4.5Vdc -14Vdc input; 0.5Vdc to 2.0Vdc output; 80A Output Current

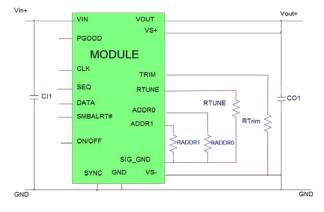




# **RoHS Compliant**

# **Applications**

- Networking equipment
- Telecommunications equipment
- Servers and storage applications
- Distributed power architectures
- Intermediate bus voltage applications
- Industrial equipment



#### **Features**

- Compliant to RoHS EU Directive 2002/95/EC (Z versions)
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Compatible in a Pb-free or SnPb reflow environment (Z versions)
- Wide Input voltage range (4.5Vdc-14Vdc)
- Output voltage programmable from 0.6Vdc to 2.0Vdc via external resistor. Digitally adjustable down to 0.5Vdc output.
- Digital interface through the PMBus™ # protocol
- Digital output voltage control loop
- Remote On/Off
- Digital Sequencing
- Power Good signal
- Fixed switching frequency with capability for external synchronization
- Ability to sink and source current
- Output overcurrent protection (non-latching)
- Over temperature protection
- Cost efficient open frame design
- Small size: 33.02mm x 22.86mm x 12.7mm [1.3" x 0.9" x 0.5"]
- Wide operating temperature range [-40°C to 85°C]
- UL\* 60950-1 2<sup>nd</sup> Ed. Recognized, CSA<sup>†</sup> C22.2 No. 60950-1-07 Certified, and VDE<sup>‡</sup> (EN60950-1 2<sup>nd</sup> Ed.) Licensed
- ISO\*\* 9001 and ISO 14001 certified manufacturing facilities

### Description

The 80A Digital GigaDLynx<sup>™</sup> power modules are non-isolated dc-dc converters that deliver up to 80A of output current. These modules operate over a wide range of input voltage (V<sub>IN</sub> =4.5Vdc - 14Vdc) and provide a precisely regulated output voltage from 0.6Vdc to 2Vdc, programmable via an external resistor and/or PMBus control. Features include a digital interface using the PMBus protocol, remote On/Off, adjustable output voltage, over current, over voltage and over temperature protection. The PMBus interface supports many commands to both control and monitor the module. The module also include a digital output voltage control loop that allows optimizing the dynamic response of the converter with reduced amounts of output capacitance leading to savings on cost and PWB area.

- \* UL is a registered trademark of Underwriters Laboratories, Inc.
- <sup>†</sup> CSA is a registered trademark of Canadian Standards Association.
- † VDE is a trademark of Verband Deutscher Elektrotechniker e.V.
- $\ensuremath{^{**}}$  ISO is a registered trademark of the International Organization of Standards
- # The PMBus name and logo are registered trademarks of the System Management Interface Forum (SMIF)



4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Absolute Maximum Ratings**

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the technical requirements. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage	All	V <sub>IN</sub>	-0.3	15	V
Continuous					
SEQ, ADDR0, ADDR1, RTUNE, VTRACK				2.0	V
VS+	All			3.0	V
ON/OFF				15	V
SYNC, CLK, DATA, SMBALERT#, PGOOD	All			5.5	V
Operating Ambient Temperature (see Thermal Considerations section)	All	TA	-40	85	°C
Storage Temperature	All	T <sub>stg</sub>	-55	125	°C

# **Electrical Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Тур	Max	Unit
Operating Input Voltage	All	V <sub>IN</sub>	4.5	_	14	Vdc
Maximum Input Current	All	I <sub>IN,max</sub>			46	Adc
$(V_{IN}=4.5V \text{ to } 14V, I_{O}=I_{O, max})$						
Input No Load Current	$V_{O,set} = 0.6 \text{ Vdc}$	I <sub>IN,No load</sub>		145		mA
$(V_{IN} = 12Vdc, I_0 = 0, module enabled)$	$V_{O,set} = 2.0Vdc$	I <sub>IN1No load</sub>		190		mA
Input Stand-by Current ( $V_{IN} = 12Vdc$ , module disabled)	All	I <sub>IN,stand-by</sub>		45		mA
Inrush Transient	All	l²t		1		A <sup>2</sup> s
Input Noise on nominal output (VIN=VIN, nom and IO=IO, min to IO, Cin = TBD) Peak-to-Peak (Full Bandwidth)	All				500	mVpp
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, $1\mu$ H source impedance; $V_{IN}$ =0 to $14V_{.}$ Io= Iomax; See Test Configurations)	All			40		mAp-p
Input Ripple Rejection (120Hz)	All			-55		dB

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Electrical Specifications** (continued)

Parameter	Device	Symbol	Min	Тур	Max	Unit
Output Voltage Set-point (with 0.1% tolerance for external	0 to 70°C	17	-0.5		+0.5	07.17
resistor used to set output voltage)	-40 to +85°C	V <sub>O, set</sub>	-1.0		+1.0	% V <sub>O, set</sub>
Output Voltage (Over all operating input voltage, resistive load, and temperature conditions until end of life)	All	V <sub>o, set</sub>	-2.5	_	+2.5	% V <sub>O, set</sub>
Adjustment Range (selected by an external resistor) (Some output voltages may not be possible depending on the input voltage – see Feature Descriptions Section)	All	V <sub>out</sub>	0.6		2.0	Vdc
PMBus Adjustable Output Voltage Range	All	V <sub>O,adj</sub>	0.5	_	2.0	$%V_{O,set}$
PMBus Output Voltage Adjustment Step Size	All		0.4			$%V_{O,set}$
Remote Sense Range	All				0.4	Vdc
Output Regulation						
Line ( $V_{IN}=V_{IN, min}$ to $V_{IN, max}$ )	All				4	mV
Load (Io=Io, min to Io, max)	All				5	mV
Temperature ( $T_{ref}=T_{A, min}$ to $T_{A, max}$ )	All			0.4		$%V_{O,set}$
Output Ripple and Noise on nominal output $(V_{IN}=V_{IN,nom}$ and $I_{O}=I_{O,min}$ to $I_{O,max}$ Co = TBD, Cin = TBD						
Peak-to-Peak (Full bandwidth)					30	$mV_{pk-pk}$
RMS (Full bandwidth)	All				12	$mV_{rms}$
External Capacitance						
Minimum output capacitance (ESR≥TBD mΩ)	All	C <sub>O,min</sub>	470		_	μF
Maximum output capacitance (ESR ≥ TBD mΩ)	All	C <sub>O, max</sub>	_		16000	μF
Output Current (in either sink or source mode)	All	lo	0		80	Adc
Output Current Limit Inception (Hiccup Mode) (current limit does not operate in sink mode)	All	Io, lim		91		Adc
Output Short-Circuit Current	All	I <sub>O, s/c</sub>		TBD		Arms
(V <sub>0</sub> ≤250mV) ( Hiccup Mode )						
Efficiency	V <sub>O,set</sub> = 0.6Vdc	η		82.4		%
V <sub>IN</sub> = 12Vdc, T <sub>A</sub> =25°C	$V_{O, set} = 0.8Vdc$	η		85.7		%
I <sub>O</sub> =I <sub>O, max</sub> , V <sub>O</sub> = V <sub>O,set</sub>	V <sub>O,set</sub> = 1.0Vdc	η		88.1		%
	$V_{O,set} = 1.2Vdc$	η		89.6		%
	$V_{0, set} = 1.5 Vdc$	η		91.2		%
	$V_{O,set} = 2.0Vdc$	η		92.8		%
Switching Frequency	All	f <sub>sw</sub>	-	400	-	kHz
Frequency Synchronization	All					
Synchronization Frequency Range	All		-10		+10	%
High-Level Input Voltage	All	V <sub>IH,SYNC</sub>	2.0			V
Low-Level Input Voltage	All	V <sub>IL,SYNC</sub>			0.4	V
Minimum Pulse Width, SYNC	All	tsync	50			ns

# **General Specifications**

Parameter	Device	Min	Тур	Max	Unit
Calculated MTBF (Io=0.8Io, max, TA=40°C) Telecordia Issue 2 Method 1 Case 3	All		TBD		Hours
Weight		_	TBD		g (oz.)

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Feature Specifications**

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbo	Min	Тур	Max	Unit
On/Off Signal Interface						
(V <sub>IN</sub> =V <sub>IN, min</sub> to V <sub>IN, max</sub> ; open collector or equivalent,						
Signal referenced to GND)						
Device Code- XXXXXX Negative Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current	All	lін	_	_	1	mA
Input High Voltage	All	VIH	2	_	V <sub>IN, max</sub>	Vdc
Logic Low (Module ON)						
Input low Current	All	lıL	_	_	10	μA
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Device Code- XXXXXX Positive Logic (See Ordering Information)						
(On/OFF pin is open collector/drain logic input with						
external pull-up resistor; signal referenced to GND)						
Logic High (Module OFF)						
Input High Current	All	lін	_	_	10	uA
Input High Voltage	All	ViH	2	_	V <sub>IN, max</sub>	Vdc
Logic Low (Module ON)						
Input low Current	All	lıL	_	_	10	μΑ
Input Low Voltage	All	VIL	-0.2	_	0.4	Vdc
Turn-On Delay and Rise Times						
$(V_{IN}=V_{IN,nom}, I_{O}=I_{O,max}, V_{O} \text{ to within } \pm 1\% \text{ of steady state})$						
Case 1: On/Off input is enabled and then input power is applied (delay from instant at which $V_{IN} = V_{IN,min}$ until $V_0 = 10\%$ of $V_0, set$ )	All	Tdelay	_	5.0	_	ms
Case 2: Input power is applied for at least one second and then the On/Off input is enabled (delay from instant at which Von/Off is enabled until Vo = 10% of Vo, set)	All	Tdelay	_	500	_	μs
Output voltage Rise time (time for Vo to rise from 10% of Vo, set to 90% of Vo, set)	All	Trise	_	2.0	_	msec
Output voltage overshoot ( $T_A = 25^{\circ}\text{C V}_{IN} = V_{IN,min}$ to $V_{IN,max,Io} = I_{O,min}$ to $I_{O,max}$ ) With or without maximum external capacitance		Output			3.0	% V <sub>O, set</sub>
Over Temperature Protection (See Thermal Considerations section)	Vin ≤ 6.5V	T <sub>ref</sub>		105		°C
over remperature motecular (see merinar considerations section)	Vin > 6.5V	1161		125		Ŭ
PMBus Over Temperature Warning Threshold*	Vin ≤ 6.5V	T <sub>WARN</sub>		95		°C
Tribus over remperature vvarning micshold	Vin > 6.5V	TWARN		115		Č
Tracking Accuracy ( $V_{IN,min}$ to $V_{IN,max}$ ; $I_{O,min}$ to $I_{O,max}$ VSEQ < $V_{O}$ )						
(Power-Up: 0.5V/ms)	All	VSEQ -Vo			100	mV
(Power-Down: 0.5V/ms)	All	VSEQ -Vo			100	mV
Input Undervoltage Lockout						
Turn-on Threshold	All				4.4	Vdc
Turn-off Threshold	All		4.1			Vdc
Hysteresis	1	1	l	0.25	1	Vdc
Trysteresis	All			0.25		vac
PMBus Adjustable Input Under Voltage Lockout Thresholds	All		4.5	0.25	14	Vdc

<sup>\*</sup> Over temperature Warning – Warning may not activate before alarm and unit may shut down before warning.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# Feature Specifications (cont.)

