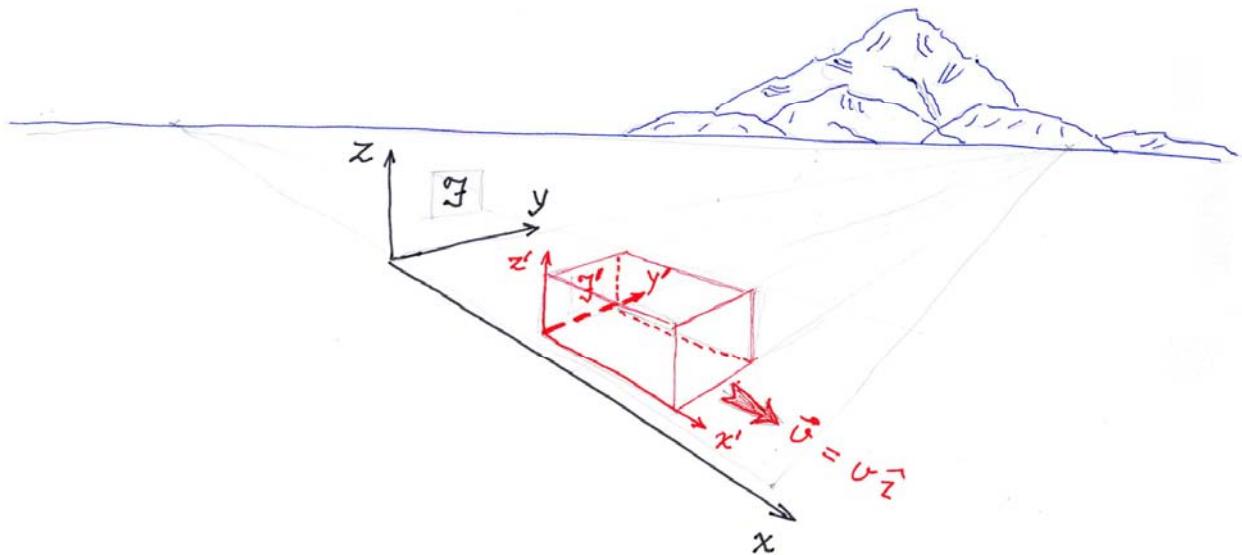


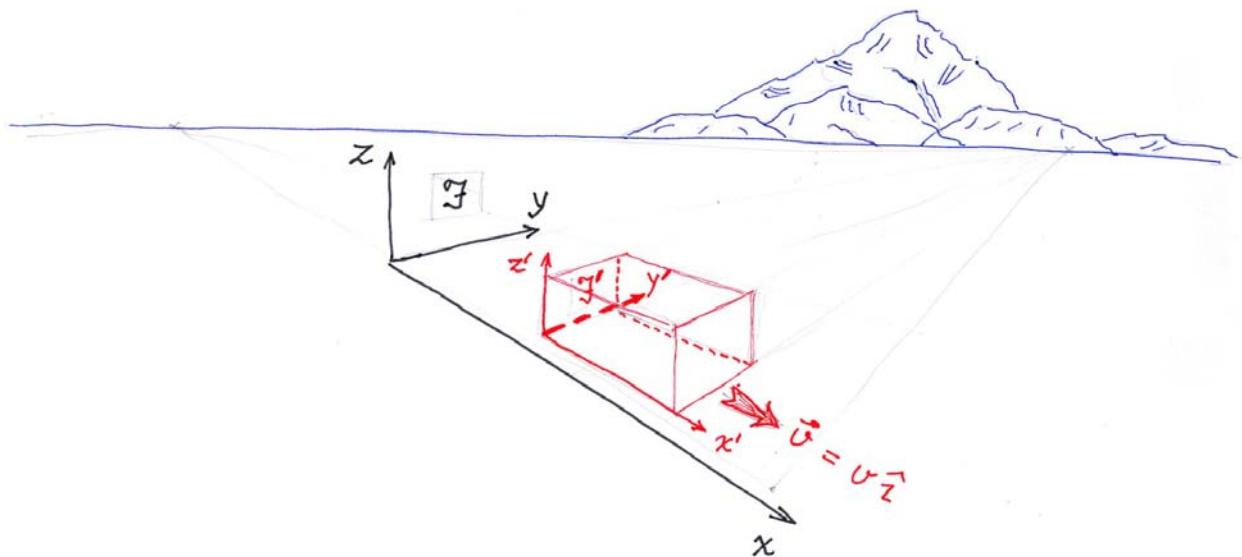
Electromagnetism and Relativity (II) 12.2/1

The Principle of Relativity : the laws of physics are the same in all inertial frames

Inertial frame — a frame of reference in which the "law of inertia" is true ; i.e., an object in motion remains in motion with constant velocity if no force is acting on it. The opposite of an inertial frame is an accelerating frame.



