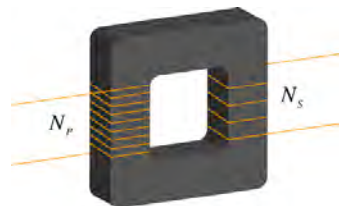
## Transformers (2)



- To transform alternating currents and voltages from high to low one uses a transformer
- A transformer that takes voltages from lower to higher is called a step-up transformer and a transformer that takes voltages from higher to lower is called a step-down transformer
- A transformer consists of two sets of coils wrapped around an iron core as illustrated
- Consider the primary windings with  $N_p$  turns connected to a source of emf

$$V_{emf} = V_{max} \sin \omega t$$

- We can assume that the primary windings act as an inductor
- The current is out of phase with the voltage and no power is delivered to the transformer



## Transformers (3)

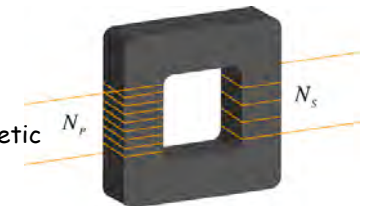


- Now consider the second coil with  $N_s$  turns
- The time-varying emf in the primary coil induces a time-varying magnetic field in the iron core
- This core passes through the secondary coil
- Thus a time-varying voltage is induced in the secondary coil described by Faraday's Law

$$V_{emf} = -N \frac{d\Phi_B}{dt}$$

- Because both the primary and secondary coils experience the same changing magnetic field we can write

$$\frac{V_P}{N_P} = \frac{V_S}{N_S} \Rightarrow V_S = V_P \frac{N_S}{N_P}$$



## Transformers (4)



- If we now connect a resistor  $R$  across the secondary windings, a current will begin to flow through the secondary coil
- The power in the secondary circuit is then  $P_S = I_S V_S$
- This current will induce a time-varying magnetic field that will induce an emf in the primary coil
- The emf source then will produce enough current  $I_P$  to maintain the original emf
- This induced current will not be  $90^\circ$  out of phase with the emf thus power can be transmitted to the transformer
- Energy conservation tells that the power produced by the emf source in the primary coil will be transferred to the secondary coil so we can write

$$P_P = I_P V_P = P_S = I_S V_S \Rightarrow I_S = I_P \frac{V_P}{V_S} = I_P \frac{N_P}{N_S}$$

## Transformers (5)



- When the secondary circuit begins to draw current, current must be supplied to the primary circuit

- We can define the current in the secondary circuit as  $V_S = I_S R$

- We can then write the primary current as\

$$I_P = \frac{N_S}{N_P} I_S = \frac{N_S}{N_P} \frac{V_S}{R} = \frac{N_S}{N_P} \left( V_P \frac{N_S}{N_P} \right) \frac{1}{R} = \left( \frac{N_S}{N_P} \right)^2 \frac{V_P}{R}$$

- With an effective primary resistance of

$$R_P = \frac{V_P}{I_P} = V_P \left( \frac{N_P}{N_S} \right)^2 \frac{R}{V_P} = \left( \frac{N_P}{N_S} \right)^2 R$$

- Note that these equations assume no losses in the transformers and that the load is purely resistive

- Real transformers have small losses

- Another application of transformers is impedance matching

- Stereo amplifier to stereo speakers