Parameter	Device	Symbol	Min	Тур	Max	Units
PGOOD (Power Good)						
Signal Interface Open Drain, V <sub>supply</sub> ≤ 5VDC						
Overvoltage threshold for PGOOD ON	All			108		$%V_{O, set}$
Overvoltage threshold for PGOOD OFF	All			110		$%V_{O,  set}$
Undervoltage threshold for PGOOD ON	All			92		%V <sub>O, set</sub>
Undervoltage threshold for PGOOD OFF	All			90		$%V_{O,  set}$
Pulldown resistance of PGOOD pin	All				TBD	Ω
Sink current capability into PGOOD pin	All				29	mA

<sup>\*</sup> Over temperature Warning – Warning may not activate before alarm and unit may shut down before warning.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Digital Interface Specifications**

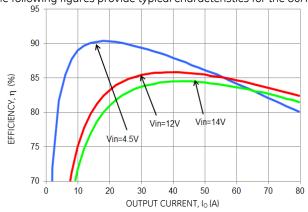
Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Conditions	Symbol	Min	Тур	Max	Unit
PMBus Signal Interface Characteristics						
Input High Voltage (CLK, DATA)		VIH	2.1			V
Input Low Voltage (CLK, DATA)		VIL			0.8	V
Input high level current (CLK, DATA)		Iн	-10		10	μΑ
Input low level current (CLK, DATA)		l <sub>IL</sub>	-10		10	μΑ
Output Low Voltage (CLK, DATA, SMBALERT#)	I <sub>OUT</sub> =2mA	Vol			0.4	V
Output high level open drain leakage current (DATA, SMBALERT#)	V <sub>OUT</sub> =3.6V	Іон	0		10	μΑ
Pin capacitance		Co			10	pF
PMBus Operating frequency range	Slave Mode	FРМВ	10		400	kHz
Data hold time		thd:dat	300			μs
Data setup time		tsu:dat	100			ns
Measurement System Characteristics	•					
Read delay time		toly	153	192	231	μs
Output current measurement range		I <sub>RNG</sub>	0		100	А
Output current measurement resolution		IRES	197			mA
Output current measurement gain accuracy	0°C to 85°C	lacc			±5	% of lo,max
	-40°C to +85°C	17100	-3		+7	А
Output current measurement offset		lofst			0.2	А
V <sub>OUT</sub> measurement range		Vout	0.5		2.0	V
V <sub>OUT</sub> measurement resolution		V <sub>OUT(res)</sub>		0.7		mV
V <sub>OUT</sub> measurement accuracy		V <sub>OUT</sub> (gain)		±1		%
V <sub>OUT</sub> measurement offset		V <sub>OUT(ofst)</sub>	-5		5	mV
V <sub>IN</sub> measurement range		V <sub>IN(rng)</sub>	0		14	V
V <sub>IN</sub> measurement resolution		V <sub>IN(res)</sub>		7.0		mV
$V_{\text{IN}}$ measurement offset		V <sub>IN(ofst)</sub>		TBD		%
V <sub>IN</sub> measurement accuracy		V <sub>IN</sub>		±1		%

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A Digital GigaDLynx™ at 0.6Vo and 25°C.



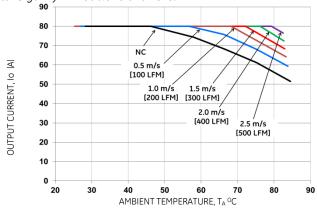
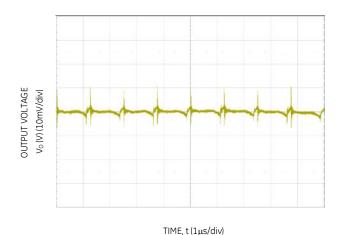


Figure 1. Converter Efficiency versus Output Current.

Figure 2. Derating Output Current versus Ambient Temperature and Airflow.



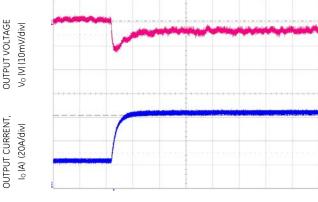
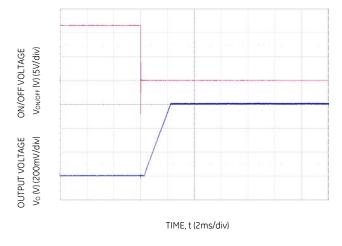


Figure 3. Typical output ripple and noise ( $C_0$ = 6x47 $\mu$ F ceramic,  $V_{IN}$  = 12V,  $I_0$  =  $I_{0,max}$ ,).

Figure 4. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 36x 47 $\mu$ F + 14x 1000 $\mu$ F, R<sub>TUNE</sub> = 4.22k $\Omega$ 

TIME, t (50µs /div)



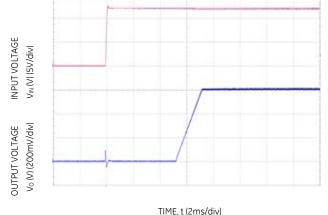


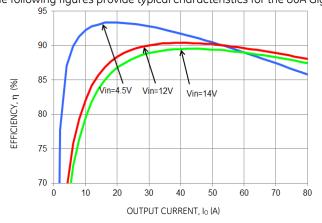
Figure 5. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 6. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{0,max}$ ).

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A GigaDLynx<sup>™</sup> at 1.0Vo and 25°C



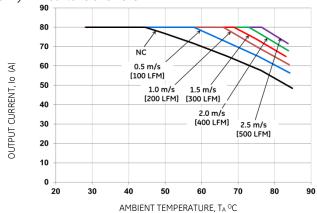
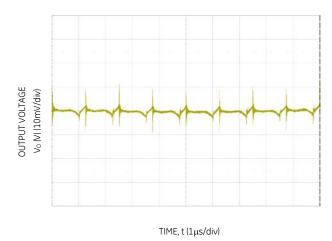


Figure 7. Converter Efficiency versus Output Current.

Figure 8. Derating Output Current versus Ambient Temperature and Airflow.



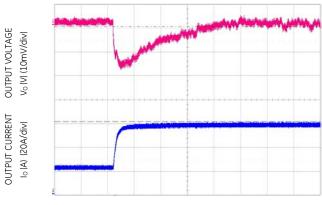
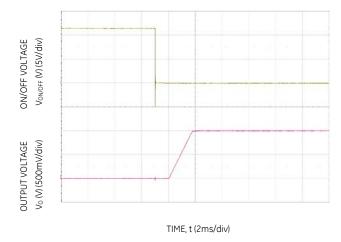


Figure 9. Typical output ripple and noise ( $C_0$ = 6x47 $\mu$ F Ceramic,  $V_{IN}$  = 12 $V_{I}$   $I_0$  =  $I_{O,max}$ , ).

Figure 10. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 30x 47 $\mu$ F + 11x 1000 $\mu$ F, R<sub>TUNE</sub> = 3.74k $\Omega$ 

TIME, t (50 $\mu$ s /div)



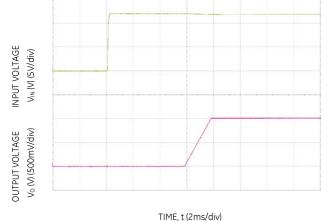


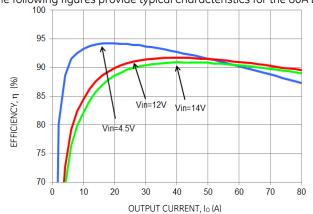
Figure 11. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 12. Typical Start-up Using Input Voltage (VIN = 12V, Io =  $I_{O,max}$ ).

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Characteristic Curves**

The following figures provide typical characteristics for the 80A Digital GigaDLynx™ at 1.2Vo and 25°C.



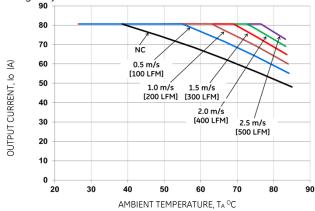
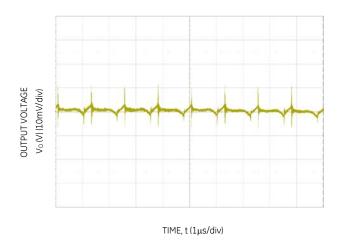


Figure 13. Converter Efficiency versus Output Current.

Figure 14. Derating Output Current versus Ambient Temperature and Airflow.



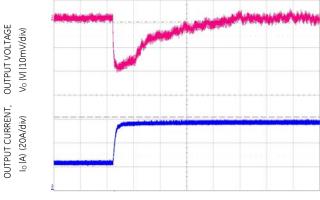
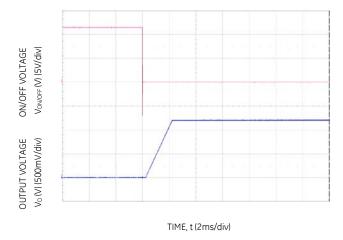


Figure 15. Typical output ripple and noise ( $C_0=6x47\mu F$  ceramic,  $V_{IN}=12V$ ,  $I_0=I_{0,max}$ ,).

Figure 16. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 26x 47 $\mu$ F + 9x 1000 $\mu$ F, R<sub>TUNE</sub> = 3.24k $\Omega$ 

TIME, t (50µs /div)



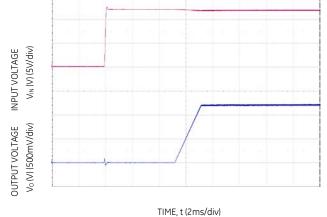


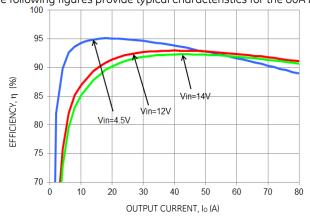
Figure 17. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 18. Typical Start-up Using Input Voltage ( $V_{IN} = 12V$ ,  $I_0 = I_{0,max}$ ).

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

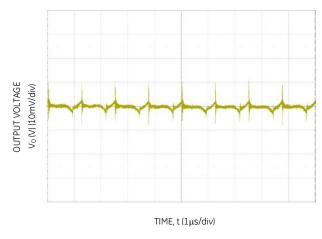
The following figures provide typical characteristics for the 80A Digital GigaDLynx<sup>™</sup> at 1.5Vo and 25°C.



80 70 ŃС 0.5 m/s [100 LFM] 60 OUTPUT CURRENT, Io 50 1.0 m/s 1.5 m/s [200 LFM] 40 2.0 m/s 30 [400 LFM] 2.5 m/s [500 LFM] 20 10 60 AMBIENT TEMPERATURE, TA °C

Figure 19. Converter Efficiency versus Output Current.

Figure 20. Derating Output Current versus Ambient Temperature and Airflow.



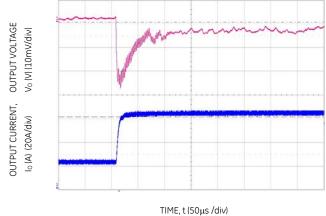
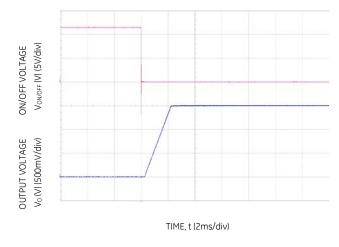


Figure 21. Typical output ripple and noise ( $C_0 = 6x47\mu F$  ceramic,  $V_{IN} = 12V$ ,  $I_0 = I_{0,max}$ ,).