Frame \mathcal{F}' moves with velocity $\vec{v} = v\hat{z}$
relative to frame \mathcal{F} .



The Lorentz transformation

$$ct' = \gamma(ct - \frac{v}{c}x)$$

$$x' = \gamma(x - vt)$$

$$y' = y$$

$$z' = z$$

$$\mathcal{F}' \leftarrow \mathcal{F}$$

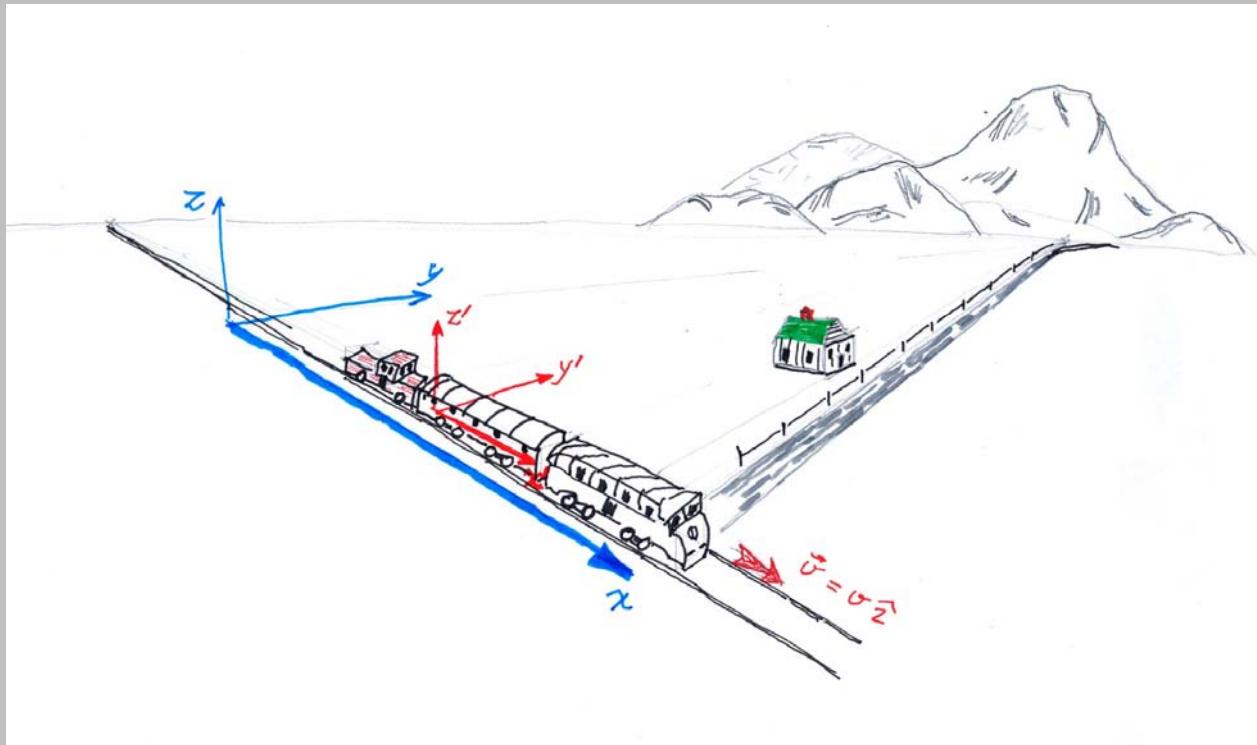
$$ct = \gamma(ct' + \frac{v}{c}x')$$

$$x = \gamma(x' + vt')$$

$$y = y'$$

$$z = z'$$

$$\mathcal{F} \leftarrow \mathcal{F}'$$



How shall we write the equations of physics,
to guarantee that they have the same
form (and make the same predictions)
in all inertial frames?

