

## Chap. 2 : The 2-body central force

### Section 8.3. *The Equations of Motion*

### Section 8.4. *The one-dimensional problem*

Read Sections 8.3 and 8.4.

**Review:** ■————■

the two-body problem reduces to

(1) center of mass motion;  $\mathcal{L}_{\text{CM}} = \frac{1}{2} M \dot{\mathbf{R}}^2$  ;  
 $\Rightarrow M d\mathbf{R}/dt = \text{constant}$  ;  $\mathbf{R} = \mathbf{V}_c t$  .

and

(2) relative motion;  $\mathcal{L}_{\text{rel}} = \frac{1}{2} \mu \dot{\mathbf{r}}^2 - U(r)$  ;  
 $\Rightarrow$  conservation laws .

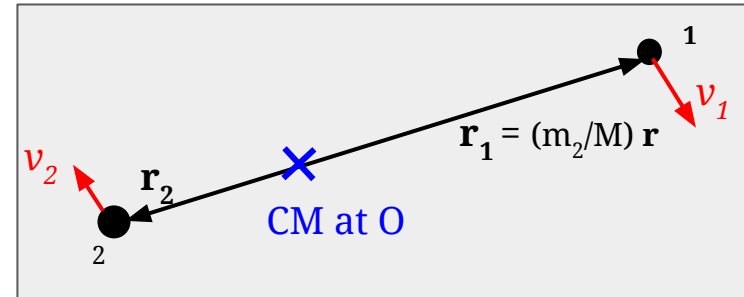
For astronomical examples,

$$U(r) = -G m_1 m_2 / r$$

## 8.3. *The Equations of Motion*

The *center of mass frame of reference* is illustrated in FIG. 8.3;  $\mathbf{R} = \mathbf{0}$  is fixed.

FIGURE 8.3



The Lagrangian is

$$\mathcal{L} = \frac{1}{2} \mu \dot{\mathbf{r}}^2 - U(r) .$$

Lagrange's equations are

$$\mu \ddot{\mathbf{r}} + \nabla U = 0 .$$

## Section 8.3. The Equations of Motion

The Lagrangian is

$$\mathcal{L} = \frac{1}{2} \mu \dot{\mathbf{r}}^2 - U(r).$$

Lagrange's equations are

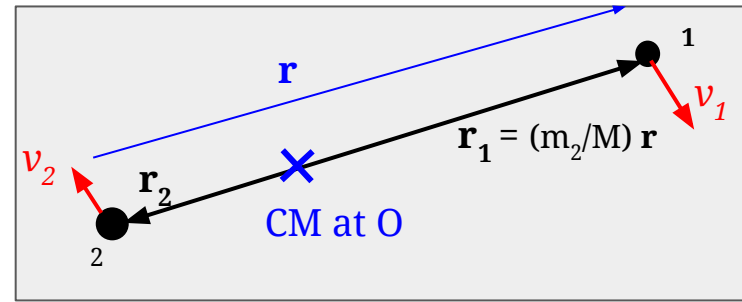
$$\mu \ddot{\mathbf{r}} + \nabla U = 0.$$

We could pretend that this is a one-body problem.

### CONSERVATION OF ANGULAR MOMENTUM

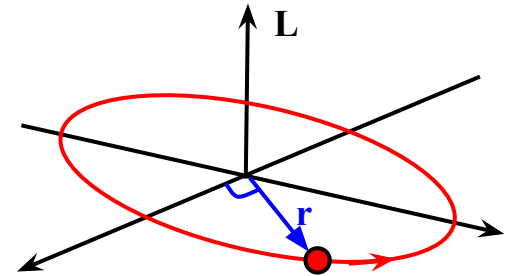
Recall: *the total angular momentum is conserved*, because there are no external forces and the internal force is central.

$$\begin{aligned} \vec{L} &= \vec{r}_1 \times m_1 \vec{v}_1 + \vec{r}_2 \times m_2 \vec{v}_2 \\ &= m_1 \left(\frac{m_2}{M}\right)^2 \vec{r} \times \dot{\vec{r}} + m_2 \left(\frac{m_1}{M}\right)^2 \vec{r} \times \dot{\vec{r}} \\ &= \mu \vec{r} \times \dot{\vec{r}} \quad \text{where } \mu = \frac{m_1 m_2}{M} \end{aligned}$$



Theorem. The orbit lies in a plane.

Proof. Because the vector  $\mathbf{L}$  is perpendicular to the orbit plane, and  $\mathbf{L}$  is constant.



