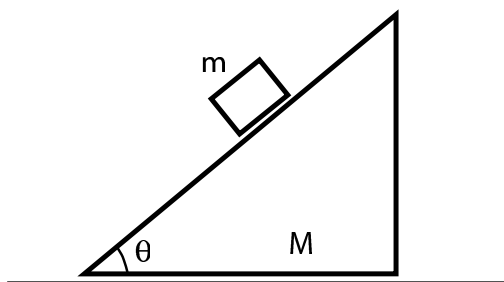


PHY422 Homework Set 2

1. [10 pts] Johnson, problem 1.10. The proper relation to demonstrate is

$$r \cos(\sin \theta (\phi - \phi_0)) = -\frac{\kappa}{\sin \theta}.$$

2. [10 pts] A smooth wedge of mass M has a triangular cross section with a side inclined at an angle θ to the horizontal base. The wedge can slide without friction along a horizontal support. Placed on the side of the wedge is a mass m that can slide with no friction along the side. Find vectors of the acceleration for the wedge and for m after the bodies are released from rest. The methodology is up to you.



3. [5 pts] Obtain the Euler-Lagrange equations of motion for a spherical pendulum, i.e. a point mass m suspended by a rigid weightless rod of length ℓ . The mass is free to move over a spherical surface rather than just the circumference of a circle.
4. [5 pts] A system with n degrees of freedom satisfies a set of Euler-Lagrange equations with a Lagrangian L . Show by a direct substitution into the equations, that that system also satisfies the Euler-Lagrange equations with the Lagrangian

$$L' = L + \frac{dF(q_1, \dots, q_n, t)}{dt},$$

where F is any arbitrary, but differentiable, function of its arguments.

5. [5 pts] Let q_1, \dots, q_n be a set of independent generalized coordinates for a system of n degrees of freedom, with a Lagrangian $L(q, \dot{q}, t)$. Suppose we transform to another set of independent coordinates s_1, \dots, s_n by means of transformation equations

$$q_i = q_i(s_1, \dots, s_n, t), \quad i = 1, \dots, n.$$

(Such a transformation is called a *point transformation*.) Show that if the Lagrangian function is expressed as a function of s_j , \dot{s}_j , and t through the equations of transformation, then L satisfies Lagrange's equations with respect to the s coordinates:

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{s}_j} \right) - \frac{\partial L}{\partial s_j} = 0.$$

In other words, the form of Lagrange's equations is invariant under a point transformation.