THEOREM 1 An equation is "manifestly covariant"
if it is written in tensor form.

Minkowski space and Tensor analysis 12.2/2

— vectors, scalars, and tensors

The position of an event in spacetime

$$x^\mu = \begin{bmatrix} x^0 \\ x^1 \\ x^2 \\ x^3 \end{bmatrix} = \begin{bmatrix} ct \\ x \\ y \\ z \end{bmatrix} \quad \text{in coordinates of an inertial frame } \mathcal{F}.$$

The same event, observed relative to the inertial frame \mathcal{F}' has the coordinates

$$x'^\mu = \begin{bmatrix} ct' \\ x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} x'^0 \\ x'^1 \\ x'^2 \\ x'^3 \end{bmatrix}$$

$$\boxed{\beta = v/c}$$

$$\boxed{\gamma = 1/\sqrt{1-v^2/c^2}}$$

The transformation

$$x'^\mu = \Lambda^\mu{}_\nu x^\nu \quad \text{where } \Lambda^\mu{}_\nu =$$

$\uparrow \quad \uparrow$

$\mathcal{F}' \quad \leftarrow \mathcal{F} \quad \rightarrow$

$$\begin{array}{c|cccc} \mu & 0 & 1 & 2 & 3 \\ \hline 0 & \gamma & -\beta\gamma & 0 & 0 \\ 1 & -\beta\gamma & \gamma & 0 & 0 \\ 2 & 0 & 0 & 1 & 0 \\ 3 & 0 & 0 & 0 & 1 \end{array}$$

— the Lorentz transformation matrix —

$$\text{E.g. } x'^0 = \gamma x^0 - \beta\gamma x^1$$

$$ct' = \gamma(ct - \frac{v}{c}x) \quad \text{etc}$$

Define "Vector": A vector is a 4-component quantity V^μ ($\mu = 0, 1, 2, 3$) that transforms in the same way as x^μ ; i.e.,

$$V'^\mu = \Lambda^\mu{}_\nu V^\nu$$

$\uparrow \quad \uparrow$

$\mathcal{F}' \quad \leftarrow \mathcal{F} \quad \rightarrow$

Definition of vector

$$\boxed{V'^\mu = \Lambda^\mu{}_\nu V^\nu}$$

Vectors, i.e., spacetime vectors ...

12.2/3

$$x'^\mu = \Lambda^\mu{}_\nu x^\nu$$

$\Lambda^\mu{}_\nu$ = Lorentz transformation matrix

$$V^\mu = \Lambda^\mu{}_\nu V^\nu \quad \leftarrow \text{definition of a vector}$$

Examples

- x^μ
- $3x^\mu$
- αx^μ for any scalar α

- $x_1^\mu \pm x_2^\mu$
- any linear combination of vectors
- We'll see other examples later, like 4-velocity and 4-momentum

Define "Scalar"

A scalar is a quantity S that has the same value in all inertial frames.

I.e., $S'(x) = S(x)$ \leftarrow where $x'^\mu = \Lambda^\mu{}_\nu x^\nu$

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THEOREM 2 Let V^μ and W^μ be Lorentz vectors.
Then $V \cdot W$, defined by $g_{\mu\nu} V^\mu W^\nu$, is a scalar.

		The metric tensor				
		v	0	1	2	3
u		-1	0	0	0	0
0		0	1	0	0	0
1		0	0	1	0	0
2		0	0	0	1	0
3		0	0	0	0	1

PROOF of theorem 2

$$\begin{aligned}
 V' \cdot W' &= g_{\mu\nu} V'^\mu W^\nu \quad (\text{Einstein summation convention!}) \\
 &= g_{\mu\nu} \Lambda_\rho^\mu V^\rho \Lambda_\sigma^\nu W^\sigma \quad (\text{Einstein summation convention!}) \\
 &\qquad\qquad\qquad \uparrow \text{everywhere!!} \\
 &= V^\rho \left\{ \Lambda_\rho^\mu g_{\mu\nu} \Lambda_\sigma^\nu \right\} W^\sigma
 \end{aligned}$$

a product of 3 matrices, call it $\mathbb{X}_{\rho\sigma}$.
Calculate it below \star .