*What about the orbits of  $r_1$  and  $r_2$ ?*

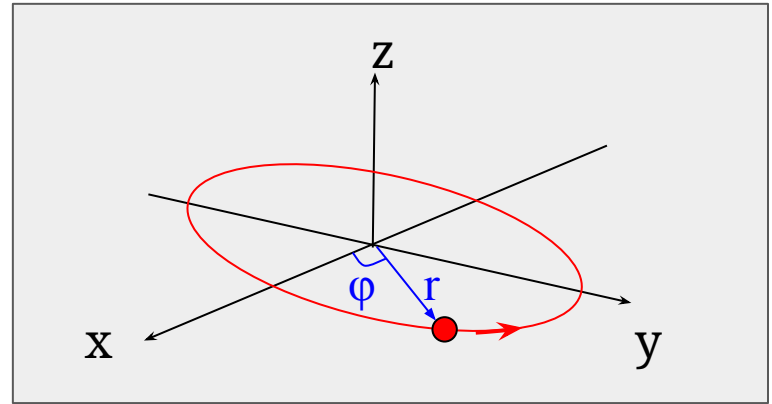
Exercise: Prove that  $d\mathbf{L}/dt = 0$ .

## SPHERICAL POLAR COORDINATES

- Set up a coordinate system.
- Define the xy-plane to be the orbit plane.
- Use spherical polar coordinates  $\{r, \theta, \varphi\}$ .
- The xy-plane is  $\theta = \pi/2$ .
- The Lagrangian for two coordinates,  $r$  and  $\varphi$ , is

$$\mathcal{L} = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\varphi}^2) - U(r)$$

$$d/dt (\partial \mathcal{L} / \partial \dot{q}) - \partial \mathcal{L} / \partial q = 0$$



- The angular coordinate ( $q = \varphi$ )

$$\frac{d}{dt} \left( \frac{\partial \mathcal{L}}{\partial \dot{\varphi}} \right) - \frac{\partial \mathcal{L}}{\partial \varphi} = \frac{d}{dt} (\mu r^2 \dot{\varphi}) = 0$$

$$\mu r^2 \dot{\varphi} = \text{a constant} = \ell$$

$\varphi$  is ignorable; the constant (the generalized momentum) is  $\ell$ .  
Exercise: Show that  $\ell = |\mathbf{L}|$ .

$$\mu r^2 \dot{\phi} = \ell$$

- The radial coordinate,  $r$

$$\begin{aligned} \frac{d}{dt} \left( \frac{\partial \mathcal{I}}{\partial \dot{r}} \right) - \frac{\partial \mathcal{I}}{\partial r} &= \frac{d}{dt} (\mu \dot{r}) - \mu r \dot{\phi}^2 + \frac{dU}{dr} \\ &= \mu \ddot{r} - \mu r \left( \frac{\ell}{\mu r^2} \right)^2 + \frac{dU}{dr} \\ &= \mu \ddot{r} - \frac{\ell^2}{\mu r^3} + \frac{dU}{dr} \\ &= \mu \ddot{r} + \frac{d}{dr} [U_{cf}(r) + U(r)] = 0 \\ \text{where } U_{cf}(r) &= \frac{\ell^2}{2\mu r^2} \end{aligned}$$

We define  $U_{CF}(r) = \ell^2 / (2\mu r^2)$ .

This is called the *CentriFugal potential energy*. It is not really a potential energy; it's really part of the kinetic energy. But it combines with  $U(r)$ , so ...

- The energy

$$\begin{aligned} E &= \frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \mu r^2 \dot{\phi}^2 + U(r) \\ &= \frac{1}{2} \mu \dot{r}^2 + \frac{1}{2} \mu r^2 \left( \frac{\ell}{\mu r^2} \right)^2 + U(r) \\ &= \frac{1}{2} \mu \dot{r}^2 + \frac{\ell^2}{2\mu r^2} + U(r) \\ &= \frac{1}{2} \mu \dot{r}^2 + U_{CF}(r) + U(r) \end{aligned}$$

- The energy is a constant of the motion; prove it ...

$$\begin{aligned} \frac{dE}{dt} &= \frac{1}{2} \mu 2 \dot{r} \ddot{r} + \frac{d}{dr} [U_{CF} + U] \dot{r} \\ &= \dot{r} \left\{ \mu \ddot{r} + \frac{d}{dr} [U_{CF} + U] \right\} \\ &= 0 \quad \text{equivalent to the} \\ &\quad \text{radial equation} \end{aligned}$$

So these are the equations of motion ...

$$(1) \quad \ell = \mu r^2 \dot{\varphi}$$

$$(2) \quad E = \frac{1}{2} \mu \dot{r}^2 + U_{\text{eff}}(r)$$

where  $U_{\text{eff}}(r) = U_{\text{CF}}(r) + U(r)$  "EFFECTIVE POTENTIAL ENERGY"

and  $U_{\text{CF}}(r) = \ell^2 / (2 \mu r^2)$  "CENTRIFUGAL POTENTIAL ENERGY"

$\ell$  and  $E$  are constants, which would be determined from the initial conditions or other information.