Figure 22. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 25x 47 $\mu$ F + 8x 1000 $\mu$ F, R<sub>TUNE</sub> = 6.81k $\Omega$ 



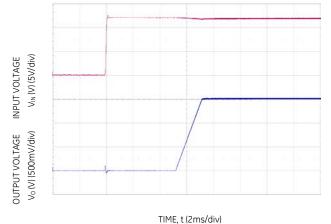


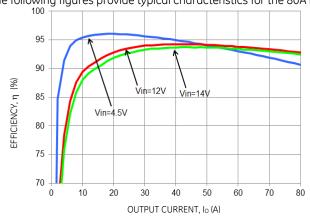
Figure 23. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 24. Typical Start-up Using Input Voltage ( $V_{IN}=12V,\,I_{o}=I_{o,max}$ ).

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

### **Characteristic Curves**

The following figures provide typical characteristics for the 80A Digital GigaDLynx™ at 2.0Vo and 25°C.



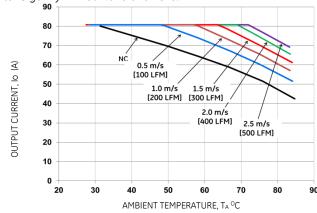
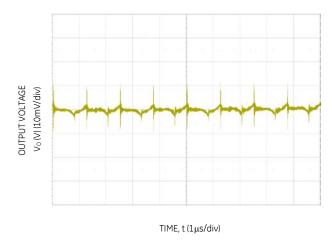


Figure 25. Converter Efficiency versus Output Current.

Figure 26. Derating Output Current versus Ambient Temperature and Airflow.



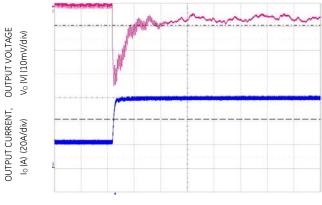
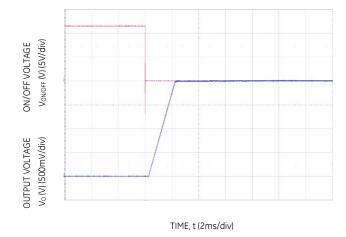


Figure 27. Typical output ripple and noise ( $C_0 = 6x47\mu F$  ceramic,  $V_{IN} = 12V$ ,  $I_0 = I_{0,max}$ ,).

Figure 28. Transient Response to Dynamic Load Change from 25% to 75% at 12Vin, Co= 20x 47µF + 7x 1000µF,  $R_{TUNE}$  =  $6.04 K\Omega$ 

TIME, t (50µs /div)



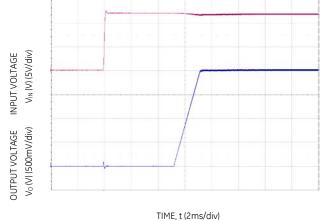


Figure 29. Typical Start-up Using On/Off Voltage ( $I_0 = I_{0,max}$ ).

Figure 30. Typical Start-up Using Input Voltage ( $V_{IN}=12V$ ,  $I_{o}=I_{o,max}$ ).

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Design Considerations**

## **Input Filtering**

The 80A GigaDLynx<sup>™</sup> module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pins of the module, to minimize input ripple voltage and ensure module stability.

To minimize input voltage ripple, ceramic capacitors are recommended at the input of the module. Figure 37 shows the input ripple voltage for various output voltages at 12A of load current with 2x22  $\mu\text{F}$  or 3x22  $\mu\text{F}$  ceramic capacitors and an input of 12V.

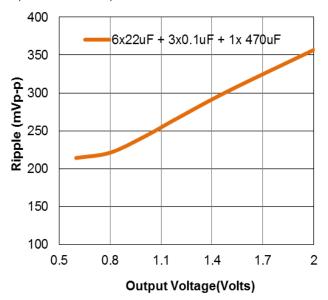


Figure 31. Input ripple voltage for various output voltages with ( $3 \times 0.1 \mu F + 6 \times 22 \mu F$ ) ceramic +  $1 \times 470 \mu F$  OSCON electrolytic capacitor at the input (80A load). Input voltage is 12V.

# **Output Filtering**

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with minimum of 6x47µF ceramic capacitors at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR polymer and ceramic capacitors are recommended to improve the dynamic response of the module.

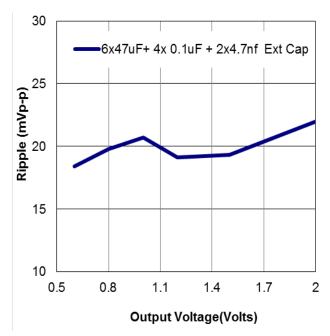


Figure 32. Output ripple voltage for various output voltages with external  $6\times47\mu\text{F}+4\times0.1~\mu\text{F}+2\times4.7\text{nF}$  ceramic capacitors at the output (80A load). Input voltage is 12V.

# **Safety Considerations**

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e., UL 60950-1 2nd, CSA C22.2 No. 60950-1-07, DIN EN 60950-1:2006 + A11 (VDE0805 Teil 1 + A11):2009-11; EN 60950-1:2006 + A11:2009-03.

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV), the input must meet SELV requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV. These units are to be protected with a TBD fuse in the positive input path.

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Analog Feature Descriptions**

#### Remote On/Off

The GigaDLynx 80A module can be turned ON and OFF either by using the ON/OFF pin (Analog interface) or through the PMBus interface (Digital). The module can be configured in a number of ways through the PMBus interface to react to the ON/OFF input:

- Module ON/OFF is controlled only through the analog interface (digital interface ON/OFF commands are ignored)
- Module ON/OFF is controlled only through the PMBus interface (analog interface is ignored)
- Module ON/OFF is controlled by either the analog or digital interface

The default state of the module (as shipped from the factory) is to be controlled by the analog interface only. If the digital interface is to be enabled, or the module is to be controlled only through the digital interface, this change must be made through the PMBus. These changes can be made and written to non-volatile memory on the module so that it is remembered for subsequent use.

## Analog On/Off

The 80A GigaDLynx<sup>TM</sup> power modules feature an On/Off pin for remote On/Off operation. With the Negative Logic On/Off option, (see Ordering Information), the module turns OFF during logic High and ON during logic Low. The On/Off signal should be always referenced to ground. Leaving the On/Off pin disconnected will turn the module ON when input voltage is present. With the positive logic on/off option, the module turns ON during logic high and OFF during logic low.

#### Digital On/Off

Please see the Digital Feature Descriptions section.

# **Monotonic Start-up and Shutdown**

The module has monotonic start-up and shutdown behavior on the output voltage for any rated input voltage, output voltage and current, and operating temperature.

#### Startup considerations at low temperature.

GDT080 is able to handle specified full-load start-up for ambient temperatures above or equal to -20°C. Below -20°C ambient temperature, the load has to be limited to 75% of specified full-load.

#### **Startup into Pre-biased Output**

The module can start into a pre-biased output as long as the pre-bias voltage is 0.5V less than the set output voltage.

#### **Analog Output Voltage Programming**

The output voltage of the module is programmable to any voltage from 0.6 to 2.0 Vdc by connecting a resistor between the Trim and VS- pins of the module as shown in Fig 33.

Without an external resistor between the Trim and VS- pins, the output of the module will be 0.6 Vdc. The value of the

trim resistor,  $R_{TRIM}$  for a desired output voltage, should be selected as per the following equation:

$$R_{TRIM} = \frac{Vref}{(Vout - Vref)} \times 2k\Omega$$

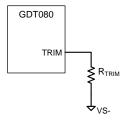


Figure 33. Circuit configuration for programming output voltage using an external resistor.

 $R_{TRIM}$  is the external resistor in  $k\Omega$ 

Vout is the desired output voltage.

Vref is the programmable internal reference

Table 1 provides Rtrim values required for some common output voltages.

Table 1

Vo, set (V)	R <sub>TRIM</sub> (KΩ)
0.6	Open
0.8	6.0
1.0	3.0
1.2	2.0
1.5	1.33
2.0	0.866

#### **Digital Output Voltage Adjustment**

Please see the Digital Feature Descriptions section.

## **Remote Sense**

The power module has a differential Remote Sense feature to minimize the effects of distribution losses by regulating the voltage between the sense pins (VS+ and VS-). The voltage drop between the sense pins and the VOUT and GND pins of the module should not exceed 0.4V.

#### **Output Voltage Sequencing**

The power module includes a sequencing feature, EZ-SEQUENCE that enables users to implement various types of output voltage sequencing in their applications. This is accomplished via an additional sequencing pin. When not using the sequencing feature, leave it unconnected.

The voltage applied to the SEQ pin should be scaled down by the same ratio as used to scale the output voltage down to the reference voltage of the module. This is accomplished by an external resistive divider connected across the sequencing voltage before it is fed to the SEQ pin as shown in Fig 34. In addition, a small capacitor (suggested value 100pF) should be connected across the lower resistor R1.

For all DLynx modules, the minimum recommended delay between the ON/OFF signal and the sequencing signal is

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10ms to ensure that the module output is ramped up according to the sequencing signal. This ensures that the module soft-start routine is completed before the sequencing signal is allowed to ramp up.

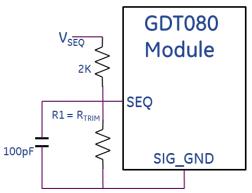


Figure 34. Circuit showing connection of the sequencing signal to the SEQ pin.

When the scaled down sequencing voltage is applied to the SEQ pin, the output voltage tracks this voltage until the output reaches the set-point voltage. The final value of the sequencing voltage must be set higher than the set-point voltage of the module. The output voltage follows the sequencing voltage on a one-to-one basis. By connecting multiple modules together, multiple modules can track their output voltages to the voltage applied on the SEQ pin.

The module's output can track the SEQ pin signal with slopes of up to 0.5V/msec during power-up or power-down. To initiate simultaneous shutdown of the modules, the SEQ pin voltage is lowered in a controlled manner. The output voltage of the modules tracks the voltages below their setpoint voltages on a one-to-one basis. A valid input voltage must be maintained until the tracking and output voltages reach ground potential.

Note that in all digital DLynx series of modules, the PMBus Output Undervoltage Fault will be tripped when sequencing is employed. This will be detected using the STATUS\_WORD and STATUS\_VOUT PMBus commands. In addition, the SMBALERT# signal will be asserted low as occurs for all faults and warnings. To avoid the module shutting down due to the Output Undervoltage Fault, the module must be set to continue operation without interruption as the response to this fault (see the description of the PMBus command VOUT\_UV\_FAULT\_RESPONSE for additional information).

# **Digital Compensator**

The GDT080 module uses digital control to regulate the output voltage. As with all POL modules, external capacitors are usually added to the output of the module for two reasons: to reduce output ripple and noise (see Figure 32) and to reduce output voltage deviations from the steady-state value in the presence of dynamic load current changes. Adding external capacitance however affects the voltage control loop of the module, typically causing the loop to slow down with sluggish response. Larger values of external capacitance could also cause the module to become unstable. In the GDT080, the digital compensation can be adjusted externally to optimize transient response

and also ensure stability for a wide range of external capacitance, as well as with different types of output capacitance. This is done by allowing the user to select among several pre-tuned compensation choices to select the one most suited to the transient response needs of the load. Figure 35 shows how the resistor RTune is connected between the RTUNE and GND pins to select the appropriate pre-tuned compensation.

