

Section 2.5.

Motion of a Charged Particle in a Magnetic Field

The magnetic force on a charged particle is the *Lorentz force*,

$$\mathbf{F} = q \mathbf{v} \times \mathbf{B}. \quad (1)$$

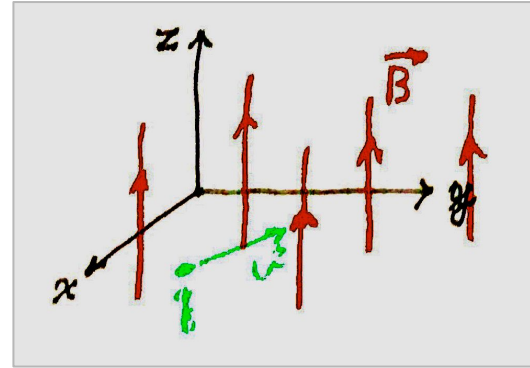
Here \mathbf{B} is the magnetic field. (PHY 184)

In general, $\mathbf{B} = \mathbf{B}(\mathbf{r}, t)$;

in Eq. (1) \mathbf{B} means the field *at the position of the charged particle*.

We'll keep it simple, and assume that \mathbf{B} is uniform in space and constant in time.

Figure 2.12



Charge q moves with velocity \mathbf{v} in a magnetic field \mathbf{B} .

Calculate the trajectory.

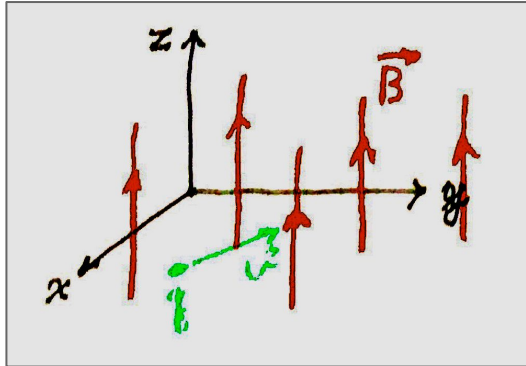
The goal is to solve this equation of motion,

$$m \frac{d\mathbf{v}}{dt} = q \mathbf{v} \times \mathbf{B}$$

Cartesian coordinates

Assume \mathbf{B} is uniform and constant.

Set up a coordinates system such that the z axis is in the direction of \mathbf{B} .



The equations of motion

$$m \frac{d\mathbf{v}}{dt} = q \mathbf{v} \times \mathbf{B}$$

$$m \mathbf{v} = m \{ v_x, v_y, v_z \}$$

$$m \dot{\mathbf{v}} = m \{ \dot{v}_x, \dot{v}_y, \dot{v}_z \}$$

(dot means d/dt)

$$q \mathbf{v} \times \mathbf{B} =$$

$$q \begin{vmatrix} \hat{e}_x & \hat{e}_y & \hat{e}_z \\ v_x & v_y & v_z \\ 0 & 0 & B \end{vmatrix} = q \{ \hat{e}_x v_y B - \hat{e}_y v_x B \}$$

$$q \mathbf{v} \times \mathbf{B} = q \{ v_y B, -v_x B, 0 \}$$

Solutions

The z component

$$m \ddot{z} = 0$$

$$v_z = v_{0z}, \text{ constant}$$

$$z(t) = z_0 + v_{0z} t$$

The transverse components

$$m \dot{v}_x = q B v_y$$

$$m \dot{v}_y = -q B v_x$$

The cyclotron frequency

$$\dot{v}_x = \frac{qB}{m} v_y = \omega v_y$$

$$\text{where } \omega = qB/m$$

$$\ddot{v}_x = \omega \dot{v}_y = -\omega^2 v_x$$

$$v_x = c_1 \cos \omega t + c_2 \sin \omega t$$

$$v_y = \frac{1}{\omega} \dot{v}_x = -c_1 \sin \omega t + c_2 \cos \omega t$$

$\therefore \vec{v}$ sweeps out a circle
of radius $\sqrt{c_1^2 + c_2^2}$.

EXERCISE: $|\mathbf{v}|$ is constant.

Results

$$v_z = \text{constant}; \quad z = v_{0z} t$$

$$v_x = c_1 \cos \omega t + c_2 \sin \omega t$$

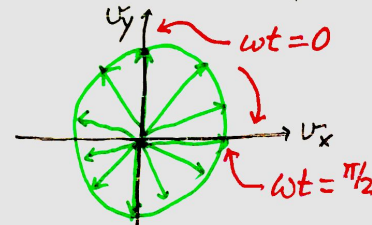
$$\Rightarrow x = \frac{c_1}{\omega} \sin \omega t - \frac{c_2}{\omega} \cos \omega t$$

$$v_y = -c_1 \sin \omega t + c_2 \cos \omega t$$

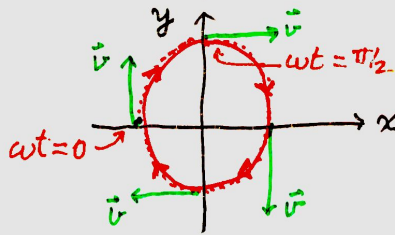
$$\Rightarrow y = \frac{c_1}{\omega} \cos \omega t + \frac{c_2}{\omega} \sin \omega t$$

Assume $v_x(0) = 0$; then $c_1 = 0$.

$$\vec{v}(t) = c_2 \left\{ \hat{e}_x \sin \omega t + \hat{e}_y \cos \omega t \right\}$$



The speed is constant;
 $\sqrt{v_x^2 + v_y^2} = c_2$



The trajectory is a circle;
radius = c_2/ω ;
direction = CLOCKWISE

$$\vec{r}(t) = x(t) \hat{e}_x + y(t) \hat{e}_y$$

The period is $2\pi/\omega$.

