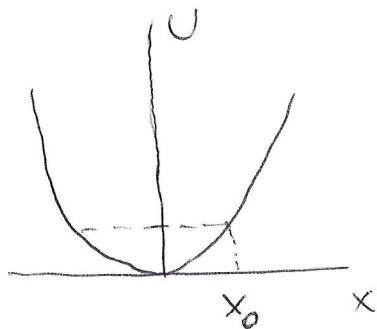


## Problem Set 2

1. Consider a particle with the Hamiltonian



$$H = \frac{P^2}{2m} + U(x), \quad U(x) = \frac{1}{2} m \omega^2 x^2$$

If the particle is "smeared" over the range  $\sim x_0$ , its potential energy is  $U \sim \frac{1}{2} m \omega^2 x_0^2$ . The uncertainty

of the momentum is  $\Delta p \sim \frac{\hbar}{x_0}$ , and thus the kinetic energy is  $\frac{P^2}{2m} \sim \frac{\hbar^2}{2m x_0^2}$ . Then the total energy is  $E \sim \frac{\hbar^2}{2m x_0^2} + \frac{1}{2} m \omega^2 x_0^2$ ; Minimize over  $x_0$  (or  $x_0^2$ -easier):

$$-\frac{\hbar^2}{2m(x_0^2)^2} + \frac{1}{2} m \omega^2 = 0, \quad x_0^2 = \frac{\hbar}{m \omega}$$

and then  $E \sim \hbar \omega$ . The correct answer is, as you know,  $E_{\min} = \frac{\hbar \omega}{2}$ , but we have obtained a reasonable estimate

## Problem Set 2

2. We have from  $x = r \sin \theta \cos \varphi$ ,  $y = r \sin \theta \sin \varphi$ ,  $z = r \cos \theta$ :

$$\frac{\partial}{\partial \theta} = z \cos \varphi \frac{\partial}{\partial x} + z \sin \varphi \frac{\partial}{\partial y} - z \tan \theta \frac{\partial}{\partial z} \quad \left| \begin{array}{l} \text{use } y \cot \theta = z \sin \varphi \\ x \cot \theta = z \cos \varphi \end{array} \right.$$

$$\frac{\partial}{\partial \varphi} = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}$$

Then  $L_{\pm} = (\text{from textbook}) \pm i e^{\pm i \varphi} \left( \frac{\partial}{\partial \theta} \pm i \cot \theta \frac{\partial}{\partial \varphi} \right)$

$$= \pm i e^{\pm i \varphi} \left( z \cos \varphi \frac{\partial}{\partial x} + z \sin \varphi \frac{\partial}{\partial y} - z \tan \theta \frac{\partial}{\partial z} \right)$$

$$\pm i \cot \theta \left( -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right)$$

$$= \pm i e^{\pm i \varphi} \left[ \frac{\partial}{\partial x} \underbrace{(z \cos \varphi \mp iy \sin \varphi)}_{ze^{\mp i \varphi}} + \frac{\partial}{\partial y} \underbrace{(z \sin \varphi \pm iz \cos \varphi)}_{\mp i z e^{\mp i \varphi}} - z \tan \theta \frac{\partial}{\partial z} \right]$$

On the other hand,

$$L_{\pm} = L_x \pm i L_y = y P_z - z P_y \pm i (z P_x - x P_z) = -i \hbar \left( \pm i z \frac{\partial}{\partial x} - z \frac{\partial}{\partial y} + (y \mp ix) \frac{\partial}{\partial z} \right)$$

Noting that  $y \mp ix = z \tan \theta (\sin \varphi \mp i \cos \varphi) = \mp i z e^{\pm i \varphi} \tan \theta$ , we see that the expressions for  $L_{\pm}$  coincide.

$$\begin{aligned} \text{We have } L_- (\sin \theta)^l e^{-il\varphi} &= -i e^{-i\varphi} \left[ \frac{\partial}{\partial \theta} - i \cot \theta \frac{\partial}{\partial \varphi} \right] (\sin \theta)^l e^{-il\varphi} \\ &= -i e^{-i\varphi} \left[ l (\sin \theta)^{l-1} \cos \theta e^{-il\varphi} - i \cot \theta (\sin \theta)^l (-i) e^{-il\varphi} \right] \\ &= -i e^{-i\varphi} l e^{-il\varphi} \left[ (\sin \theta)^{l-1} \cos \theta - \frac{\cos \theta}{\sin \theta} (\sin \theta)^l \right] = 0 \end{aligned}$$

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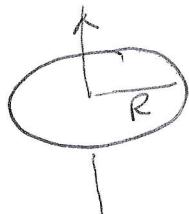
3. We have  $L^2 = L_+L_- + L_z^2 - \hbar L_z$  | Using the previous problem,  
 $L_z = -i\hbar \frac{\partial}{\partial \varphi}$

$$\begin{aligned}
 &= -\hbar^2 e^{i\varphi} \left[ \frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \varphi} \right] e^{-i\varphi} \left( \frac{\partial}{\partial \theta} - i \cot \theta \frac{\partial}{\partial \varphi} \right) - \hbar^2 \frac{\partial^2}{\partial \varphi^2} + i \hbar^2 \frac{\partial}{\partial \varphi} \\
 &= -\hbar^2 \left[ \frac{\partial^2}{\partial \theta^2} + \frac{i}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} - i \cot \theta \frac{\partial^2}{\partial \theta \partial \varphi} + i \cot \theta \frac{\partial^2}{\partial \varphi \partial \theta} + \cot \theta \frac{\partial}{\partial \theta} \right. \\
 &\quad \left. + \cot^2 \theta \frac{\partial^2}{\partial \varphi^2} - i \cot^2 \theta \frac{\partial}{\partial \varphi} \right] - \hbar^2 \frac{\partial^2}{\partial \varphi^2} + i \hbar^2 \frac{\partial}{\partial \varphi} \\
 &= -\hbar^2 \left[ \frac{\partial^2}{\partial \theta^2} + \cot \theta \frac{\partial}{\partial \theta} \right] - \hbar^2 (\cot^2 \theta + 1) \frac{\partial^2}{\partial \varphi^2} \\
 &= -\hbar^2 \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial}{\partial \theta} \right) - \frac{\hbar^2}{\sin^2 \theta} \frac{\partial^2}{\partial \varphi^2}
 \end{aligned}$$

## Problem Set 2

4.

The magnetic moment is  $\mu = I \cdot A$



$$A = \pi R^2. \text{ Current} = \frac{\text{charge through cross section}}{\text{time}}$$

Make a cross section of the donut, assume flat it spins with angular velocity  $\omega$ . Period is  $\frac{2\pi}{\omega}$ . Current is

$$I = \frac{\text{charge}}{\text{time}} = \frac{Q}{2\pi/\omega} = \frac{\omega}{2\pi} Q. \text{ Then } \mu = \frac{\omega}{2} Q R^2$$

$$\text{Angular momentum is } L = M \omega R^2.$$

$$\text{The gyromagnetic ratio is } \frac{\mu}{L} = \frac{Q}{2M}$$