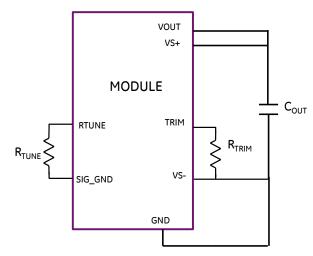


Figure 35. Circuit diagram showing connection of  $R_{\text{\tiny TUNE}}$  to tune the control loop of the module.

Recommended values of  $R_{TUNE}$  for different output capacitor combinations are given in Table 1. The GDT080 pre-tuned compensation can be divided into four different banks (COMP0, COMP1, COMP2 and COMP3) that are available to the user to compensate the control loop for various values and combinations of output capacitance and to obtain reliable and stable performance under different conditions. Each bank consists of seven different sets of compensation coefficients pre-calculated for different values of output capacitance. The four banks are set up as follows:

- COMPO: Recommended for the case where all of the output capacitance is composed of only ceramic capacitors. The range of output capacitance is from the required minimum value of 470µF to a maximum of 7500µF.
- COMP1: For the most commonly used mix of ceramic and polymer type capacitors that have higher output capacitance in a smaller size and for output voltages between 0.6V to 1.2V. The range of output capacitance is from 470µF to a maximum of 15,692µF. This is the combination of output capacitance and compensation that can achieve the best transient response at lowest cost and smallest size. For example, with the maximum output capacitance of 15,692µF, and selecting RTUNE = 4.22kΩ, transient deviation can be as low as 15mV, for a 50% load step (0 to 40A).
- COMP2: Same range and types of capacitance as COMP1, but for an output voltage range from 1.2V to 2V.

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• COMP3: Suitable also for a mix of ceramic and higher ESR polymers or electrolytic capacitors such as OSCON. Selecting R<sub>TUNE</sub> according to Table 2 will ensure stable operation of the module with sufficient stability margin as well as yield optimal transient response.

In applications with tight output voltage limits in the presence of dynamic current loading, additional output capacitance will be required. Table 4 lists recommended values of  $R_{\text{TUNE}}$  in order to meet 2% output voltage deviation limits for some common output voltages in the presence of a 40A to 80A step change (50% of full load), with an input voltage of 12V.

Please contact your GE technical representative to obtain more details of this feature as well as for guidelines on how to select the right value of external RTUNE to tune the module for best transient performance and stable operation for other output capacitance values. Simulation models are also available via the GE Power Module Wizard to predict stability characteristics and transient response.

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Table 2. R<sub>TUNE</sub> compensation table

Output Capacitance Type	Number of Output Capacitors**	Total Output Capacitance (µF)**	Compensation Bank	$R_{TUNE}$ resistor ( $k\Omega$ )
Ceramic	18 x 47µ	756	Comp 0	0
Ceramic	18 × 47μ + 14 × 100μ	1485	Comp 0	0.392
Ceramic	18 × 47μ + 16 × 100μ	2052	Comp 0	0.576
Ceramic	18 × 47μ + 22 × 100μ	2538	Comp 0	0.787
Ceramic	18 × 47μ + 40 × 100μ	3996	Comp 0	1
Ceramic	18 × 47μ + 52 × 100μ	4968	Comp 0	1.24
Ceramic	18 × 47μ + 83 × 100μ	7479	Comp 0	1.5
Ceramic + Polymer	16 × 47µ + 2 × 1000µ	2672	Comp 1	1.78
Ceramic + Polymer	16 × 47µ + 3 × 1000µ	3672	Comp 1	2.1
Ceramic + Polymer	16 × 47μ + 5 × 1000μ	5672	Comp 1	2.43
Ceramic + Polymer	16 × 47μ + 7 × 1000μ	7672	Comp 1	2.8
Ceramic + Polymer	16 × 47µ + 9 × 1000µ	9672	Comp 1	3.24
Ceramic + Polymer	18 × 47μ + 12 × 1000μ	12,756	Comp 1	3.74
Ceramic + Polymer	18 × 47μ + 14 × 1000μ	14,756	Comp 1	4.22
Ceramic + Polymer	16 × 47µ + 2 × 1000µ	2672	Comp 2	4.75
Ceramic + Polymer	16 × 47µ + 3 × 1000µ	3672	Comp 2	5.36
Ceramic + Polymer	16 × 47μ + 5 × 1000μ	5672	Comp 2	6.04
Ceramic + Polymer	16 × 47μ + 7 × 1000μ	7672	Comp 2	6.81
Ceramic + Polymer	16 × 47µ + 9 × 1000µ	9672	Comp 2	7.68
Ceramic + Polymer	18 × 47μ + 12 × 1000μ	12,756	Comp 2	8.66
Ceramic + Polymer	18 × 47μ + 14 × 1000μ	14,756	Comp 2	9.53
Ceramic + Electrolytic	16 x 47µ + 4 x 470µ	2552	Comp 3	10.5
Ceramic + Electrolytic	16 × 47µ + 7 × 470µ	3962	Comp 3	11.8
Ceramic + Electrolytic	16 x 47μ + 9 x 470μ	4902	Comp 3	13
Ceramic + Electrolytic	18 × 47μ + 14 × 470μ	7336	Comp 3	14.3
Ceramic + Electrolytic	18 x 47μ + 20 x 470μ	10,156	Comp 3	15.8
Ceramic + Electrolytic	18 × 47μ + 24 × 470μ	12,036	Comp 3	17.4
Ceramic + Electrolytic	18 × 47μ + 30 × 470μ	14,856	Comp 3	19.1

<sup>\*\*</sup> Total output capacitance includes the capacitance inside the module of value  $8 \times 47 \mu F$  (3m $\Omega$  ESR).

Note: The capacitors used in the digital compensation Loop tables are  $47\mu\text{F}/3~\text{m}\Omega$  ESR ceramic,  $100\text{uF}/3.2\text{m}\Omega$  ceramic,  $1000~\mu\text{F}/6\text{m}\Omega$  ESR polymer capacitor and  $470\text{uF}/9\text{m}\Omega$  ESR Polymer capacitor.

Table 3. General recommended values of  $R_{\text{TUNE}}$  for Vin=12V and various external ceramic capacitor combination

Со	14x 47μF	19x 100μF	25x 100µF	35x 100μF	50x 100μF
$R_{TUNE}$ ( $k\Omega$ )	0.0	0.576	0.787	1.0	1.24

Table 4. Recommended values of  $R_{\text{TUNE}}$  to obtain transient deviation of 2% of Vout for a 40A step load with Vin=12V.

Vo	2V	1.2V	0.6V
	14x47uF +	28x47uF +	36x47uF +
Co	<b>C</b> <sub>2</sub> 5×1000μF		14x1000µF
	polymer	polymer	polymer
$R_{TUNE}$ ( $k\Omega$ )	9.53	3.24	4.22
∆V (mV)	32	19.8	12

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

## **Digital Output Voltage Margining**

Please see the Digital Feature Descriptions section.

#### **Overcurrent Protection (OCP)**

To provide protection in a fault (output overload) condition, the unit has internal current-limiting circuitry on the output and can endure current limiting continuously. The module overcurrent response is non-latching shutdown with automatic recovery. The Overcurrent Protection response time is programmable via the PMBus through manufacturer-specific commands. The unit operates normally once the output current is brought back into its specified range.

#### **Load Transient Considerations**

The GDT080 module can achieve 100% load transient above -20°C ambient temperature. Below -20°C ambient temperature, the load transient is limited to a maximum of 75% of specified full load current.

### **Digital Sequencing**

The module supports digital sequencing operation. Both ratiometric and simultaneous sequencing are supported.

#### **Overtemperature Protection**

To provide protection in a fault condition, the unit has a thermal shutdown circuit. The unit will shut down if the overtemperature threshold of TBD (typ) is exceeded at the thermal reference point  $T_{\text{ref}}$ . Once the unit goes into thermal shutdown it will wait to cool before attempting to restart.

## Digital Temperature Status via PMBus

Please see the Digital Feature Descriptions section.

# Digitally Adjustable Output Over and Under Voltage Protection

Please see the Digital Feature Descriptions section.

#### Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation is disabled. The module will begin to operate at an input voltage above the undervoltage lockout turn-on threshold.

### Digitally Adjustable Input Undervoltage Lockout

Please see the Digital Feature Descriptions section.

## **Digitally Adjustable Power Good Thresholds**

Please see the Digital Feature Descriptions section.

#### **Power Good**

The module provides a Power Good (PGOOD) signal that goes high to indicate output voltage being within a specified range. The signal is implemented as an open-drain output.. The PGOOD signal is de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going outside the specified thresholds. The default PGOOD thresholds are  $\pm$  12.5%.

The PGOOD terminal should be connected through a pullup resistor (suggested value  $100 \mathrm{K}\Omega$ ) to a source of 5VDC or lower.

#### **Synchronization**

The module switching frequency can be synchronized to an external signal within the specified range. Synchronization is done by applying the external signal to the SYNC pin of the module as shown in Fig. 36, with the converter being synchronized by the rising edge of the external signal. The Electrical Specifications table specifies the requirements of the external SYNC signal. If the SYNC pin is not used, the module runs at the default switching frequency.

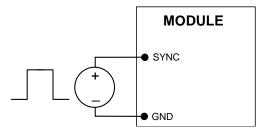


Figure 36. External source connections to synchronize switching frequency of the module.

# Measuring Output Current, Output Voltage and Input Voltage

Please see the Digital Feature Descriptions section.

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# **Digital Feature Descriptions**

## **PMBus Interface Capability**

The 80A Digital GigaDLynx<sup>™</sup> power modules have a PMBus interface that supports both communication and control. The modules supports a subset of version 1.1 of the PMBus specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

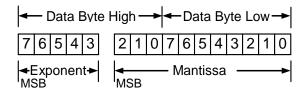
All communication over the module PMBus interface will work with or without Packet Error Checking (PEC) . The module generates the correct PEC byte for all transactions, and checks the PEC byte if sent by the master.

The module also supports the SMBALERT# response protocol whereby the module alerts the bus master if it wants to talk. For more information on the SMBus alert response protocol, see the System Management Bus (SMBus) specification.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored are saved (see Table 6 for which command parameters can be saved in non-volatile storage).

#### **PMBus Data Format**

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by  $Value = Mantissa \times 2^{Exponent}$ 

# **PMBus Addressing**

The power module is addressed through the PMBus using a device address. The module supports 128 possible addresses (0 to 127 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to SIG\_GND. Note that some of these addresses (0, 1, 2, 3, 4, 5, 6, 7, 8, 9, 10, 11 12, 40, 44, 45, 55 in decimal) are reserved according to the SMBus specification and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 5 (E96 series resistors are recommended). Note that if either

address resistor value is outside the range specified in Table 5, the module will respond to address 127.

Table 5

	PMBus Address Table									
		ADDR1 Resistor Values								
ADDR0 Resistor Values	0	680	1.2K	1.8K	2.7K	3.9K	4.7K	5.6K		
0	64	16	32	48	64	80	96	112		
680	1	17	33	49	65	81	97	113		
1.2K	2	18	34	50	66	82	98	114		
1.8K	3	19	35	51	67	83	99	115		
2.7K	4	20	36	52	68	84	100	116		
3.9K	5	21	37	53	69	85	101	117		
4.7K	6	22	38	54	70	86	102	118		
5.6K	7	23	39	55	71	87	103	119		
6.8K	8	24	40	56	72	88	104	120		
8.2K	9	25	41	57	73	89	105	121		
10K	10	26	42	58	74	90	106	122		
12K	11	27	43	59	75	91	107	123		
15K	12	28	44	60	76	92	108	124		
18K	13	29	45	61	77	93	109	125		
22K	14	30	46	62	78	94	110	126		
27K	15	31	47	63	79	95	111	127		

Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2.

