MANDL AND SHAW

CHAPTER 4 THE DIRAC FIELD

- 4.1 The number representation for fermions 🗸
- 4.2 The Dirac equation
- 4.3 Second quantization
- 4.4 The fermion propagator
- 4.5 The electromagnetic interaction and gauge invariance
- **PROBLEMS**; 4.1 4.2 4.3 4.4 4.5

APPENDIX A THE DIRAC EQUATION

- A1 A2 A3 A4
- A5 A6 A7 A8
- PROBLEMS; A.1 A.2

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CHAPTER 6 THE DIRAC EQUATION

- 6.1 Properties
- 6.2 Hydrogen atom (skip)
- 6.3 Traces

CHAPTER 7 QUANTIZATION OF THE DIRAC FIELD

- 7.1 Particles and Antiparticles
- 7.2 Second quantization
- 7.3 Canonical quantization
- 7.4 Lorentz group
- 7.5 Microcausality
- 7.6 Spin and statistics

Notations, conventions and units

- Section 1.2: RATIONALIZED gaussian electromagnetic units
- Section 2.1: Relativity notations
- □ Section 6.1: Natural units

$$x^{\mu} = (x^{0}, x^{1}, x^{2}, x^{3}) ; x^{0} = ct$$
 $g^{\mu\nu} = g_{\mu\nu} = \mathbf{DIAG}(1, -1, -1, -1)$
 $x_{\mu} = g_{\mu\nu} x^{\nu} ; (x_{0}, x_{i}) = (x^{0}, x^{i})$
 $p.x = g_{\mu\nu} p^{\mu} x^{\nu} = p^{0} x^{0} - p^{i} x^{i}$
 $p^{2} = p.p = E^{2} - p^{2} = m^{2}$
 $\partial_{\mu} = \partial /\partial x^{\mu} = (\partial /\partial x^{0}, \partial /\partial x^{i})$
 $\hbar = 1 \text{ and } c = 1$

 $\alpha = e^2 / (4\pi\hbar c) = 1 / 137.037$

The Dirac Equation (Read Appendix A and Sec 4.2)

/1/ Recall the Schroedinger equation

$$2t \frac{\partial V}{\partial t} = \frac{-t^2}{2m} \nabla^2 V$$

The plane wave solutions are

$$\Psi(x,t) = C e^{i(p.x-Et)}$$
 (h = 1)

$$H \Psi = E \Psi \implies E = p^2 / 2m$$

(nonrelativisic)

$$\mathbf{P} = -i \nabla$$
, so $\mathbf{P} \Psi = \mathbf{p} \Psi(\mathbf{x}, t)$

The plane wave is an eigenstate of momentum.

/2/ The Dirac equation

We need an equation with these properties:

(i) linear in time, (unlike Klein Gordon)

(ii) with plane wave solutions,

(iii) with
$$E = \sqrt{p^2 + m^2}$$
.

$$\Psi(x,t) \propto e^{i(p.x-Et)} = e^{-ip.x}$$

Should we try

$$H \Psi = \sqrt{p^2 + m^2} \Psi$$
;

i.e.,
$$H = \sqrt{P^2 + m^2}$$
 ?

But that is a nonlocal operator.

• To be consistent with relativity, t and (x, y, z) should be treated similarly; because the Lorentz transformations mix t and (x, y, z).

So let's try

$$i \partial \Psi / \partial t = (\alpha \cdot P + \beta m) \Psi$$

such that

sqrt of
$$P^2+m^2$$

$$(\alpha.P + \beta m)^2 = P^2 + m^2$$

The quantities β and (α_x , α_y , α_z) will be

matrices.

$$\Psi(x,t) \propto e^{i(p.x-Et)} u$$
.

$$(\vec{x} \cdot \vec{p} + \beta m) u = E u$$

 $(\vec{\alpha} \cdot \vec{p} + \beta m)^2 u = E^2 u$

$$\alpha^{i} \alpha^{j} \beta^{i} \beta^{j} + \beta^{2} m^{2}$$
 $+ 2m \beta^{i} (\alpha^{i} \beta + \beta \alpha^{i})$
 $= \beta^{2} + m^{2}$

