

Example 2.4 $F = -\gamma v$ "retarding force"

$$m \frac{dv}{dt} = -\gamma v \Rightarrow \frac{dv}{v} = -\frac{\gamma}{m} dt$$

$$\ln v = -\frac{\gamma}{m} t + c$$

$$\text{or } \ln v - \ln v_0 = -\frac{\gamma}{m} (t - t_0)$$

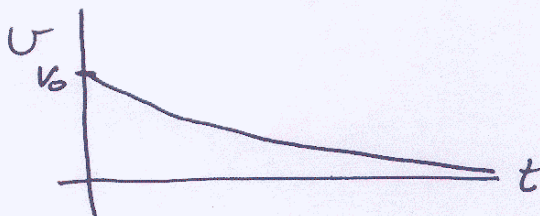
$$\frac{v}{v_0} = e^{-\gamma t/m} \quad (t_0 = 0)$$

$$v = v_0 e^{-\gamma t/m}$$

← That's obvious:

$$\frac{dv}{dt} = -\frac{\gamma}{m} v$$

$$\frac{df}{dx} = f \text{ means } f = e^x \text{ or } C e^x$$



$$\begin{aligned} \text{Distance} &= \int_0^{\infty} v dt = \int_0^{\infty} v_0 e^{-\gamma t/m} dt \\ &= v_0 \left(\frac{-1}{\gamma/m} \right) e^{-\gamma t/m} \Big|_0^{\infty} = \frac{-m v_0}{\gamma} \{ e^{-\infty} - e^0 \} \\ &= \frac{m v_0}{\gamma} \end{aligned}$$

$$D = \frac{m v_0}{\gamma}$$

Example 2.5

$$F = F_0 - \gamma v$$

$$m \frac{dv}{dt} = F_0 - \gamma v$$

- Method #1 : Separation of variables (exercise)
- Method #2 : This is a linear inhomogeneous equation;

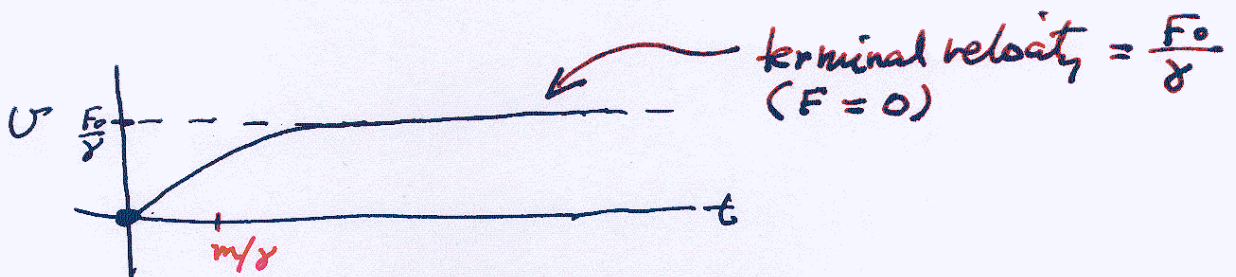
$\therefore v =$ particular solution + general solution of the homogeneous equation

$$v = \frac{F_0}{\gamma} + C e^{-\gamma t/m}$$

Initial conditions $v(0) = 0$

$$0 = \frac{F_0}{\gamma} + C \quad \text{means } C = -F_0/\gamma$$

$$v = \frac{F_0}{\gamma} \left\{ 1 - e^{-\gamma t/m} \right\}$$



For small t ,

$$v \approx \frac{F_0}{\gamma} \left\{ 1 - \left[1 - \frac{\gamma t}{m} \right] \right\} = \frac{F_0}{m} t$$

is for $\frac{\gamma t}{m} \ll 1$.

Solution Key

Quiz B

Tuesday, June 2

Consider a particle that moves in one dimension. Suppose the velocity of the particle, as a function of time, is

$$v(t) = v_0 \tanh \alpha t$$

... where v_0 and α are constants.

