## The Electromagnetic Field Tensor part I <br> $F^{\mu \mathrm{v}}(\mathrm{x})$

Consider an arbitrary inertial frame

$$
\boldsymbol{F}:\{\mathrm{ct}, \mathrm{x}, \mathrm{y}, \mathrm{z}\}
$$

How do we define the fields $E(x, t)$ and $B(x, t)$ ?
The force on a test charge $q$ is

$$
\mathrm{dp} / \mathrm{dt}=\mathbf{F}=\mathrm{q} \mathbf{E}+\mathrm{q} \mathbf{u} \times \mathbf{B}
$$

where

$$
\mathbf{u}=\text { velocity }=\mathrm{d} \mathbf{x} / \mathrm{dt} .
$$

Recall: $\mathbf{p}=\mathrm{mu} / \sqrt{1-\mathrm{u}^{2} / \mathrm{c}^{2}}$

Now, by the principles of special relativity (the laws of physics are the same in all inertial frames) we should write the equations in covariant form; i.e., write the equations only in terms of Lorentz scalars, vectors and tensors.

## Mathematics of Tensor Analysis

Definitions and Notations
Contravariant vectors: $\mathrm{x}^{\mu}, \mathrm{A}^{\mu}, \ldots$
Covariant vectors: $x_{\mu}, A_{\mu}, \ldots$
These are related by

$$
x_{\mu}=g_{\mu v} x^{v} ; \text { or, } A_{\mu}=g_{\mu v} A^{v}
$$

where we use the Einstein summation
convention (so the sum over v from 0 to 3 is implied).

Here $g_{\mu v}$ is the metric tensor

$$
\mathrm{g}_{\mathrm{\mu v}}=\operatorname{diag}(1,-1,-1,-1) ;
$$

note that

$$
\begin{aligned}
& A_{0}=A^{0} \\
& A_{1}=-A^{1}, A_{2}=-A^{2}, A_{3}=-A^{3}
\end{aligned}
$$

"Raising and lowering the index"
$\left(a_{0}, a_{1}, a_{2}, a_{3}\right)=\left(a^{0},-a^{1},-a^{2},-a^{3}\right)$
Or, equivalently, $a_{\mu}=g_{\mu v} a^{v}$ or $a^{\mu}=g^{\mu v} a_{v}$ where $g^{\mu \mathrm{v}}=g_{\mu \mathrm{v}}$.

Theorem 1. If $\mathrm{A}^{\mu}$ and $\mathrm{B}^{\mu}$ are Lorentz vectors
(contravariant) then $A^{\mu} B_{\mu}$ is a scalar.
(* we always use the Einstein summation convention, so $A^{\mu} B_{u}$ means that we sum over $\mu$ from 0 to 3. *)

Note this tricky important point:
$\mathrm{A}^{\mu} \mathrm{B}_{\mu}$ has no index.
$\mu$ is summed from 0 to 3 .
$\mathrm{A}^{\mu} \mathrm{B}_{\mu}$ means the sum of four terms.

## Proof \#1.

Consider 2 inertial frames, $\boldsymbol{F}$ and $\boldsymbol{F}^{\prime} \&$ relative velocity $\mathbf{v}$.

Relative to frame $F$ we have

$$
\begin{aligned}
& \mathrm{A}^{\mu} \mathrm{B}_{\mu}=\mathrm{A}^{0} \mathrm{~B}^{0}-\mathrm{A}^{1} \mathrm{~B}^{1}-\mathrm{A}^{2} \mathrm{~B}^{2}-\mathrm{A}^{3} \mathrm{~B}^{3} \\
& \quad \text { (do you see why?) } \\
& =\mathrm{A}^{0} \mathrm{~B}^{0}-\mathrm{A}_{\|} \mathrm{B}_{\|}-\mathbf{A}_{\perp} \cdot \mathbf{B}_{\perp}
\end{aligned}
$$

Now consider the Lorentz transformation...