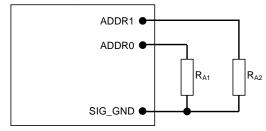


Figure 37. Circuit showing connection of resistors used to set the PMBus address of the module.

#### **PMBus Enabled On/Off**

The output of the module can be turned on and off via the PMBus interface. The OPERATION command is used to actually turn the module on and off via the PMBus, while the ON\_OFF\_CONFIG command configures the combination of analog ON/OFF pin input and PMBus commands needed to turn the module on and off. Bit [7] in the OPERATION command data byte enables the module, with the following functions:

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0 : Output is disabled1 : Output is enabled

This module shall use the lower five bits of the ON\_OFF\_CONFIG data byte to set various ON/OFF options as follows:

Bit Position	4	3	2	1	0
Access	r/w	r/w	r/w	r/w	r
Function	PU	CMD	CPR	POL	CPA
Default Value	1	0	1	1	0

PU: Sets the default to either operate any time input power is present or for the ON/OFF to be controlled by the analog ON/OFF input and the PMBus OPERATION command. This bit shall be used together with the CP, CMD and ON bits to determine startup.

Bit Value	Action
0	Module powers up any time power is present regardless of state of the analog ON/OFF pin
1	Module does not power up until commanded by the analog ON/OFF pin and the OPERATION command as programmed in bits [2:0] of the ON_OFF_CONFIG register.

CMD: The CMD bit controls how the device responds to the  $\ensuremath{\mathsf{OPERATION}}$  command.

Bit Value	Action
0	Module ignores the ON bit in the
U	OPERATION command
1	Module responds to the ON bit in the
	OPERATION command

CPR: Sets the response of the analog ON/OFF pin. This bit issued together with the CMD, PU and ON bits to determine startup.

Bit Value	Action
	Module ignores the analog ON/OFF pin, i.e.
0	ON/OFF is only controlled through the
	PMBUS via the OPERATION command
1	Module requires the analog ON/OFF pin to
	be asserted to start the unit

#### **PMBus Adjustable Soft Start Rise Time**

The soft start rise time of module output is adjustable in the module via PMBus. The TON\_RISE command can set the rise time in ms, and allows choosing soft start times between 200µs and 14ms.

#### **Output Voltage Adjustment Using the PMBus**

The VOUT\_SCALE\_MONITOR parameter is important for a number of PMBus commands related to output voltage trimming, margining, over/under voltage protection and the PGOOD thresholds. The output voltage of the module is determined by the value of the  $R_{\text{Trim}}$  resistor connected between TRIM pin and analog ground VS-, as specified earlier in the data sheet. The information on the output

voltage divider ratio is conveyed to the module through the VOUT\_SCALE\_MONITOR parameter. The read-out of output voltage also depends on VOUT\_SCALE\_PARAMETER. If correct VOUT\_SCALE\_PARAMETER is not used, the output voltage read-out will be wrong. The VOUT\_SCALE\_MONITOR parameter is defined by the ratio of internal reference of the controller to the nominal output voltage selected by R<sub>Trim</sub> resistor.

$$VOUT\_SCALE\_MONITOR = \frac{0.6V}{Nominal Output Voltage}$$

For example, for a nominal output voltage of 1.2V, the VOUT\_SCALE\_PARAMETER is equal to 0.5. Table 6 below defines values of VOUT\_SCALE\_MONITOR to the various nominal output voltages.

Table 6

Vo, set (V)	VOUT_SCALE_MONITOR
0.6	1
0.8	0.75
1.0	0.6
1.2	0.5
1.5	0.4
2.0	0.3

When PMBus commands are used to trim or margin the output voltage, the value of  $V_{\text{REF}}$  is what is changed inside the module, which in turn changes the regulated output voltage of the module.

The nominal output voltage of the module is adjustable with a minimum step size of TBD over a  $\pm$  25% range from nominal using the VOUT\_TRIM command over the PMBus.

## **Output Voltage Margining Using the PMBus**

Output voltage of the module can also be margined via PMBus commands. The command

MFR\_VOUT\_MARGIN\_HIGH sets the margin high voltage, while the command MFR\_VOUT\_MARGIN\_LOW sets the margin low voltage. Both the MFR\_VOUT\_MARGIN\_HIGH and MFR\_VOUT\_MARGIN\_LOW commands use the "Linear" mode. Two bytes are used for data. The actual margined output voltage is determined by the resistor on the TRIM, which as explained earlier is taken into consideration by VOUT\_SCALE\_MONITOR command. The module then sets the output voltage to the margined high or low voltage levels using the OPERATION command. Bits [7:4] shall be used to enable margining as follows:

1001: Vout set to MFR\_VOUT\_MARGIN\_LOW (Ignore Fault) 1010: Vout set to MFR\_VOUT\_MARGIN\_HIGH (Ignore Fault)

## **Temperature Status via PMBus**

The module provides information related to temperature of the module through standardized PMBus commands. Commands READ\_TEMPERATURE1, READ\_TEMPERATURE\_2 are mapped to module temperature (at TBD location) and internal temperature of the PWM controller, respectively.

# 80A GigaDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

The temperature readings are returned in  ${}^{\circ}\text{C}$  and is two bytes.

# PMBus Adjustable Output Over and Under Voltage Protection

The module has output over and under voltage protection capability. The PMBus command VOUT\_OV\_FAULT\_LIMIT is used to set the output over voltage threshold. The default value is configured to be 115% of the commanded output. The command VOUT\_UV\_FAULT\_LIMIT sets the threshold that detects an output under voltage fault. The default values are 85% of the commanded output voltage. Both commands use two data bytes formatted in the Linear format.

## PMBus Adjustable Input Undervoltage Lockout

The module allows adjustment of the input under voltage lockout and hysteresis. The command VIN\_ON allows setting the input voltage turn on threshold, while the VIN\_OFF command sets the input voltage turn off threshold. For both the VIN\_ON and VIN\_OFF commands, possible values are 4.5V to 14V . Both VIN\_ON and VIN\_OFF commands use the "Linear" format with two data bytes.

# Measurement of Output Current, Output Voltage, Input Voltage and output power

The module can measure key module parameters such as output current, output voltage and input voltage and provide this information through the PMBus interface.

# **Measuring Output Current Using the PMBus**

The module measures output current by using the inductor winding resistance as a current sense element. The inductor winding resistance is then multiplied by the current gain factor that will be used to scale the measured voltage into a current reading. This gain factor shall be the argument of the IOUT\_CAL\_GAIN command, and consists of two bytes in the Linear data format. During manufacture, each module is calibrated by measuring and storing the current gain factor into non-volatile storage.

The current measurement accuracy is also improved by each module being calibrated during manufacture with the offset in the current reading. The IOUT\_CAL\_OFFSET command is used to store and read the current offset. The READ\_IOUT command provides tmodule average output current information. This command only supports positive output current, i.e. current sourced from the module. If the converter is sinking current a reading of 0 is provided. The READ\_IOUT command returns two bytes of data in the Linear data format.

### Measuring Output Voltage Using the PMBus

The module provides output voltage information using the READ\_VOUT command. The command returns two bytes of data in Linear format

#### Measuring Input Voltage Using the PMBus

The module provides input voltage information using the READ\_VIN command. The command returns two bytes of data in the Linear format.

### Reading the Status of the Module using the PMBus

The module supports a number of status information commands implemented in PMBus. A 1 in the bit position shall indicate the fault that is flagged.

STATUS\_BYTE: Returns one byte of information with a summary of the most critical device faults

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0
0	None of the above	0

STATUS\_WORD: Returns two bytes of information with a summary of the module's fault/warning conditions.

Bit Position	Flag	Default Value
7	X	0
6	OFF	0
5	VOUT Overvoltage	0
4	IOUT Overcurrent	0
3	VIN Undervoltage	0
2	Temperature	0
1	CML (Comm. Memory Fault)	0

High Byte

None of the above

Bit Position	Flag	Default Value
7	VOUT fault or warning	0
6	IOUT fault	0
5	VIN Fault	0
4	X	0
3	PowerGOOD	0
2	Fan Fault	0
1	Shortciruit	0
0	X	0

STATUS\_VOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VOUT OV Fault	0
6	X	0
5	X	0
4	VOUT UV Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

STATUS\_IOUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	IOUT OC Fault	0
6	X	0
5	X	0
4	X	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS\_INPUT: Returns one byte of information relating to the status of the module's output voltage related faults.

Bit Position	Flag	Default Value
7	VIN_OV_FAULT	0
6	X	0
5	X	0
4	VIN_UV_FAULT	0
3	X	0
2	X	0
1	X	0
0	X	0

STATUS\_TEMPERATURE: Returns one byte of information relating to the status of the module's temperature related faults.

Bit Position	Flag	Default Value
7	OT Fault	0
6	OT Warning	0
5	X	0
4	X	0
3	Χ	0
2	X	0
1	X	0
0	X	0

STATUS\_CML: Returns one byte of information relating to the status of the module's communication related faults.

Bit Position	Flag	Default Value
7	Invalid/Unsupported Command	0
6	Invalid/Unsupported data	0
5	Packet Error Check Failed	0
4	Memory Fault	0
3	X	0
2	X	0
1	X	0
0	X	0

MFR\_VIN\_MIN: Returns minimum input voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -2, and lower 11 bits are mantissa in two's complement format – fixed at 12)

MFR\_VOUT\_MIN: Returns minimum output voltage as two data bytes of information in Linear format (upper five bits are exponent – fixed at -10, and lower 11 bits are mantissa in two's complement format – fixed at 614)

MFR\_SPECIFIC\_00: Returns information related to the type of module and revision number. Bits [7:2] in the Low Byte indicate the module type (xxxxxx corresponds to the PLX002 series of module), while bits [7:3] indicate the revision number of the module.

#### Low Byte

Bit Position	Flag	Default Value
7:2	Module Name	XXXXXX
1:0	Reserved	10

#### **High Byte**

Bit Position	Flag	Default Value
7:3	Module Revision Number	None
2:0	Reserved	000

#### Writing to OTP (One Time Programmable) Memory

The GDT080 EEPROM memory can be completely written in entirety, for example, using STORE\_DEFAULT\_ALL command, only four times. During the situation of partial rewrites, for example, when trying to store only four commands using STORE\_DEFAULT\_CODE command four times in succession, numerous writes are possible within the confines of available memory.

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Summary of Supported PMBus Commands**

Please refer to the PMBus 1.2 specification for more details of these commands.

