## Electromagnetism and Relativity

 (Chapter 12)We live in a 4-dimensional spacetime. Events (e.g., measurements) are observed with respect to coordinates; space ( $x, y, z$ ) and time ( $t$ ).


This frame of reference is called an inertial frame if the "Law of inertia" holds true in terms of these coordinates.

4-vector notation

$$
x^{\mu}=\left(\begin{array}{l}
x^{0} \\
x^{1} \\
x^{2} \\
x^{3}
\end{array}\right)=\left(\begin{array}{l}
c t \\
x \\
y \\
z
\end{array}\right)
$$

which can be confusing: sometimes $x^{\mu}$ means a 4 -vector; but other times $x^{\mu}$ means the $\mu$ component of a vector.

Recall 3-vectors:
$\mathbf{x}=x \mathbf{i}+y \mathbf{j}+z \mathbf{k}$
$x^{i}$ is a notation for the $i$ - th component of $\mathbf{x}$ $x^{1}=x ; x^{2}=y ; x^{3}=z$
$\mu, v, \lambda, \ldots$ greek letters $=0,1,2,3$
$\mathrm{i}, \mathrm{j}, \mathrm{k}, \ldots$ roman letters $=1,2,3$

## Einstein's Postulates <br> of Special Relativity

(1) The laws of physics have the same form in all inertial frames.
(2) The speed of light in free space
is the same in all inertial frames;
$c=2.998 \times 10^{8} \mathrm{~m} / \mathrm{s}$.

## Lorentz transformations

(The equations were first published by Lorentz; they were given a more profound interpretation by A. Einstein.)
Consider two inertial frames,
IF : (ct, $x, y, z$ )
IF': (ct', $\left.x^{\prime}, y^{\prime}, z^{\prime}\right)$
Assume that $\mathbb{F}$ 'moves with velocity vi with respect to .IF
(Later we'll generalize the results for $v$ in an arbitrary direction.)

If and IF.


The position of $0^{\prime}$ (the origin of $F^{\prime}$ )
is $\mathbf{x}_{0}$, with respect to $\boldsymbol{F}$; $\mathbf{x}_{0},(\mathrm{t})=\mathrm{v} \mathrm{t}$.
Exercise.
Derive the transformation $\mathrm{x}^{\mu} \rightarrow \mathrm{x}^{\prime \mu}$.
I.e., given the coordinates of an event in $\mathbb{I}$, what are the coordinates of the same event
in $\mathbb{I}$ '?
Assume it is linear, so
$\mathrm{X}^{\prime \mu}=\sum_{\mathrm{v}=0}{ }^{3} \Lambda^{\mu}{ }_{v} \mathrm{X}^{v} \quad$ (matrix-vector notation)

$$
\begin{aligned}
& c t^{\prime}=\Lambda_{0}^{0} c t+\Lambda_{0}^{0}{ }_{1} x+\Lambda^{0}{ }_{2} y+\Lambda^{0}{ }_{3} z \\
& x^{\prime}=\Lambda_{0}^{1} c t+\Lambda_{1}{ }_{1} x+\Lambda^{1}{ }_{2} y+\Lambda_{3}^{1} z \\
& y^{\prime}=\Lambda^{2}{ }_{0} c t+\Lambda^{2}{ }_{1} x+\Lambda^{2} y+\Lambda^{2}{ }_{3} z \\
& z^{\prime}=\Lambda^{3}{ }_{0} c t+\Lambda^{3}{ }_{1} x+\Lambda^{3}{ }_{2} y+\Lambda^{3}{ }_{3} z
\end{aligned}
$$

(The matrix notation is so much simpler. We will need to get used to 4vector notations; this is also called tensor analysis.)

Galilean Relativity

$$
\begin{aligned}
& c t^{\prime}=c t \\
& x^{\prime}=x-v t \\
& y^{\prime}=y \\
& z^{\prime}=z
\end{aligned}
$$

(1) there is a universal time .
(2) $x^{\prime}=0$ means $x=v t$, as specified.

Spatial axes just translate without any scale change.
So what's wrong with this? The speed of light would not be constant.

## Special Relativity

Try this ...

$$
\begin{aligned}
& c t^{\prime}=A_{1} c t+A_{2} x \\
& x^{\prime}=A_{3}(x-v t) \\
& y^{\prime}=y \\
& z^{\prime}=z
\end{aligned}
$$

Note: $\mathbf{x}^{\prime}=0$ means $\mathbf{x}=\mathbf{v t}$, as specified. $\ldots$ and determine $A_{1}, A_{2}, A_{3}$ to satisfy the postulate of the absolute speed of light.

Suppose

at the origin $O^{\prime}$ at time $t^{\prime}=0$.


The light propagates outward at speed c, in either frame of reference.