One Strategy: First solve (2) [ *which only depends on  $r(t)$*  ]; then integrate (1) to get  $\varphi(t)$ .

Better strategy: First combine (1) and (2) to eliminate  $t$ , and solve for  $r(\varphi)$ ; then integrate (1) to get the relation between  $\varphi$  and  $t$ .

## Section 8.4.

### *The equivalent one-dimensional problem*

#### THE RADIAL EQUATION

$$E = \frac{1}{2} \mu \dot{r}^2 + U_{CF}(r) + U(r)$$

It's a one-dimensional problem;  
try to find  $r(t)$  .

Recall the graphical analysis of potential energy. Kinetic energy is positive, so  $E$  must be greater than  $U_{eff}(r)$ ; or, rather,  ***$r$  is limited to have  $U_{eff}(r) < E$ .***

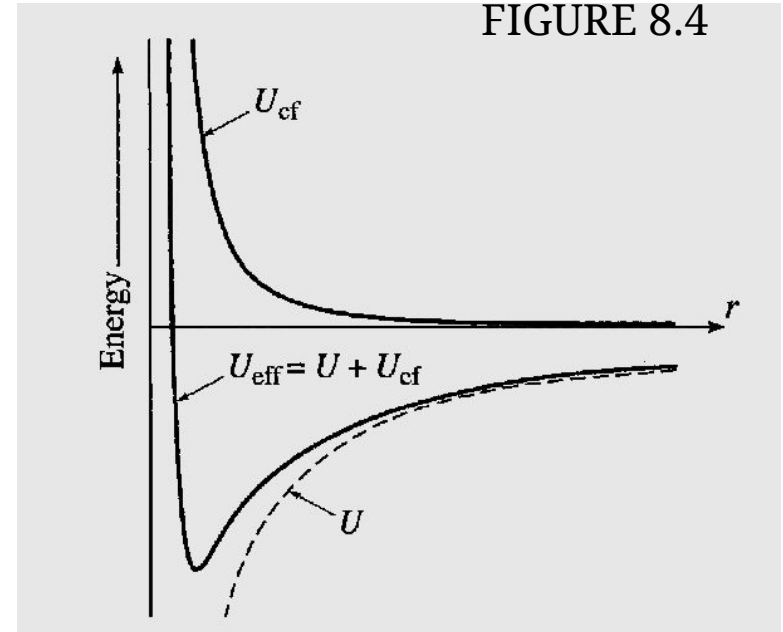
Also, wherever  $U_{eff}(r)$  is equal to  $E$  is a turning point.

#### The effective potential energy

$$U_{eff}(r) = U(r) + \ell^2 / (2\mu r^2)$$

$$U(r) = -G m_1 m_2 / r = -GM\mu / r \quad \text{for satellites}$$

$$U_{CF}(r) = \ell^2 / (2\mu r^2) \quad \text{"centrifugal potential"}$$



## Example 8.2.

### Energy considerations for a comet or planet

Look at FIGURE 8.5.

☒ If  $E < 0$  then there are two turning points, at  $r = r_{\min}$  and  $r = r_{\max}$ .

