Homework Assignment #2 due in class Friday, September 15

[6] Problem 1.35 *
[7] Problem 1.38 *
[8] Problem 1.39 **
[9] Problem 1.44 *
[10] Problem 1.51 *** [computer]

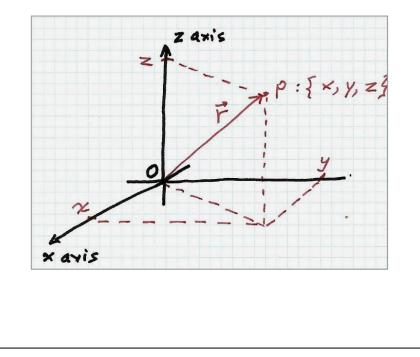
Use the cover sheet.

<u>Computer problems.</u>

- Your best bet is to use *Mathematica*.
- It is available in many MSU microcomputer labs; e.g., 106 Farrell Hall or 1210 Anthony Hall.
- Or, get a free student copy for your laptop.
- If you are not familiar with *Mathematica*, then do the Mathematica tutorial.

THINGS TO STUDY

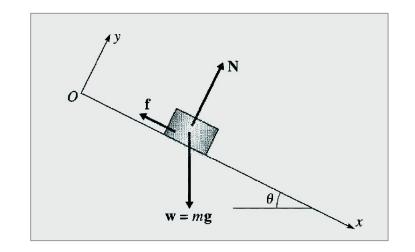
SECTION 1.6 CARTESIAN COORDINATES



 $\vec{r}(t) = \chi(t) \hat{e}_{\chi} + \gamma(t) \hat{e}_{\chi} + z(t) \hat{e}_{z}$ $\vec{F}(\vec{r}) = F_x \hat{e}_x + F_y \hat{e}_y + F_z \hat{e}_z$ F depends on position $\vec{a} = \vec{r} = \vec{F}(\vec{r})$ $a_x = \chi = \frac{F_x}{m}$ etc

Example 1.1

A block sliding down an inclined plane



Determine the motion.

Use the Cartesian coordinates x,y, shown in the figure.

The result is

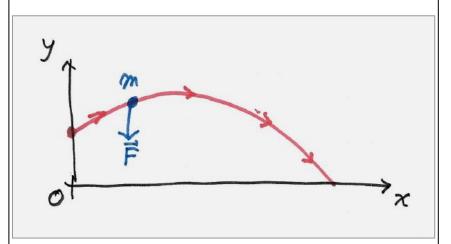
 $m dv_x/dt = mg (sin \theta - \mu cos \theta);$

i.e., constant acceleration along x.

μ = coefficient of friction (PHY 183)

Another example

A projectile in Earth's gravity (PHY 183)



Determine the motion.

Neglecting air resistance ...

2D Cartesian coordinates
 x = horizontal coordinate
 y = vertical coordinate

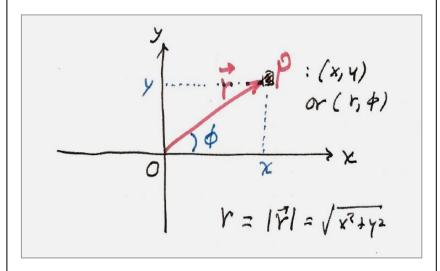
$$F_x = 0$$
 and $F_y = -mg$

The trajectory is a parabola;

$$x(t) = x_0 + v_{0x} t$$

$$y(t) = y_0 + v_{0y} t - \frac{1}{2} g t^2$$

SECTION 1.7 PLANE POLAR COORDINATES



Know (and memorize!) the equations that relate plane polar coordinates (r and θ) and Cartesian coordinates (x and y).

- $x = r \cos \varphi$
- $y = r \sin \varphi$

$$r = sqrt(x^{2}+y^{2})$$
$$tan \phi = y /x$$

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etc.

Example 1.2

The oscillating skateboard Figure 1.14

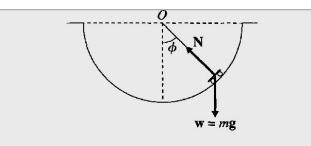


Figure 1.14 A skateboard in a semicircular trough of radius R. The board's position is specified by the angle ϕ measured up from the bottom. The two forces on the skateboard are its weight $\mathbf{w} = m\mathbf{g}$ and the normal force N.

(It is just the same as a simple pendulum – a mass on a string.)

It is natural to use plane polar coordinates, r(t) and φ(t).

(Do you see why?)

The general equations for polar components of acceleration are, in general,

$$a_r = r - r \dot{a}^2 \quad ; \quad a_\phi = r \dot{\phi} + 2 \dot{r} \dot{\phi}$$

For circular motion, r(t) = R ; then

$$-R\dot{\phi}^2 = (mg \, \omega s \phi - N)$$
 and $R\dot{\phi} = (-mg \, sm \phi)/m$

$$\ddot{\phi} = -\frac{a}{R} \sin \phi$$

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IN-CLASS EXERCISES