### Table 7

Hex Code	Command				Brief	Descrip	otion					Non-Volatile Memory Storage
		Turn Module on or o	off. Also	used to	margii	n the ou	tput vo	ltage				
		Format			l	Jnsigne	d Binar	У				
01	OPERATION	Bit Position	7	6	5	4	3	2	1	0		
01	OPERATION	Access	r/w	r	r/w	r/w	r/w	r/w	r	r		
		Function	On	Х		Ма	rgin		Х	Χ		
		Default Value	0	0	0	0	0	0	Х	Χ		
		Configures the ON/commands	OFF fur	nctionali	•		ation of		ON/OF	F pin an	d PMBus	
02	ON_OFF_CONFIG	Bit Position	7	6	5	4	3	2	1	0		YES
02	011_011_001110	Access	r	r	r	r/w	r/w	r/w	r/w	r		TLS
		Function	X	X	X	pu	cmd	cpr	pol	сра		
		Default Value	0	0	0	1	0	1	1	1		
						l		l	l.			
03	CLEAR_FAULTS	Clear any fault bits device has been as	serting	it.								
		module whose com	sed to control writing to the module via PMBus. Copies the current register setting in the odule whose command code matches the value in the data byte into non-volatile emory (EEPROM) on the module  Format  Unsigned Binary									
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	X	X	X	X	X		
		Function	bit7	bit6	bit5	X	X	X	X	X		
		Default Value	0	0	0	X	X	X	X	X		
10	WRITE PROTECT	Bit5: 0 – Enables all	·	·	-			^	- / /	- //		YES
	_	1 – Disables all and ON_OF	writes	except t	he WRI	TE_PRO						
		Bit 6: 0 - Enables al	l writes	as pern	nitted in	bit5 or	bit7					
		1 – Disables al OPERATION										
		Bit7: 0 – Enables all										
		1 – Disables all						Г comm	and			
		(bit5 and bit										
11	STORE_DEFAULT_ALL	Copies all current re the module. Takes of							e memo	ory (EEPI	ROM) on	
12	RESTORE_DEFAULT_ALL	Restores all current	registe	r setting	gs in the	modul	e from v	values i	n the m	odule no	on-volatile	
<u> </u>		memory (EEPROM)										
		Copies the current i									es the	
17	CTORE REFAULT COST	value in the data by							1		1	
13	STORE_DEFAULT_CODE	Bit Position	7	6	5	4	3	2	1	0		
		Access Function	W	W	w	Ommo	nd code	W	W	W		
			<u> </u>								<u> </u>	
		Restores the current register setting in the module whose command code matches the value in the data byte from the value in the module non-volatile memory (EEPROM)										
14	RESTORE DEFAULT CODE	Bit Position	7 7	6	ue in tri	4	3	2	memor 1	y (EEPRO	וויוכ 	
14	RESTORE_DEFAULT_CODE	Access	w	w	W	W	W	W	W	w		
		Function	VV	_ vv			nd code		_ vv	vv		
		The module has MC changed	DDE set	to Lineo					ese valu	ies canr	ot be	
		Bit Position	7	6	5	4	3	2	1	0		
20	VOUT_MODE	Access	r	r	r	r	r	r	r	r		
		Function	'	Mode		<u> </u>		xponer	1	1 1		
		Default Value	0	0	0	1	0	0	1	1		
		Delault value	J	J	U		J	U				

<sup>\*</sup>NOTE: The EEPROM memory can be completely written in entirety (for example, using STORE\_DEFAULT\_ALL command) only four times. During the situation of partial rewrites, numerous writes are available within the confines of the available memory (for example, using STORE\_DEFAULT\_CODE command).

Hex Code	Command				Brie	ef Desc	ription					Non-Volatile Memory Storage
		Apply a fixed offset	voltaae	to the	output	voltaae	commo	ınd valu	ie. Expo	nent is f	fixed at -13.	
		Format					mpleme					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	17 00	17 00	17 00		Byte	17 00	17 00	17 00		
22	VOUT_TRIM	Default Value	0	0	0	0	0	0	0	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
			r/w	r/w	r/w	r/w		r/w		r/w		
		Access Function	1/W	I/W	I/W		r/w	I/W	r/w	I/W		
		Default Value	_	_			Byte					
		Delault value	0	0	0	0	0	0	0	0		
		Sets the target volt	ago for	maraini	ing tha	outout	high Ev	nonont	ic fixed	at 17		
		Format	uge ioi				mpleme			ut -13.	1	
			7									
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
25	VOUT MARGIN HIGH	Function					Byte					YES
		Default Value	0	0	0	0	0	1	0	1		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Low	Byte					
		Default Value	0	0	0	1	1	1	1	1		
		C = 4 = 4  = 4 = 4 = 4 + 1 = 14					C	:	. £:	. 17		
		Sets the target volt	age for							t -13	1	
		Format	_				mpleme					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
26	VOUT MARGIN LOW	Function			•		Byte	•	•	•		YES
	V 0 0 1 _ 1	Default Value	0	0	0	1	0	1	0	1		123
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Low	Byte					
		Default Value	0	1	0	0	1	0	0	0		
		Sets the scaling of Output voltage. Th scaled by the value	e intern	al refer	ence is t							
		Format		L	inear, tv	wo's co	mpleme	nt binar	ту			
		Bit Position	7	6	5	4	3	2	1	0		YES
2A	VOUT SCALE MONITOR	Access	r	r	r	r	r	r	r/w	r/w		
		Function		Е	xponer	nt		1	Mantiss	a		
		Default Value	1	0	1	1	1	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function					itissa					
		Default Value	0	0	0	0	0	0	0	0		
											-	
		Sets the value of in	put volt	J			ule turns mpleme			is fixed (	at -6 1	
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r	r	r	r	r	r	r	r	1	
		Function	<del>- '-</del>		xponer		<u> </u>		Mantiss		1	
35	VIN_ON	Default Value	1	1	0	0	1	0	1	0	1	YES
		Bit Position	7	6	5	4	3	2	1	0	1	
			r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Access Function	'	1/W	1/00			1/00	1700	1700	1	
		Default Value	^	0	1	1	ntissa		1	1	1	
		Delault value	0	0	1	1	0	0	1	1	J	
	İ	1										

Hex Code	Command				Brief	Descri	ption					Non-Volatile Memory Storage
		Sets the value of in	put volt	age at v	which th	ie modu	le turns	off. Exp	onent i	s fixed	at -6	
		Format		L	inear, tv	vo's cor	npleme	nt binaı	У			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
36	VIN OFF	Function		E	xponer	nt		1	Mantisso	a		YES
30	VIIN_OFF	Default Value	1	1	0	0	1	0	1	0		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa					
		Default Value	0	0	0	1	0	0	1	1		
		Returns the value o	f the ac	iin corre	ection te	erm useo	d to cor	rect the	measu	red out	out current	
		Format				vo's cor						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r/w		
	10.17 64: 5:	Function			xponer				Mantisso			
38	IOUT_CAL_GAIN	Default Value	ue V: Variable based on factory calibration								YES	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function		1		Man			1	1		
		Default Value		V: Vc	ariable b	ased or		y calibr	ation			
			ı								ı	
		Returns the value o current	f the of							ured ou	ıtput	
	IOUT_CAL_OFFSET	Format				vo's cor				-		
		Bit Position	7	6	5	4	3	2	1	0		
39		Access	r	r	r	r	r	r/w	r	r		YES
33		Function			xponer		. (		Mantiss	123		
		Default Value				ased or				0		
		Bit Position	7	6	5	r/w	3	2	1	0		
		Access	r	r	r/w		r/w	r/w	r/w	r/w		
		Function Default Value		14.146	vriabla b	Man		, aalibr	ation			
		Delduit value		V: VC	ariable t	ased or	1 Tactor	y calibr	ution			
		Sets the voltage lev	el for a			oltage fo wo's co				at -13.	7	
			-						<del></del>	1 ^	-	
		Bit Position	7	6	5	4	3	2	1	0	-	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				High	Byte					
40	VOUT_OV_FAULT_LIMIT	Default Value	0	0	0	1	0	1	1	0		YES
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function			,	Low	Byte			1	1	
		Default Value	0	1	1	0	0	1	1	0	1	
		Instructs the mo	dule on	what a	ction to	take in	resnone	e to a a	outout 4	nvervol+	ane fault	
		Format	Guic OII	vviiut u		Unsigne			Jacput	J V CI V UIL	age raun	
		Bit Position	7	6	5	4	3	2	1	0	-	
41	VOUT OV FAULT RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r	-	YES
41	VOO1_0V_1 AUL1_NL3FUN3E	Function	RSP	RSP	RS[2]	RS[1]	RS[0]	X	X	X	1	1123
		Default Value	[1] 1	[0]	1	1	1	0	0	0	-	
		Delduit value		U			1	U	U	l 0	J	

Hex Code	Command		Brief Description Sets the value of output voltage at which the module generates warning for over-voltage												
		Sets the value of ou Exponent is fixed at	utput vo	ltage at	which	the mod	dule ger	nerates	warning	g for ove	er-voltage.				
		Format		L	inear, tv	vo's cor	mpleme	nt bina	ry						
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r	r	r	r	r	r	r	r					
42	VOUT_OV_WARN_LIMIT	Function		E	xponer	nt			Mantiss	a		YES			
		Default Value	0	0	0	1	1	1	1	1					
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function			1 1		tissa		1 0	1 1					
		Default Value	0	0	1	0	0	0	0	1					
		Sets the value of ou Exponent is fixed at	t -13	L	inear, t	vo's cor	mpleme	nt bina	ry		der-voltage.				
		Bit Position	7	6	5	4	3	2	1	0					
1.7	VOLIT LIV MARKI LIMIT	Access	r	r	r	r	r	r	r Mantice	r/w	-	VEC			
43	VOUT_UV_WARN_LIMIT	Function Default Value	0	0	xponer 0	1 1	0	0	Mantiss 0	a 1		YES			
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w					
		Function	1700	1700	1700		itissa	1700	17 00	1700					
		Default Value	0	1	0	0	1	0	0	0					
44	VOUT_UV_FAULT_LIMIT	Sets the voltage levent Format Bit Position Access Function Default Value Bit Position Access Function Default Value	7 r 0 7 r	6 r		wo's con 4 r nt 1 4 r/w	mpleme 3 r 0 3 r/w tissa 0	nt bina 2 r/w		0 r		YES			
		Sets the voltage lev	el for a	n outpu					is fixed	at -13.	_				
		Format		-			d Binar		-						
/	VOLIT LIVE FALUET DECEDENCE	Bit Position	7	6	5	4	3	2	1	0		VEC			
45	VOUT_UV_FAULT_RESPONSE	Access	r/w RSP	r/w RSP	r/w	r/w	r/w	r	r	r		YES			
		Function	[1]	[0]	RS[2]	RS[1]	RS[0]	Χ	Χ	Χ					
		Default Value	1	0	1	1	1	0	0	0					
		Sets the current lev	el for a							d)	7				
		Format		1			mpleme								
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r	r	r	r	r	r/w	r	r	-				
46	IOUT_OC_FAULT_LIMIT	Function Default Value	1	1	xponer 1	0	0	0	Mantiss 1	1	-	YES			
		Bit Position	7	6	5	4	3	2	1	0	-				
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w	1				
		Function	<del>- '-</del>	<u>' '                                  </u>	1, , ,		itissa	1, **	17 VV	1, 77					
		Default Value	0	0	0	0	1	1	1	1	1				

Hex Code	Command				Brief	Descri	ption					Non-Volatile Memory Storage
		Cata that all a affa		-1 -1	la talla ada							
		Sets the value of cu	irrent ie							or overc	current. 1	
		Format				vo's cor						
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r/w		
4A	IOUT_OC_WARN_LIMIT	Function			xponer				Mantiss			YES
		Default Value	1	1	1	0	0	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	-			Man						
		Default Value	1	1	1	1	1	1	1	1		
		Sets the temperatu	re level								-	
		Format			inear, t	vo's cor	npleme	nt bina	У			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r/w	r	r		
4F	OT_FAULT_LIMIT	Function		E	xponer	nt			Mantiss	а		YES
	01_17(021_211111	Default Value	1	1	1	0	1	0	1	1		123
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man						
		Default Value	1	1	1	0	0	1	1	1		
		Configures the over	tempe	rature f							_	
		Format				Únsigne	d Binary	y				
		Bit Position	7	6	5	4	3	2	1	0		
50	OT_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	Χ	Х	Х		
		Default Value	1	0	1	1	1	0	0	0		
		Sets the over temper	erature	warning	g level i	n °C						
		Format		L	inear, t	wo's cor	npleme	nt bina	Ύ		1	
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r	r	r	r	r	r	r	r	1	
51	OT WARN LIMIT	Function		Е	xponer	nt			Mantiss	а		YES
	3	Default Value	1	1	1	0	1	0	1	1	1	. 20
		Bit Position	7	6	5	4	3	2	1	0	1	
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w	1	
		Function		•	•	Man			•	•	1	
		Default Value	1	0	0	1	0	1	1	0	1	