- W.R.T. frame $F^{\prime}$

$$
\left(x^{\prime 2}+y^{\prime 2}+z^{\prime 2}\right)^{1 / 2}=c t^{\prime}
$$ or

$x^{\prime 2}+y^{\prime 2}+z^{\prime 2}=c^{2} \mathrm{t}^{\prime 2}$
outgoing spherical pulse


- W.R.T. frame $\boldsymbol{F}$

$$
\begin{equation*}
x^{2}+y^{2}+z^{2}=c^{2} t^{2} \quad \text { (same c }!\text { ) } \tag{2}
\end{equation*}
$$

Substitute the Lorentz transformation into Eq. (1) and compare the result to Eq. (2).

$$
A_{3}{ }^{2}(x-v t)^{2}+y^{2}+z^{2}=\left(A_{1} c t+A_{2} x\right)^{2}
$$

so ...

$$
\begin{aligned}
c^{2} t^{2} & -x^{2}=\left(A_{1} c t+A_{2} x\right)^{2}-A_{3}^{2}(x-v t)^{2} \\
=\left(A_{1}^{2}\right. & \left.-A_{3}^{2} v^{2} / c^{2}\right) c^{2} t^{2} \\
& +\left(A_{1} A_{2}+A_{3}^{2} v / c\right) 2 c t x \\
& +\left(A_{2}^{2}-A_{3}^{2}\right) x^{2}
\end{aligned}
$$

Thus, we require,

$$
\begin{aligned}
& A_{1}^{2}-A_{3}^{2} v^{2} / C^{2}=1 \\
& A_{1} A_{2}+A_{3}^{2} v / c=0 \\
& A_{2}^{2}-A_{3}^{2}=-1
\end{aligned}
$$

Exercise: verify that the solution of these equations is

$$
\begin{aligned}
& A_{1}=A_{3}=\left(1-v^{2} / c^{2}\right)^{-1 / 2} \\
& \text { and } A_{2}=-(v / c)\left(1-v^{2} / c^{2}\right)^{-1 / 2}
\end{aligned}
$$

The Lorentz trunsformution $f$ of $\rightarrow$ of

$$
\begin{aligned}
c t^{\prime} & =\gamma\left(c t-\frac{v}{c} x\right) \quad \gamma=\frac{1}{\sqrt{1-v / c^{2}}} \\
x^{\prime} & =\gamma(x-v t) \\
y^{\prime} & =y \\
z^{\prime} & =z \\
T^{\prime} & \leftarrow \bar{J}
\end{aligned}
$$

The reverse transformation $\mathcal{F}^{\prime \prime} \rightarrow \mathcal{F}$

$$
\begin{aligned}
c t & =\gamma\left(c t^{\prime}+\frac{v}{c} x^{\prime}\right) \\
x & =\gamma\left(x^{\prime}+v t^{\prime}\right) \\
y & =y^{\prime} \\
z & =z^{\prime} \\
\sigma & \leftarrow f^{\prime}
\end{aligned}
$$

Why? Becance of moves with veloaty -v $\hat{z}$ w.r.t. $\mathscr{q}^{\prime}$. ( $\vec{x}=0$ means $\vec{x}^{\prime}=-v_{\hat{\imath}} t^{\prime}$.) Origin $f^{\boldsymbol{q}}$. Change the sign of $v$.

For an arbitrary divectim of the relative velocity $\vec{v}$
Say ने moves welout $\vec{v}$ w.r.t. the frame of, Then

$$
\begin{aligned}
& c t^{\prime}=\gamma\left(c t-\frac{v}{c} x_{11}\right) \\
& x_{11}^{\prime}=\gamma\left(x_{11}-v t\right) \\
& \vec{x}_{1}^{\prime}=\vec{x}_{1} \quad \quad \gamma=1 / \sqrt{1-v^{2} / c^{2}}
\end{aligned}
$$

The Lorentz contraction effect. A meter stick moves with velocity $v$ along the $x$ axis of inertial frame $F$.
Calculate the distance between the ends of the stick at a given time $t$ (ie., for the same time $t$ at both ends).
In the rest frame $\left(F^{\prime}\right)$ the length is $D^{\prime}=1$ meter.

$$
\mathrm{D}^{\prime}=\gamma(\Delta \mathrm{x}-\mathrm{v} \Delta \mathrm{t})
$$

Thus $\Delta x=D^{\prime} / \gamma=\left(1-v^{2} / c^{2}\right)^{1 / 2} D^{\prime}$
If $v=0.1 \mathrm{c}$ then $\Delta x=0.995 \mathrm{~m}$; if $\mathrm{v}=0.9 \mathrm{c}$ then $\Delta \mathrm{x}=0.436 \mathrm{~m}$.