Thus $V' \cdot W' = g_{\rho\sigma} V^\rho W^\sigma = V \cdot W$. Q.E.D.

$V \cdot W$ has the same value
in all inertial frames
 \Rightarrow a scalar.

$$\star \quad \mathbb{X}_{\rho\sigma} = \underbrace{\begin{bmatrix} \gamma & -\beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \gamma & -\beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}}_{\mathbb{X}_{\rho\sigma}}$$

$$\begin{aligned}
 \mathbb{X}_{\rho\sigma} &= \begin{bmatrix} -\gamma & \beta\gamma & 0 & 0 \\ -\beta\gamma & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \\
 &= \begin{bmatrix} -\gamma^2 + \beta^2\gamma^2 & \beta\gamma^2 - \beta\gamma^2 & 0 & 0 \\ \beta\gamma^2 - \beta\gamma^2 & -\beta^2\gamma^2 + \gamma^2 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = g_{\rho\sigma}
 \end{aligned}$$

$\gamma^2(1-\beta^2) = 1$

Metric Tensor and Scalar Product 12.2/5

	\downarrow
$g_{\mu\nu}$	$\mu\nu$
-1	00
+1	11, 22, 33
0	$\mu \neq \nu$

\downarrow

$$\text{1) } a \cdot b = g_{\mu\nu} a^\mu b^\nu \quad (\sum_{\mu,\nu} \text{ implied!})$$

$$a \cdot b = -a^0 b^0 + a^1 b^1 + a^2 b^2 + a^3 b^3$$

$$a \cdot b = -a^0 b^0 + \vec{a} \cdot \vec{b}$$

2) Or, diag $(-1, 1, 1, 1)$

{ Notation: a^μ is a 4-vector } Spacetime
 { \vec{a} is a 3-vector } Space only

④ Examples

$$x^2 = x \cdot x = -(ct)^2 + x^2 + y^2 + z^2$$

$$x'^2 = x' \cdot x' = -(ct')^2 + x'^2 + y'^2 + z'^2$$

$x^2 = x'^2$ by Theorem 2. Therefore the speed of light is constant. The "light cone":

$$\begin{aligned} x^2 = 0 &\implies ct = \sqrt{x^2 + y^2 + z^2} \\ x'^2 = 0 &\implies ct' = \sqrt{x'^2 + y'^2 + z'^2} \end{aligned}$$

These are the same points in 2 reference frames; c is the same.

⑤ Proper time (τ) of an object in space time

$$c^2 (d\tau)^2 = c^2 (dt)^2 - (dx)^2 - (dy)^2 - (dz)^2$$

$$c^2 (d\tau)^2 = -g_{\mu\nu} dx^\mu dx^\nu$$

REMEMBER?
From Last Time?

$$\hookrightarrow = -(dx) \cdot (dx);$$

SO Proper Time is a scalar by Theorem 2

$$dx \cdot dx = dx' \cdot dx' \quad \leftarrow \text{special case of the general result } V \circ W = V' \circ W'$$

⑥ Vectors used in particle dynamics

Define 4-velocity by $\gamma^\mu = \frac{dx^\mu}{d\tau}$

Do you see why these quantities are vectors?

Define 4-momentum by $p^\mu = m\gamma^\mu = m \frac{dx^\mu}{d\tau}$

REMEMBER? From Last Time?

Tensor Analysis

12.2/6

A tensor T^{uv} is a quantity that transforms
in the same way as $x^u x^v$.

{I.e., this is a tensor
with rank = 2}

$$T'^{uv} = \Lambda^u_{\rho} \Lambda^v_{\sigma} T^{\rho\sigma}$$

\uparrow \uparrow
 \mathcal{F}' \mathcal{F}

Theorem 1 An equation is "manifestly covariant" if it is written in tensor form.

$$\boxed{T_1^{uv} = T_2^{uv}}$$

↗ ↘

Similar idea in classical mechanics:

$$\text{Newton's second law } \vec{F} = m\vec{a}.$$

That's "tensor form" for ordinary 3D vectors.