The frequency is $\omega/(2\pi)$.

ω is called the *angular frequency*.

It is interesting to analyze the problem using ***complex numbers***.

Define

$$\eta = v_x + i v_y$$

$$i = \sqrt{-1}$$

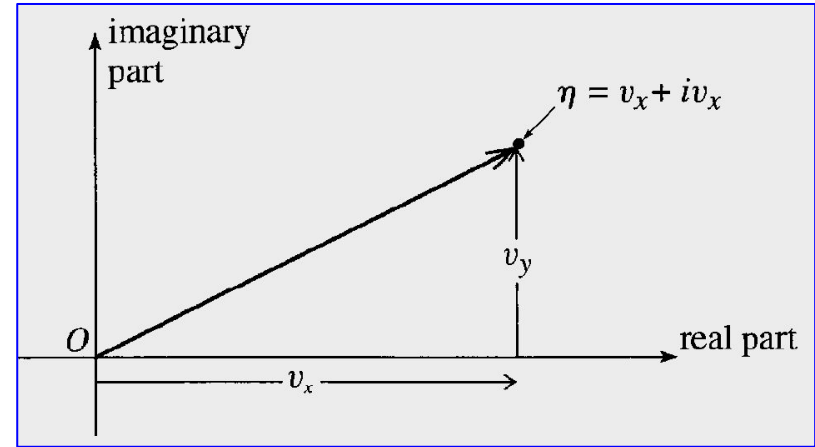
That is,

$$v_x = \text{Re } \eta$$

$$v_y = \text{Im } \eta$$

Figure 2.13 :

The plane of complex numbers



Now write the equations of motion (transverse components) in terms of η .

Solve the equations of motion using the complex variable

$$\eta = v_x + i v_y$$

$$\dot{\eta} = \dot{v}_x + i \dot{v}_y$$

$$= \omega v_y + i(-\omega) v_x$$

$$= -i\omega (v_x + i v_y) = -i\omega \eta$$

$$\dot{\eta} = -i\omega \eta$$

The exponential function

$$\frac{df}{dx} = \alpha f(x) \Rightarrow f(x) = A e^{\alpha x}$$

because then

$$\frac{df}{dx} = A \alpha e^{\alpha x} = \alpha f(x) \quad \checkmark$$

So $\eta(t)$ is an exponential function

$$\eta(t) = A e^{-i\omega t} \quad \text{Complex!}$$

In the next section **[Section 2.6]** we'll review some important properties of complex numbers and the complex exponential function — *widely useful in theoretical physics.*

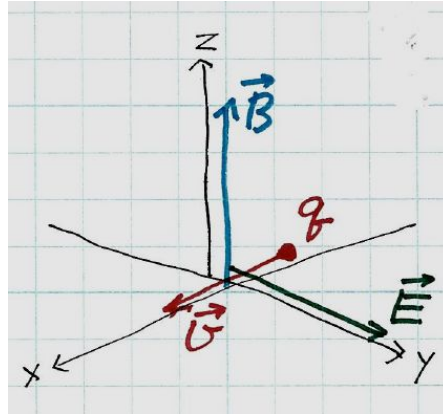
Aside Some related problems:

A charge q moving in both magnetic and electric fields,

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

- If \mathbf{E} and \mathbf{B} are parallel :
Taylor Problem 2.53 (*easy*)

- If \mathbf{E} and \mathbf{B} are perpendicular :



- If $\mathbf{v} = \mathbf{E} \times \mathbf{B} / B^2$ then the charge moves through the fields with constant velocity.

Proof

$$\vec{F} = q\vec{E} + q\vec{v} \times \vec{B}$$

$$= q\vec{E} + q\left(\frac{\vec{E} \times \vec{B}}{B^2}\right) \times \vec{B}$$

$$\bullet (\vec{A} \times \vec{B}) \times \vec{C} = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{A}(\vec{B} \cdot \vec{C})$$

$$= q\vec{E} + \frac{q}{B^2} \left[\underbrace{\vec{B}(\vec{E} \cdot \vec{B})}_0 - \underbrace{\vec{E}(\vec{B} \cdot \vec{B})}_{B^2} \right] = 0$$

(\perp fields)

Q.E.D. by
Newton's first law

- In the most general case, the charge has a "drift velocity" $\mathbf{E} \times \mathbf{B} / B^2$; PHY 481; in general the trajectory is a cycloid curve.

Homework Assignment #4
due in class Wednesday, September 27

- [17] Problem 2.23 *
- [18] Problem 2.31 **
- [19] Problem 2.41 **
- [20] Problem 2.53 *
- [21] Problem 2.43 *** [computer]
- [22] Graph $f_n(x)$.

Use the cover sheet.