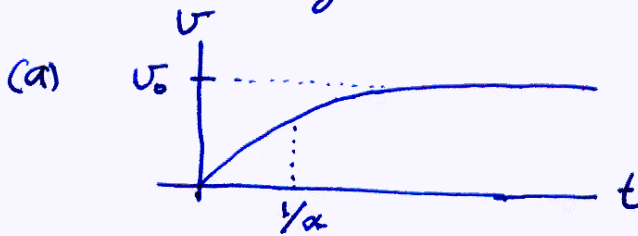
(a) Sketch a graph of v versus t . Indicate relevant positions on the v and t axes.

(b) Let F be the force on the particle. Determine F as a function of v .

(c) Sketch a graph of F versus v . Indicate relevant positions on the F and v axes.

HINTS: $\tanh x = \sinh x / \cosh x$ and $\cosh^2 x - \sinh^2 x = 1$.

Consider $t \geq 0$ only.



2 points

The particle accelerates, and finally approaches a constant velocity v_0 .

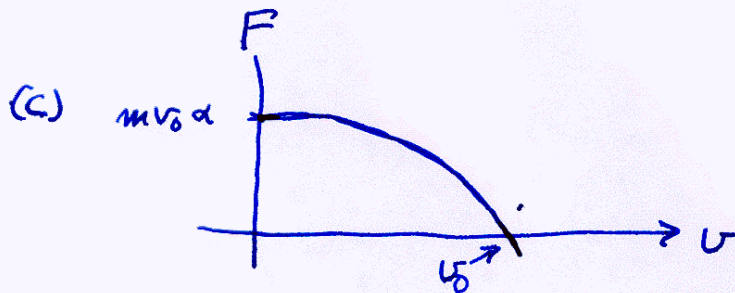
(b) $F = m \frac{dv}{dt}$

$$F = m v_0 (1 - \tanh^2 \alpha t) \alpha$$

$$F = m v_0 \alpha - \frac{m \alpha}{v_0} v^2$$

2 points

$$\begin{aligned} \frac{d}{dx} \tanh x &= \frac{d}{dx} \frac{\sinh x}{\cosh x} \\ &= \frac{\cosh x}{\cosh^2 x} - \frac{\sinh x}{\cosh^2 x} \sinh x \\ &= 1 - \tanh^2 x = \operatorname{sech}^2 x \end{aligned}$$



$$F \text{ is } c_1 - c_2 v^2.$$

2 points

Comment: v_0 is the terminal velocity, at which $F = 0$.

Homework Set B (Chapter 1)

1-7

$$\hat{i} + \hat{j} + \hat{k}$$
$$-\hat{i} + \hat{j} + \hat{k}, \quad -\hat{i} - \hat{j} + \hat{k}, \quad \hat{i} + \hat{j} - \hat{k}$$
$$\text{length} = \sqrt{3}$$

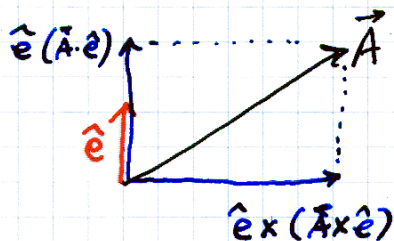
1-10

$$v = b\omega \sqrt{1 + 3 \cos^2 \omega t}$$

1-16

a plane

1-24



$$\vec{A} = \hat{e}(\vec{A} \cdot \hat{e}) + \hat{e} \times (\vec{A} \times \hat{e})$$

1-26

Not graded

1-31

Not graded

1-34

$$\frac{d}{dt} (\vec{A} \times \dot{\vec{A}}) = \dot{\vec{A}} \times \dot{\vec{A}} + \vec{A} \times \ddot{\vec{A}} = \vec{A} \times \ddot{\vec{A}}$$

$$\therefore \int \vec{A} \times \ddot{\vec{A}} dt = \int \frac{d}{dt} (\vec{A} \times \dot{\vec{A}}) dt$$

$$= \vec{A} \times \dot{\vec{A}} + C \quad \text{QED}$$