Hex Code	Command				Brief D	escripti	on					Non-Volatile Memory Storage
		Sets the input over	voltane	fault lir	mit Fxn	onent is	: fixed n	t -6				
		Format			compler				ic fived	at 17	1	
		Bit Position	7	, two s t	5	4	3	2	1 1	0		
		Access	r	r	r	r	r	r	r	r		
		Function	1		xponer		'		Mantiss			
55	VIN_OV_FAULT_LIMIT	Default Value	1	1	0	1	0	0	1	1		YES
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	<u> </u>	.,,,,	.,,,,		tissa	.,,,,	.,,,,	.,,,,		
		Default Value	1	0	0	1	1	0	1	0		
						ı	ı	ı	ı			
		Configures the VIN	overvol	tage fa						-	i	
		Format					d Binar		1			
		Bit Position	7	6	5	4	3	2	1	0		
56	VIN_OV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP [1]	RSP [0]	RS[2]	RS[1]	RS[0]	X	Χ	X		
		Default Value	1	0	0	0	0	0	0	0		
		Sets the value of th	e input	voltage	that ca	uses inp	out volto	age low	warnin	g. Expor	nent	
		Format		1	inear, tv	NU, CUL	nnlema	nt hina	`\/		1	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
57	VIN OV WARN LIMIT	Function	'		xponer		'		Mantiss			YES
31	VIN_OV_WARN_LIMIT	Default Value	1	1	0	1	0	0	1	1		. 20
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa	ı	ı			
		Default Value	1	0	0	1	0	1	0	0		
		Sets the value of th	e input	voltage	that ca	uses inp	out volto	age low	warnin	g. Expor	nent	
		Format		L	inear, tv	vo's cor	npleme	nt binar	У		]	
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
58	VIN_UV_WARN_LIMIT	Function			xponer	nt		1	Mantiss	a		YES
		Default Value	1	1	0	0	1	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function	<u> </u>	-			tissa					
		Default Value	0	1	0	0	0	0	0	0		
		Sets the value of the fixed at -6.	e input	voltage	that ca	uses an	input u	indervo	ltage fa	ult. Expo	onent	
		Format		ı	inear, tv	vo's cor	npleme	nt binar	v			
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r	r	r	r	r	r	r		
59	VIN UV FAULT LIMIT	Function			xponer		·		Mantiss			YES
		Default Value	1	1	0	0	1	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Man	tissa					
		Default Value	0	0	0	0	1	1	1	0		

Hex Code	Command				Brie	f Descri	iption					Non-Volatile Memory Storage
		Instructs the modu	le on wh	nat actio	on to ta	ke In re	sponse	to an in	put und	ervoltag	ge fault.	
		Format	7	6			d Binar		1	_		
		Bit Position	7	6	5	4	3	2	1	0		1150
5A	VIN_UV_FAULT_RESPONSE	Access	r/w	r/w	r/w	r/w	r/w	r	r	r		YES
		Function	RSP	RSP	RS[2]	RS[1]	RS[0]	X	X	X		
		DefaultMalue	[1]	[0] 0	1	1	1	0	0	0		
		Default Value	1	U	1	1	1	U	U	U		
		Sets the output vol-	tage lev						_	xponen	t is fixed at	
		Format					mpleme					
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
5E	POWER_GOOD_ON	Function				High	Byte					YES
		Default Value	0	0	0	1	0	0	1	0		
		Bit Position	7	6	5	4	3	2	1	0		
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w		
		Function				Low	Byte					
		Default Value	0	0	1	1	1	1	1	1		
					•		•	•				
		Sets the output voltat -13.	tage lev				pin is complem			. Expon	ent is fixed	
		Bit Position	7		5	4	3	2	1	0	-	
			7	6 r/w	r/w	r/w	r/w	r/w		0 r/w	_	
	POWER_GOOD_OFF	Access	r	I/W	I/W			I/W	r/w	I/W		1,50
5F		Function					h Byte			1	_	YES
		Default Value	0	0	0	1	0	0	0	1	_	
		Bit Position	7	6	5	4	3	2	1	0	_	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	_	
		Function	_				v Byte				_	
		Default Value	0	1	0	0	1	0	0	0		
60	TON_DELAY	Sets the delay time Format Bit Position Access Function Default Value Bit Position Access Function	7 r 1 7 r/w	6 r E 1 6 r/w	Linear, 5 r xponer 1 5 r/w	two's co	mplem 3 r 1 3 r/w ntissa	ent bind 2 r 0 2 r/w	1 r Mantiss 0 1 r/w	0 0 r/w		YES
		Default Value	0	0	0	0	0	0	0	0		
61	TON_RISE	Sets the rise time in Format Bit Position Access Function Default Value Bit Position	7 r 1 7 r/w	6 r		two's co	ing start		ary 1 r Mantiss 1 1 r/w	0 r/w 6a 1 0 r/w		YES
		Access Function	I/W	I/W	I/W			I/W	I/W	I/W	$\dashv$	
		Default Value	1	0	0		ntissa 1	1	1	0	-	
		Delault value	1	U	0	0	1	1	1	0		

Hex Code	Command				Brief De	escripti	on				Non-Volatile Memory Storage
		Sets the delay time	in ms	of the c	utput v	oltaae (	durina tu	ırn-off			
		Format					omplem		v		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	R	r	r	r	r	r/w	
<i>C 1</i> :	TOFF DELAY	Function			xponei	nt		1	Mantiss	а	YES
64	TOFF_DELAY	Default Value	1	1	1	1	1	0	0	0	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function					ıntissa				
		Default Value	0	0	0	0	0	0	0	0	
		Sets the fall time in	ms of	the outr	out volte	age dur	ing turn-	-off			
		Format					omplem		У		
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	R	r	r	r	r	r/w	
65	TOEE EALL	Function		E	xpone	nt		1	<b>Mantiss</b>	а	YES
00	TOFF_FALL	Default Value	1	0	1	1	1	0	1	1	YES
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w	
		Function					ıntissa				
		Default Value	1	0	0	0	1	1	1	0	
		Returns one byte of	f inform	ation w	ith a su	mmary	of the m	nost critic	cal mod	dule faults	
		Format					ed Binar				
		Bit Position	7	6	5	4	3	2	1	0	
78	STATUS_BYTE	Access	r	r	R	r	r	r	r	r	YES
		Flag	Х	OFF	VOUT	IOUT_ OC	VIN_U\	/ TEMP	CML	OTHE R	123
		Default Value	0	0	0	0	0	0	0	0	
		Returns two bytes of conditions	of inforr	mation (	with a s				fault/v	varning	
		Format				Unsign	ed bina				
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	R	r	r	r	r	r	
79	STATUS_WORD	Flag	VOUT	IOUT_ OC	Х	Х	PGOOL		Х	Х	YES
		Default Value	0	0	0	0	0	0	0	0	
		Bit Position	7	6	5	4	3	2	1	0	
		Access	r	r	R	r	r	r	r	r	
		Flag	Х	OFF	VOUT _OV	IOUT_ OC	VIN_U\			R	
		Default Value	0	0	0	0	0	0	0	0	
		Returns one byte or related faults	f inform	ation w	ith the		of the mo		utput v	oltage	
7A	STATUS_VOUT	Bit Position	-	7	6 5	unsigr	ea Bina 4	3 2	1	0	YES
/A	51A1U5_VUU1	Access	,			-	r	rr		r	YES
		Flag	VOU				UT_UV	XX		X	
		Default Value	V00			)	0	0 0		0	
			'	-	, i	- 1	•	~   ·			

Hex Code	Command			Brief D	escrip	tion					Non-Volatile Memory Storage
		Returns one byte of	f information	with the	status	of the	module'	s output (	current		
		related faults	ı							_	
		Format				gned B		1	4   6		
7B	STATUS_IOUT	Bit Position	7	6 5	4		3	2	1 0		YES
		Access	r	r r	r	IOLIT	r	r	r r		
		Flag	IOUT_OC	XX		1001_	OC_WAR		X X		
		Default Value	0	0 0	0		0	0	0 0		
		Returns one byte of	f information	with the	status	of the	module'	s input re	lated fai	ults	
		Format			Unsi	igned (	3inary				
7.0	CTATUC INDUT	Bit Position	7	(	6	5	4	¥ 3	2 1	0	VEC
7C	STATUS_INPUT	Access	r		r	r	1	r	r r	r	YES
		Flag	VIN_OV_FAI	JLT _W		VIN_U' WARNI			x x	X	
		Default Value	0	(	0	0	(	0	0 0	0	
		Returns one byte of faults	f information					s tempero	ature rel	ated	
		Format			Unsigr			,			
7D	STATUS_TEMPERATURE	Bit Position	7	6	ì	5	4 3	2 1	. 0		
		Access	r	r		r	r r	r r			
		Flag	OT_FAULT		/ARN	Χ	X X	XX			
		Default Value	0	0		0	0 0	0 0	0		
		Returns one byte of related faults  Format	f information	with the		of the		s commu	nication		
		Bit Position	7	6	5	4	3 2	1	0		
7E	STATUS_CML	Access	r	r	r	r	rr	r	r		
, _	335_32	Flag	Invalid Command	Invalid Data	PEC Fail	X	X X	Other Comm Fault	n X		
		Default Value	0	0	0	0	0 0	0	0		
		Returns the value of	f the input vo						is fixed o	at -6	
		Format	7 .				ment bin				
		Bit Position	7 6 r r	5 r	4 r	3 r		1 r	0 r		
		Access Function	r r	Expone		l L	1	Mantiss			
88	READ_VIN	Default Value	1 1	Expone 0	1	1	. 0	0	0		
		Bit Position	7 6	5	4	3		1	0		
		Access	rr	r	r	r		r	r		
		Function	_ '   '	'		antissa		<u>'</u>			
		Default Value	0 0	0	0	0		0	0		
		Returns the value of	f the output	voltage c				nt is fixed	at -13	1	
		Format					ment bin				
		Bit Position	7 6	5	4	3		1	0		
		Access	r r	r	r	r	r	r	r		
8B	READ VOUT	Function			Mo	antissa					
OB	NLAD_VOOT	Default Value	0 0	0	0	0		0	0		
		Bit Position	7 6	5	4	3	_	1	0		
		Access	r r	r	r	r		r	r		
		Function			_	antissa		T -			
		Default Value	0 0	0	0	0	0	0	0		

