Some ancient history

Who discovered magnetism?

■ The discovery of magnetism is attributed to *Thales of Miletus*.

■ Thales (624 – 546 BC) was the first pre-Socratic philosopher of Ancient Greece.

■ Thales was the first scientist in the history of Western Civilization—remembered for discoveries in mathematics, astronomy, electricity and magnetism.

■ "A lodestone has a soul because it can cause movement of iron."

■ Origin of the word "magnet".



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Lecture 2-3 {Wed , Sept 18} Methods of solving boundary-value problems in magnetostatics

Jackson Section 5.9

The field equations are

 $\nabla \cdot \vec{B} = 0$ and $\nabla \times \vec{H} = \vec{J}$

where J means J_{free} . B and H are related by some constitutive relation. But that's only part of the problem. The other part consists of the *boundary conditions*.

Jackson gives three methods.

A. The vector potential

We always have $\nabla \cdot \vec{B} = 0$; then we can write

 $\vec{B} = \nabla \times \vec{A}$

and now solve for $\vec{A}(\vec{x})$.

If there is a linear constitutive equation, $\vec{B} = \mu \vec{H}$, then

 $\nabla \times (\nabla \times \overrightarrow{A}) = \mu \overrightarrow{J}$

which is analogous to Poisson's equation.

B. The scalar potential (requires $\vec{J}_{\text{free}} = 0$) This method can be used in any region of space where $\vec{J} = 0$. Then $\nabla \times \vec{H} = 0$ so we can write

 $\stackrel{\rightarrow}{H} = - \nabla \Phi_M$

For a linear constitutive equation, $\vec{B} = \mu \vec{H}$, the other field equation gives

 $\nabla \cdot (\mu \nabla \Phi_{\mathsf{M}}) = 0$

which is analogous to Laplace's equation.

C. "Hard Ferromagnets": \vec{M} is given and $\vec{J}_{\text{free}} = 0$.

Although $J_{\text{free}} = 0$, there are *bound* molecular currents in (or on the surface) of the matter (iron or ...) producing a magnetic field.

C (a) Using a scalar potential ...

Since $\vec{J} = 0$, write $\vec{H} = -\operatorname{grad} \Phi_M$. Now div $\vec{B} = 0 = \mu_0 \operatorname{div} (-\operatorname{grad} \Phi_M + \vec{M})$; $\therefore \nabla^2 \Phi_M = -\rho_M$ where $\rho_M = -\operatorname{div} \vec{M}$. The problem reduces to Poisson's equation.

C (b) Using a vector potential ...

We can always write $\vec{B} = \operatorname{curl} \vec{A}$. Then curl $\vec{H} = \vec{J} = 0$ implies curl $\begin{bmatrix} \vec{B} & / \mu_0 - \vec{M} \end{bmatrix} = 0$ Or, $\nabla^2 \vec{A} = -\mu_0 \vec{J}_M$ where $J_M = \nabla \times \vec{M}$. Again, this is Poisson's equation.



Jackson Section 5.10



 $\vec{M} = M_0 \hat{e}_z$ inside, i.e. for r < a. What are \vec{B} and \vec{H} both inside and outside? Solution by method C (a). Write $H = -\nabla \Phi_M$ because $J_{\text{free}} = 0$. For r < a, $\Phi_M(r,\theta) = -c_1 r \cos \theta = -c_1 z$; For r > a, $\Phi_M(r,\theta) = c_2 \frac{\cos\theta}{r^2}$; ... solutions of Laplace's equation. Boundary conditions at $r = a \dots$ B_r is continuous at r = a $B_r = \mu_0 \{ H_r + M_0 \cos \theta \} = \mu_0 H_r$ $c_1 + M_0 = 2 c_2 / a^3$ H_t is continuous at r = a $H_{\theta}(r=a-) = H_{\theta}(r=a+)$ $-c_1 = c_2 / a^3$ Solution: $c_1 = -\frac{M_0}{3}$ and $c_2 = \frac{M_0 a^3}{3}$

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$$\vec{H}(\mathbf{r},\theta) = \begin{cases} c_1 \hat{e}_z = -\frac{M_0}{3} \hat{e}_z & \text{for } r < a \\ c_2 \left[\hat{r} \frac{2\cos\theta}{r^3} + \hat{\theta} \frac{\sin\theta}{r^3} \right] & \text{for } r > a \end{cases}$$

$$\vec{B}(\mathbf{r},\theta) = \begin{cases} \mu_0 \frac{2M_0}{3} & \text{for } \mathbf{r} < a \\ \vec{\mu}_0 \vec{H}(\mathbf{r},\theta) & \text{for } \mathbf{r} > a \end{cases}$$

Solution by method C (b).

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Write $\overrightarrow{B} = \operatorname{curl} \overrightarrow{A}$. There is a bound surface current $\overrightarrow{K_M}(\overrightarrow{x'}) = M_0 \ \hat{e}_z \times \hat{r'} = M_0 \sin \theta' \ \hat{e}_{\phi}'$ The vector potential $\overrightarrow{A}(\overrightarrow{x}) = A_{\phi} \ \hat{e}_{\phi}$ can be calculated from the Green's function integral \Longrightarrow

 $A_{\phi}(\vec{x}) = \frac{\mu_0}{3} M_0 a^2 \frac{r_{<}}{r_{>}^2} \sin \theta$

where $r_{<} = \min\{r,a\}$ and $r_{>} = \max\{r,a\}$.

This gives the same constant \vec{B} inside the sphere, and the same dipole field \vec{B} outside the sphere.