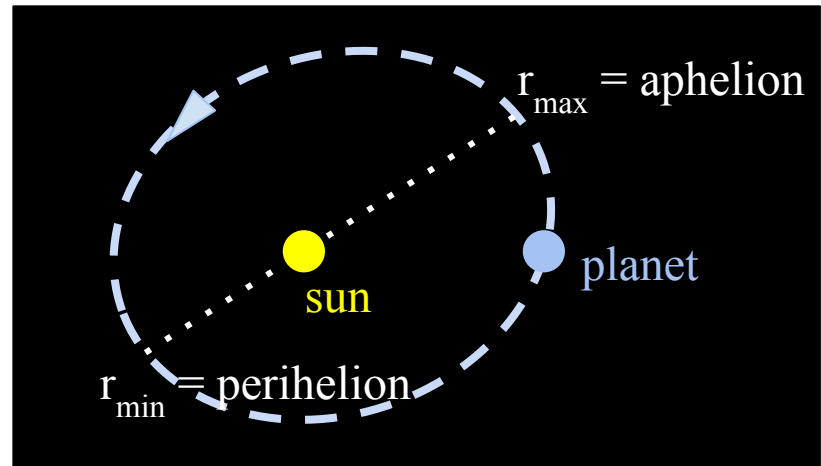
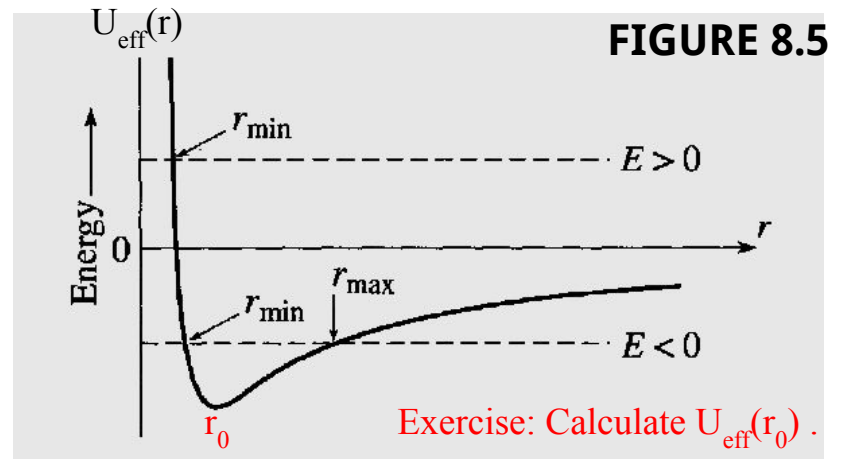
This is a bounded orbit.

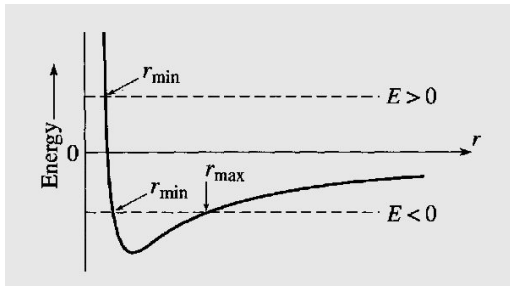
As the satellite revolves around the sun, it never gets closer than  $r_{\min}$  and it never gets farther away than  $r_{\max}$ . At some time,  $r = r_{\min}$ ; then  $r$  increases until  $r = r_{\max}$ ; then  $r$  decreases back to  $r_{\min}$ ; etc.

☒  $r_{\min} = r_{\max} = r_0$  is a circular orbit.

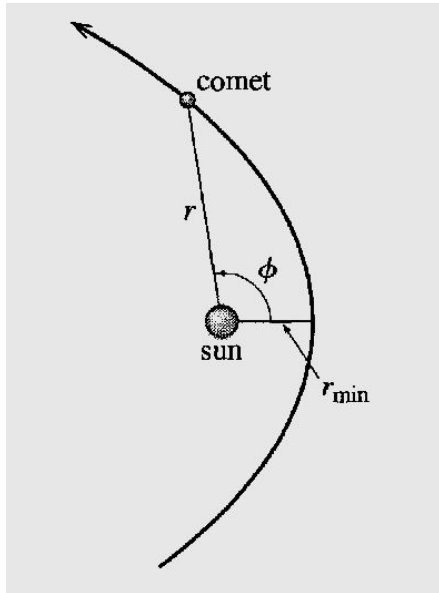
**Exercise: Calculate  $E$  for a circular orbit.**

☒ If  $E > 0$  then there is only one turning point, at  $r = r_{\min}$ . This is an unbounded orbit. The satellite will escape from the sun ( $r \rightarrow \infty$ ).





**FIGURE 8.6 : A typical unbounded orbit**



## Calculate $r(t)$ using a computer

By energy conservation,

$$\dot{r}^2 = \frac{2}{\mu} \left[ E - \frac{l^2}{2\mu r^2} + \frac{GM\mu}{r} \right]$$

with  $r(0) = r_p$ . Then  $E = \frac{l^2}{2\mu r_p^2} - \frac{GM\mu}{r_p}$

Then (PERIHELION)

$$t = \int_{r_p}^r \frac{dr'}{\sqrt{\frac{2}{\mu} \left[ E - \frac{l^2}{2\mu r'^2} + \frac{GM\mu}{r'} \right]}}$$

Calculate the integral numerically,  
then plot  $r$  versus  $t$ .