So we must require
$$\frac{1}{2}(\alpha^{i} \alpha^{j} + \alpha^{j} \alpha^{i}) = \delta_{ij}$$

$$\alpha^{i} \beta + \beta \alpha^{2} = 0$$

$$\beta^{2} = 1$$

 β and (α_x , α_y , α_z) Since they don't commute, they must be matrices. Four - vector notations (Appendix A)
Define $\gamma^0 = \beta$;
also, $(\gamma^1, \gamma^2, \gamma^3) = (\beta \alpha_x, \beta \alpha_y, \beta \alpha_z)$

UPPER AND LOWER INDICES:

$$\{x^{0}, x^{1}, x^{2}, x^{3}\} = \{ct, x, y, z\}$$
 (c = 1)
$$\{x_{0}, x_{1}, x_{2}, x_{3}\} = \{ct, -x, -y, -z\}$$

$$g_{\mu\nu} = diag(1, -1, -1, -1)$$

$$\{y^{0}, y^{1}, y^{2}, y^{3}\} = \beta \{1, \alpha_{x}, \alpha_{y}, \alpha_{z}\}$$

$$\{y_{0}, y_{1}, y_{2}, y_{3}\} = \beta \{1, -\alpha_{x}, -\alpha_{y}, -\alpha_{z}\}$$

$$y \cdot A = y^{\mu} A_{\mu} = y_{\mu} A^{\mu} = y^{0} A^{0} - y^{i} A^{i}$$

$$2^{i} \frac{\Im \psi}{\Im A} = -i \stackrel{\sim}{\alpha} \cdot \nabla \Upsilon + \beta m \Upsilon$$

$$2'\frac{\partial \mathcal{V}}{\partial t} = -i\vec{\alpha}\cdot\nabla\mathcal{V} + \beta m\mathcal{V}$$

$$i\gamma^{0}\frac{\partial \mathcal{V}}{\partial t} = -i\vec{\gamma}\cdot\nabla\mathcal{V} + m\mathcal{V}$$

$$i(\gamma^{0}\frac{\partial}{\partial x^{0}} + \vec{\gamma}\cdot\nabla)\mathcal{V} - m\mathcal{V} = 0$$

$$i$$
 (γ^0 $\partial_0^{}$ + γ^i $\partial_i^{}$) $\psi^{}-m$ $\psi^{}$ = 0

That is the Dirac equation.

Various notations may be used

$$i \gamma^{\mu} \partial_{\mu} \psi - m \psi = 0$$

$$i \gamma \cdot \partial \psi - m \psi = 0$$

$$i \not \partial \psi - m \psi = 0$$

Slash notation

$$\not Q = \gamma^{\mu} Q_{\mu}$$
.

/3/ The gamma matrices

What are the gamma matrices?

They are not unique.

The gamma matrices are 4 X 4 matrices, defined by certain anticommutation relations:

Thus, the defining equation is

$$\{ \gamma^{\mu}, \gamma^{\nu} \} = 2 g^{\mu\nu}$$
 (**)

Theorem. If $\{\gamma^{\mu}, \gamma^{\nu}\} = 2 g^{\mu\nu}$, and U is a unitary matrix (U*U = 1), then $\{\gamma^{\prime \mu}, \gamma^{\prime \nu}\} = 2 g^{\mu\nu}$ where $\gamma^{\prime \mu} = U \gamma^{\mu} U^{*}$.

Proof.

Exercise.

Find U such that $\gamma_{\mathbf{M}}^{\mu} = U \gamma^{\mu} U^{\dagger}$.

• The standard representation ("Dirac rep.") for the gamma matrices is

$$y^{\circ} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \text{ and } y^{\circ} = \begin{pmatrix} 0 & \sigma_{a'} \\ -\sigma_{a'} & 0 \end{pmatrix}$$
where $1 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$ and $\sigma_{a'} = i \text{ th } Pauli makrix$

$$\sigma_{x} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_{y} = \begin{pmatrix} 0 & -2i \\ 2i & 0 \end{pmatrix}, \quad \sigma_{z} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

Exercise. Verify (★). (We never raise the index on a Pauli matrix!)