$$
\begin{aligned}
& \mathrm{A}^{\prime \mu} \mathrm{B}_{\mu}^{\prime}=\mathrm{A}^{\prime 0} \mathrm{~B}^{\prime 0}-\mathrm{A}_{1}^{\prime} \mathrm{B}_{\|}^{\prime}-\mathrm{A}_{\perp}^{\prime} \cdot \mathrm{B}_{\perp}^{\prime} \\
& =\gamma\left[A^{0}-(\mathrm{v} / \mathrm{c}) \mathrm{A}\right] \mathrm{\gamma}\left[\mathrm{~B}^{0}-(\mathrm{v} / \mathrm{c}) \mathrm{B}\right] \\
& -\gamma\left[A_{1}-(v / c) A^{0}\right] \gamma\left[B_{\|}-(v / c) B^{0}\right]-A_{\perp} \cdot B_{\perp} \\
& =\gamma^{2} A^{0} B^{0}\left(1-v^{2} / c^{2}\right)-\gamma^{2} A_{1} B_{1}\left(1-v^{2} / c^{2}\right)-A_{\perp} \cdot B_{\perp} \\
& =A^{0} B^{0}-A_{1} B_{\|}-A_{\perp} \cdot B_{\perp} \\
& =A^{\mu} B_{\mu}
\end{aligned}
$$

Q. E. D.

## Proof \#2.

$$
\begin{aligned}
& A^{\prime \mu} B_{\mu}^{\prime}=g_{\mu v} A^{\prime \mu} B^{\prime v} \\
& =g_{\mu v} \Lambda_{\rho}^{\mu} A^{\rho} \Lambda^{\mu} \Lambda_{\rho}^{v}{ }_{\sigma} B^{\sigma} \\
& =g_{\mu v} \Lambda_{\rho}^{\mu} \Lambda_{\sigma}^{v}{ }_{\sigma} A^{\rho} B^{\sigma}
\end{aligned}
$$

## Exercise: Prove that $g_{\mu v} \Lambda^{\mu}{ }_{\rho} \Lambda^{\nu}{ }_{\sigma}=g_{\rho \sigma}$

The metric tensor is the same in all inertial frames; $\operatorname{diag}(1,-1,-1,-1)$.

So...

$$
\begin{equation*}
A^{\prime \mu} B_{\mu}^{\prime}=g_{\rho \sigma} A^{\rho} B^{\sigma}=A^{\rho} B_{\rho} \tag{Q.E.D.}
\end{equation*}
$$

Do you get this?
$A^{\mu} B_{\mu}$ does not depend on $\mu$ because $\mu$ is summed from 0 to 3 by the Einstein summation convention.

$$
\begin{aligned}
A^{\mu} B_{\mu} & =A^{0} B^{0}-A^{1} B^{1}-A^{2} B^{2}-A^{3} B^{3} \\
& =A^{v} B_{v}=A^{\rho} B_{\rho}=A^{\varepsilon} B_{\xi}
\end{aligned}
$$

Theorem 2. If $A^{\mu}$ is a Lorentz vector and $C^{\mu v}$ is a Lorentz tensor, then $\mathrm{C}^{\mathrm{uv}} \mathrm{A}_{\mathrm{v}}$ is a Lorentz vector.

Proof. What do we need to prove? We need to prove that $\mathrm{C}^{\mu \mathrm{v}} \mathrm{A}_{\mathrm{v}}$ transforms in the same was as $x^{\mu}$; i.e., ( remember, $x^{\prime \mu}=\Lambda^{\mu}{ }_{\rho} x^{\rho}$ )

$$
C^{\prime \mu v} A_{v}^{\prime}=\Lambda_{\rho}^{\mu} C^{\rho v} A_{v}
$$

(N. B. : the Einstein summation convention applies to $\rho$ and $v$ )

$$
\begin{align*}
\mathrm{C}^{\prime \mu \mathrm{v}} \mathrm{~A}_{\mathrm{v}}^{\prime} & =\mathrm{g}_{\mathrm{V} \lambda} \mathrm{C}^{\prime \mu \mathrm{v}} \mathrm{~A}^{\prime \lambda}=\mathrm{g}_{\mathrm{v} \lambda} \Lambda^{\mu}{ }_{\rho} \Lambda^{\mathrm{v}}{ }_{\sigma} \mathrm{C}^{\rho \sigma} \Lambda_{\mathrm{K}}^{\lambda} A^{\mathrm{K}} \\
& =\Lambda^{\mu}{ }_{\rho} \mathrm{g}_{\sigma \mathrm{K}} \mathrm{C}^{\rho \sigma} \mathrm{A}^{\mathrm{K}}=\Lambda_{\rho}^{\mu}{ }_{\rho}^{\rho \sigma} \mathrm{C}_{\sigma} \quad \text { (Q. E. } \tag{Q.E.D.}
\end{align*}
$$

Do you get this?
Ignoring the indices, this is how it goes...
$C^{\prime} A^{\prime}=g C^{\prime} A^{\prime}=g \Lambda \Lambda C \Lambda A$

$$
=\Lambda \Lambda \mathrm{g} \Lambda \mathrm{CA}=\Lambda \mathrm{g} \mathrm{CA}=\Lambda \mathrm{CA} ;
$$

... but make sure the indices work out correctly!