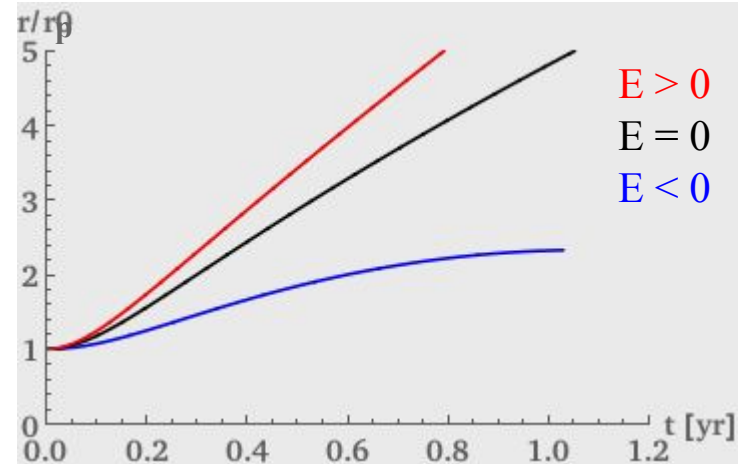
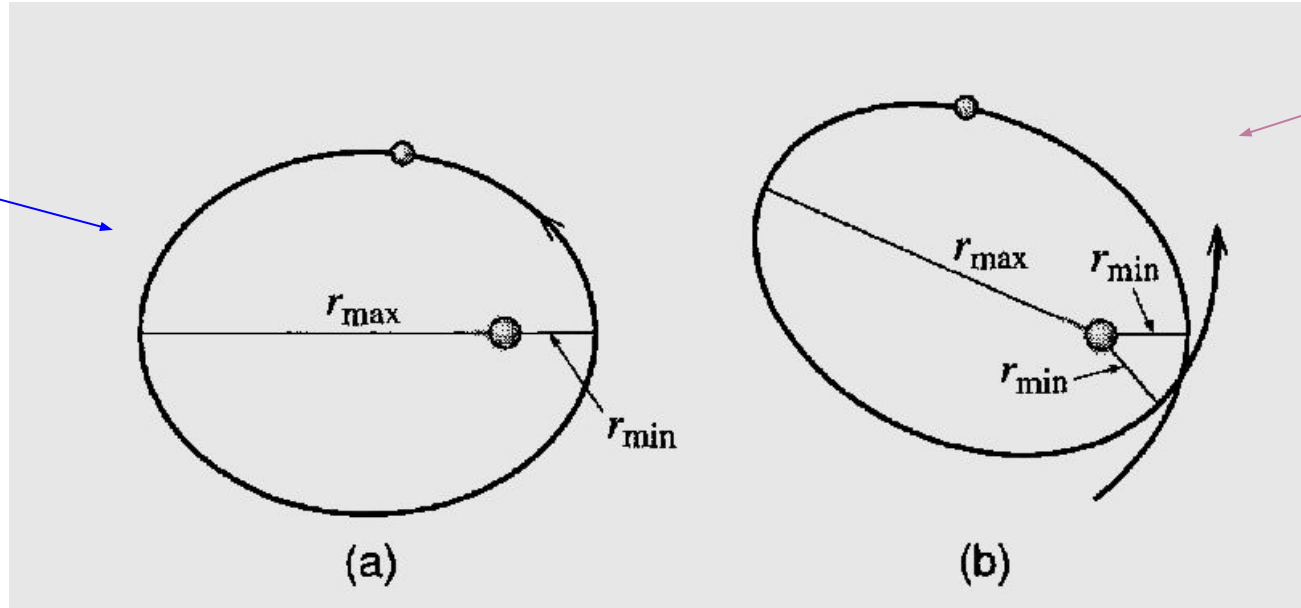




FIGURE 8.7. Typical bounded orbits

(a) A closed orbit: the orbit is a closed curve because when  $r$  varies from  $r_{\min}$  to  $r_{\max}$  to  $r_{\min}$ ,  $\phi$  varies from 0 to  $2\pi$ ; i.e., the *radial period* is equal to the *angular period*; for example, an ellipse.

(b) An unclosed orbit: the orbit is bounded but not closed; in this figure the radial period is less than the angular period; for example, a precessing ellipse.



## Homework Assignment 13

due in class Friday December 2

[71] Problem 8.4 ★

[72] Problem 8.6 ★

[73] Problem 8.12 ★★

[74] Problem 8.15 ★

[75] Problem 8.16 ★★

[76] Another problem on the cover sheet.

*Use the cover sheet.*