Newton's second law is "manifestly covariant"
with respect to 3D rotations. \vec{F} and $m\vec{a}$ are both vectors.
i.e. 3D vectors

Proof of the theorem Suppose $T_1^{uv} = T_2^{uv}$ (frame \mathcal{F})

Now consider

$$\begin{aligned} T_1'^{uv} - T_2'^{uv} &= \Lambda^u_{\rho} \Lambda^v_{\sigma} T_1^{\rho\sigma} - \Lambda^u_{\rho} \Lambda^v_{\sigma} T_2^{\rho\sigma} \\ &= \Lambda^u_{\rho} \Lambda^v_{\sigma} [T_1^{\rho\sigma} - T_2^{\rho\sigma}] \\ &= 0 \end{aligned}$$

$\underbrace{= 0}_{= 0}$

so $T_1'^{uv} = T_2'^{uv}$. QED.

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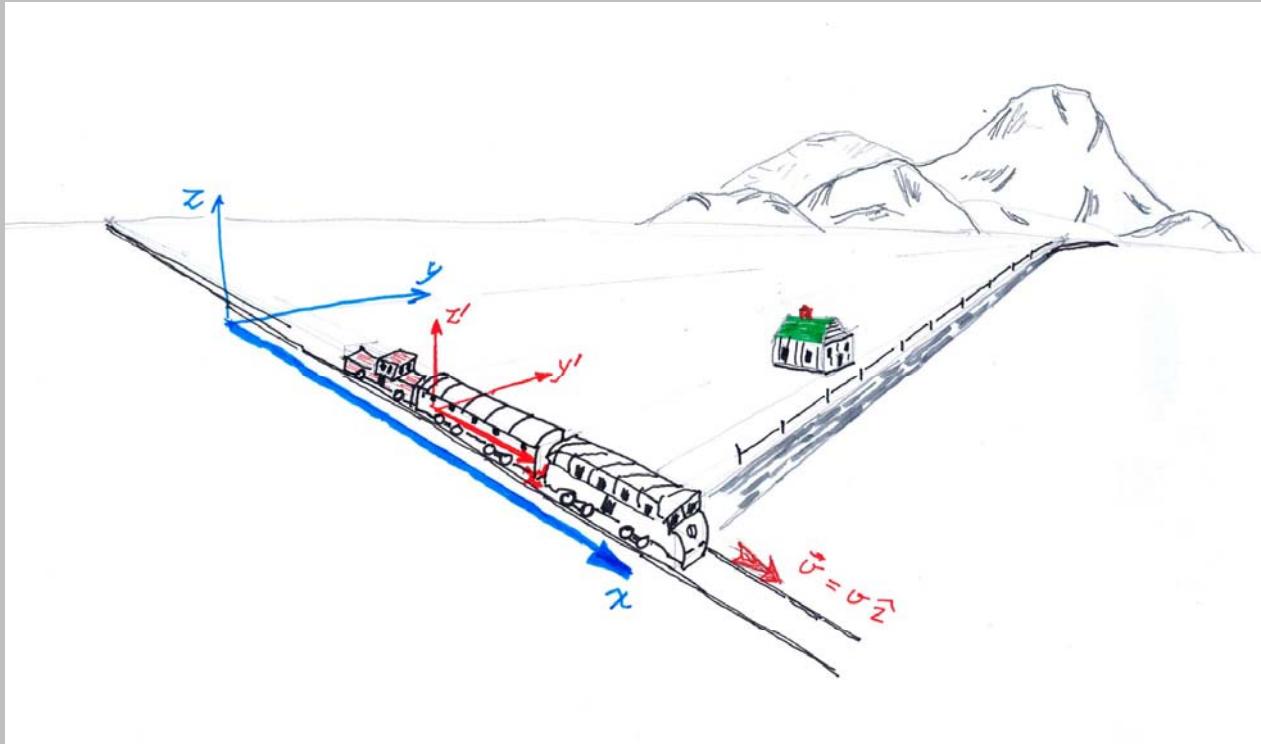
So here is what we'll do after the spring break:

Write the equations of electromagnetism in tensor form

$$\frac{\partial F^{\mu\nu}}{\partial x^\nu} = \mu_0 J^\mu \quad \text{and} \quad \frac{\partial G^{\mu\nu}}{\partial x^\nu} = 0 ,$$

$$\frac{dp^\mu}{dx} = K^\mu = q F^{\mu\nu} \eta_\nu .$$

That will tell us how the fields transform between F and F' !



Quiz Question:
Where are you going for Spring Break?