## Summary and generalizations

Contraction of ...
contravariant vector and covariant vector $\rightarrow$ scalar
contravariant tensor and covariant vector $\rightarrow$ contravariant vector
tensor of rank n and tensor of rank $\mathrm{m} \rightarrow$ tensor of rank $|n-m|$
rank $1 \square \operatorname{rank} 1=$ rank 0 (i.e., $\mathrm{V} \square \mathrm{V}=\mathrm{S}$ )
rank $2 \square \operatorname{rank} 1=\operatorname{rank} 1$ (i.e., $\mathrm{T} \square \mathrm{V}=\mathrm{V}$ )
In general, $T_{1} \square T_{2}=T_{3}$ where the rank of $T_{3}$ is $\mathrm{n}_{3}=\mathrm{n}_{1}+\mathrm{n}_{2}-\#$ of contracted indices
There are also tensors with mixed contravariant and covariant indices: $\mathrm{T}_{\alpha \beta \gamma} \lambda \mu v$
That is the algebra of tensors.

## The calculus of tensors

Theorem 4. The differential operator $\partial / \partial x^{\mu}$, which we sometimes denote by $\partial_{\mu}$, transforms as a covariant vector.

Proof. Let $\varphi(\mathrm{x})$ be a scalar function of $\mathrm{x}^{\mu}$.
Now consider $\Phi_{\mu} \equiv \partial_{\mu} \varphi$.
According to the theorem, it is a covariant vector. Or, equivalently, $\Phi^{\mu}$ is a contravariant vector. That's what we have to prove.

$$
\begin{aligned}
& \text { Example: Let } \varphi=g_{\rho 0} x^{\rho} x^{\sigma} \text { (a scalar); } \\
& \text { then } \quad \begin{aligned}
\partial_{\mu} \varphi & \varphi g_{\mu \sigma} x^{\sigma}+g_{\mu \mu} x^{\rho} \\
= & 2 g_{\mu \lambda} x^{\lambda}=2 x_{\mu} .
\end{aligned}
\end{aligned}
$$

... a covariant vector, as claimed.

Now watch carefully

$$
\begin{aligned}
& \Phi^{\prime \mu}=g^{\mu \mathrm{v}} \Phi_{\mathrm{v}}^{\prime}=\mathrm{g}^{\mathrm{\mu v}} \quad \partial / \partial \mathrm{x}^{\prime \mathrm{v}} \varphi\left(\mathrm{x}^{\prime}\right) \\
& =g^{\mu v} \partial / \partial x^{\prime v} \varphi(x) \quad\{\text { because } \varphi \text { is a scalar }\} \\
& =g^{\mu v} \partial \varphi / \partial x^{\rho} \quad \partial x^{\rho} / \partial x^{\prime v} \\
& \text { \{ sum over } \rho \text { is implied! \} } \\
& =g^{\mathrm{hv}} \Phi_{\rho}\left[\Lambda^{-1}\right]_{\mathrm{v}}^{\rho} \\
& \left\{\mathrm{x}^{\prime}=\Lambda \mathrm{x} \text { implies } \mathrm{x}=\Lambda^{-1} \mathrm{x}^{\prime}\right\} \\
& =\Lambda_{\sigma}^{\mu} g^{\sigma \rho} \Phi_{\rho} \\
& \text { (recall: } \Lambda \mathrm{g} \Lambda=\mathrm{g} \text { ) } \\
& =\Lambda^{\mu}{ }_{\sigma} \Phi^{\sigma}
\end{aligned}
$$

(Q. E. D.)

## Consequences and generalizations

$$
\begin{array}{ll}
\partial_{\mu} \varphi=\Phi_{\mu} & \text { vector } \\
\partial_{\mu} G_{v}=T_{\mu v} & \text { tensor }
\end{array}
$$

Differentiation produces tensors from vectors.