• The Majorana representation

$$\chi_{M}^{0} = \begin{pmatrix} 0 & \sigma_{2} \\ \sigma_{2} & 0 \end{pmatrix}$$
 and $\chi_{M}^{1} = \begin{pmatrix} i \sigma_{3} & 0 \\ 0 & i \sigma_{3} \end{pmatrix}$ etc.

See (A.79)

which is sometimes convenient.

 (Peskin and Schroeder use yet a different representation.) For most calculations, we don't need to use any specific representation of the gamma matrices. Instead we can use some identities that are true for all representations.

$$\{ \gamma^{\mu}, \gamma^{\nu} \} = 2 g^{\mu\nu}$$
 (\(\phi\)

/4/ Examples of gamma matrix identities

I Trace ($\gamma^{\mu} \gamma^{\nu}$)

Lemma. Trace(BA) = Trace(AB).

Proof. Trace(BA)

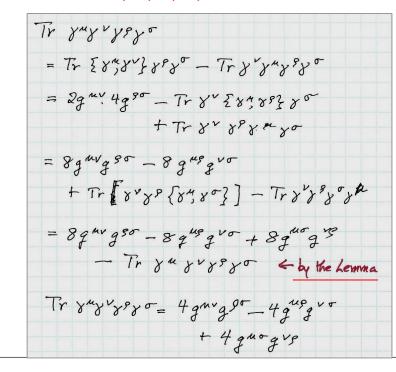
- $= \sum B_{rs} A_{sr} = \sum A_{sr} B_{rs}$
- = Trace(AB).

Even if A and B do not commute, i.e., $BA \neq AB$, always Tr(BA) = Tr(AB).

$$T_{r} y_{uyv} = \frac{1}{2} T_{r} (y_{uyv} + y_{vyu})$$

$$= \frac{1}{2} T_{r} 2q^{uv} I_{uv} = 4q^{uv}$$

I Trace ($\gamma^{\mu} \gamma^{\nu} \gamma^{\rho} \gamma^{\sigma}$)



$$8^{n}\gamma^{g}\delta_{n} = \{3^{n}, 3^{g}\}\delta_{n} - 3^{g}\delta^{n}\delta_{n}$$

$$= 2g^{ng}\delta_{n} - 3^{g}\delta^{n}\delta_{n}$$

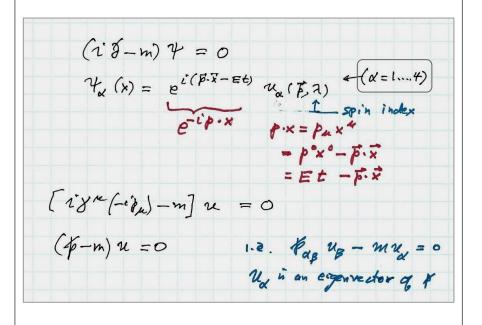
$$= -23^{g}$$

Etc.

We'll use many such identities. See the Appendix, Sections A.2 and A.3.

/5/ The Dirac spinors

► Plane wave solutions of the Dirac equation



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Now, consider (p-m)(p+m)

= pp - m^2 = ymy^{\nu} p_{\mu}p_{\nu} - m^2
= \frac{1}{2} \frac{2}{8} \frac{8}{1} \frac{8}{1} \frac{9}{1} \frac{9}{1} p_{\mu}p_{\nu} - m^2
= p^2 - m^2 = 0
Therefore, u(\bar{p}, \lambda) can be any of the 4 columns of p+m.
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► In the standard (Dirac) representation:

Normalization choice

Ut (F) US (F) = E Srs

This can be done in different ways.

We'll follow Mandl and Shaw: eq. (A.27);

$$u_r^t(F) u_s(F) = \frac{E}{m} \delta_{rs}$$
 $r, s \in \{1, 2\}$

and
$$\sum_{r=1}^{2} (u_r \overline{u}_r - v_r \overline{v}_r) = 1_{4\times4}$$
 completeness

r, s ∈ {1, 2}

Check the normalization:

"ENERGY PROJECTION OPERATORS"; Section A.5;

Homework Problems due Friday, Feb. 17

Problem 24.

- A. Determine the Dirac spinors $v_1(p)$ and $v_2(p)$ for antiparticles.
- B. Determine the polarization sum Λ^- (p) for antiparticles.