Returns the volue of the output current of the module	Hex Code	Command		Non-Volatile Memory Storage									
READ_IOUT			Returns the value o	of the ou	utput cu	irrent of	the mo	dule					, ,
Bit Position   7   6   5   4   3   2   1   0	8C								nt bina	rv			
Access				7							0		
READ_IOUT   Exponent   Montissa							_				-		
READ_IOUI   Default Value   1								· · ·					
Bit Position		READ_IOUT		1				0					
Access   r   r   r   r   r   r   r   r   r													
Function													
Returns the module inductor temperature in °C   Format						1		ntissa		1			
READ_TEMPERATURE_1   Format				0	0	0			0	0	0		
READ_TEMPERATURE_1   Format			Returns the module	induc	tor tem	neratur	e in °C						
Bit Position			_	Induc				mnleme	nt hina	r\/			
READ_TEMPERATURE_1				7							Ι 0		
READ_TEMPERATURE_1				<u> </u>	_						-		
Default Value   Bit Position   7   6   5   4   3   2   1   0				<del>- '-</del>	1			1 '					
Bit Position   7   6   5   4   3   2   1   0	8D	READ_TEMPERATURE_1		<del>                                     </del>	Ι	_nporiei				1011033	Ĭ		
Access				7	6	5	4	7	2	1	0		
Returns the module PWM controller temperature in °C					_						_		
Returns the module PWM controller temperature in °C				<u> </u>	<u>' '                                  </u>	<u>' '                                  </u>			'	' '	' '		
READ_TEMPERATURE_2							1 1011	lussa					
READ_TEMPERATURE_2			Detugate the gradual DIAM controller to a 200										
READ_TEMPERATURE_2     Bit Position   7		READ_TEMPERATURE_2	· · · · · · · · · · · · · · · · · · ·										
READ_TEMPERATURE_2													
READ_TEMPERATURE_2				7	6	5	4	3	2	1	0		
Default Value				r				r					
Bit Position   7   6   5   4   3   2   1   0   0   0   0   0   0   0   0   0	8F												
Access	02												
Function				1	6	5	1		2		0		
Default Value				r	r	r			r	r	r		
Returns the switching Frequency of the converter. The Frequency is in Kilohertz and is read only, consisting of two bytes.    Format							Man	ıtissa					
Section   Sect													
Format   Linear, two's complement binary											and		
Bit Position   7   6   5   4   3   2   1   0				urig of t				1			1	1	
READ_FREQUENCY				<u> </u>									
Punction   Exponent   Mantissa					_		_				_		
Default Value				r	<u> </u>			r			1 .		
Default Value	95	READ_FREQUENCY		_									
Access   r   r   r   r   r   r   r   r   r													
Function													
Default Value				r	l r	l L	1	1	r	l L	l r		
Returns one byte indicating the module is compliant to PMBus Spec. 1.1 (read only)  Format Unsigned Binary  Bit Position 7 6 5 4 3 2 1 0  Access r r r r r r r r r				0	^	Λ			0	Λ			
Format			Delault value			U			U	U	U		
Format													
Format			Returns one byte in	dicatin	g the m	odule is	compli	ant to P	MBus S	pec. 1.1	(read or	nly)	
Access r r r r r r r							Unsigne	ed Binar	/			_	
Access r r r r r r r	98	PMBUS_REVISION	Bit Position	7	6					1	0		YES
		111863_NEVISION		r	r	1	r	r		_	r		
Delauit value			Default Value										

# **Manufacturer Specific PMBus commands:**

Hex Code	Command	Brief Description											Non-Volatile Memory Storage
		Returns the minimu	ım inpu							rate at	(read only	y)	
		Format			inear, tu								
		Bit Position	7	6	5	4	3		2	1	0		
		Access	r	r	r	r	r	-	r	r	r		
A0	MFR_VIN_MIN	Function			Exponer					antisso			YES
7.0		Default Value	1	1	1	1	(		0	0	0		123
		Bit Position	7	6	5	4	3		2	1	0		
		Access	r	r	r	r	r		r	r	r		
		Function					ntisso						
		Default Value	0	0	0	0	1	L L	1	0	0		
		Returns the minimum output voltage possible from the module (read only)											
		Format		L	inear, tu	vo's co	mple	ement l	binary				
		Bit Position	7	6	5	4	14)	3	2	1	0		
		Access	r	r	r	r	r		r	r	r		
A4	MFR_VOUT_MIN	Function				Ma	ntisso	מ					YES
A4	MI K_VOOT_MIN	Default Value	0	0	0	0	(		0	1	0		TLS
		Bit Position	7	6	5	4	3	3	2	1	0		
		Access	r	r	r	r	r	-	r	r	r		
		Function				Ma	ntisso	<u> </u>					
		Default Value	0	1	1	0	(	)	1	1	0		
		Returns module na	Returns module name information (read only)										
	MFR_SPECIFIC_00	Format			l	Unsign	ed Bi						
		Bit Position	7	6	5	4	3	3	2	1	0		
		Access	r	r	r	r	r	-	r	r	r		
D0		Function				Res	erve	<u>b</u>					YES
DU		Default Value	0	0	0	0	(		0	0	0		TLS
		Bit Position	7	6	5	4	3	3	2	1	0		
		Access	r	r	r	r	r	-	r	r	r		
		Function			Module	e Name				Rese	rved		
		Default Value	0	0	0	1	(	)	0	0	0		
		Returns module inf	ormatio	n (read	only)							7	
		Format		,				Binary	1				
		Bit Position	7	6	5		4	3	2	1			
		Access	r	r	r		r	r	r	r	r		
		Function					lule N		T 0		1 0	4	
		Default Value	0	0	(		0	0	0	0		1	
		Bit Position	7	6	5		4	3	2	1		1	
		Access	r	r	r		r	<u>r</u>	r	r	r	_	
		Function	_	1 0	1 6		lule N				1 0	1	
		Default Value	0	0	(		1	0	0	0		4	
		Bit Position	7	6	5		4	3	2	1		4	
L 2	MED CDECISIO 01	Access	r	r	r		r	r	r	r	r	4	VEC
D1	MFR_SPECIFIC_01	Function	_	T ~	1 -		lule N				1 ^	4	YES
		Default Value	0	0	(		1	7	0	0		4	
		Bit Position	7	6	5		4	3	2	1		-	
		Access	r	r	r		r I. I. A	r	r	r	r	4	
		Function	7		1 -		lule N		٦	1		-	
		Bit Position	7 r	6 r	5		4	3	2	1		-	
		Access Function	r	r	r		r Iule N	r lame	r	r	r	-	
		Default Value	0	0			0	0 0	0	0	0	-	
		Bit Position	7	6	5		4	3	2	1		-	
		Access	r	r	r	_	r	r	r	r		1	
		Function	'	<u> </u>			lule N					-	
		Default Value	0	0			0	0	0	0	0	-	
		Deluult vulue	U	1 0		,	U	U	U	U	U	<u> </u>	

4.5Vdc –14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# Manufacturer specific PMBus commands (Continued)

Hex Code	Command	Brief Description										Non-Volatile Memory Storage			
		Sets the target volt	age for							at -13.	 1	-			
		Format Bit Position	7	6	inear, tv	4 4	npieme 3	2	1	0					
		Access	r	r	r	r	r	r	r	r					
		Function			xponer		, '		Mantiss						
DB	MFR_VOUT_MARGIN_HIGH	Default Value	1	1	1	1	0	0	0	0		YES			
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r	r	r	r	r	r	r	r					
		Function	'	'	'	Man		' '	' '	'					
		Default Value	0	0	0	0	1	1	0	0					
		<u> </u>						l							
		Sets the target volt													
		Format Linear, two's complement binary													
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r	r	r	r	r	r	r	r					
DC	MFR_VOUT_MARGIN_LOW	Function Default Value	0	0	0	Man 0		0	1 1	0		YES			
		Bit Position	7	6	5	4	3	2	1	0					
		Access	r	r	r	r	r	r	r	r					
		Function					tissa	'	. '						
		Default Value	0	1	1	0	0	1	1	0					
		Deldait value	U			U	U	1 1		U					
		Returns the index d	lerived f	rom the	e resisto	r strapp	ed to th	ne RTUN	NE pin o	f the mo	odule.				
		Format			l	Jnsigne	d Binar	У							
DD	MFR_RTUNE_INDEX	Bit Position	7	6	5	4	3	2	1	0		YES			
טט		Access	r	r	r	r	r	r	r	r		153			
		Function				Rese	rved								
		Default Value													
D1	MFR_WRITE_PROTECT	corresponding PME Format Bit Position Access Function Default Value Bit Position Access Function Default Value Bit 0: ON_OFF_CON Bit 1: IOUT_CAL cor Bit 2: IOUT_OC_FAL	7 r 0 15 r 0 UFIG	6 r 0 14 r 0 compris	0 13 r Module	Jnsigne 4 r Rese 0 12 r	d Binary 3 r erved 0 111 r	y 2 r 0 10 r 0	1 r 0 9 r Rese 0	0 r 0 8 r r erved 0	SET	YES			
		Bit 3: IOUT_OC_FAL Bit 4: OT_FAULT_LIR Bit 5: OT_FAULT_RE Bit 6: TOFF_MAX_W Bit 7: MFR_EXT_TEN Bit 8: MFR_PHASE_( Bit 9: MFR_SPECIFIC Gets or sets the tar	JLT_RES MIT SPONSI /ARN_LI /IP_CAL CONTRO	E MIT _OFFSE		en switc	hina of	f the de	vice. in v	volts. Se	ettina a				
DB	MFR_VOUT_OFF	non-zero value here Format Bit Position Access Function Default Value Bit Position Access Function Default Value Bit Position Access Function Default Value		nable sh L 6 r		n into pi wo's con 4 r t 0 4 r/w	re-bias.	nt bina 2 r/w		0 r		YES			

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Thermal Considerations**

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 38. The preferred airflow direction for the module is shown in Figure 39.

Power Module

Power Module

76.2\_
(3.0)

Probe Location for measuring airflow and ambient temperature

Air flow

Figure 38. Thermal Test Setup.

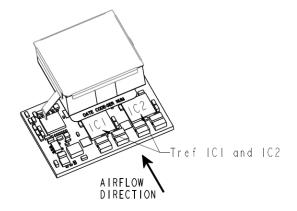


Figure 39. Preferred airflow direction and location of hotspot of the module (Tref).

The thermal reference points,  $T_{\text{ref}}$  used in the specifications are also shown in Figure 39. For reliable operation the temperatures at these points should not exceed 120°C. The

output power of the module should not exceed the rated power of the module (Vo,set  $\times$  Io,max).

Please refer to the Application Note "Thermal Characterization Process For Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

# 80A GigaDLynx<sup>TM</sup>: Non-Isolated DC-DC Power Modules

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

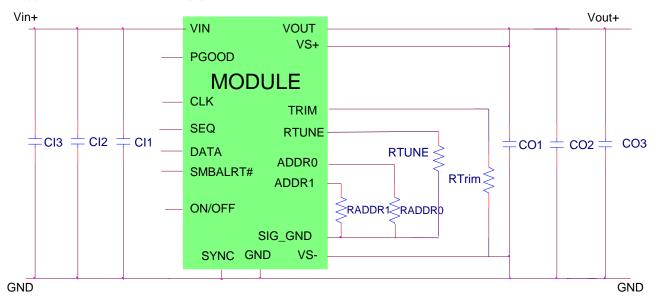
#### **Example Application Circuit**

#### Requirements:

Vin: 12V Vout: 1.2V

lout: 80A max., worst case load transient is from 20A to 60A  $\Delta$ Vout: 1.5% of Vout (18mV) for worst case load transient

Vin, ripple 2% of Vin (220mV p-p)



CI1 Decoupling cap - 1x0.1μF/16V ceramic capacitor (e.g. Murata LLA215R71A224MA14)

CI2 6x22µF/16V ceramic capacitor (e.g. Murata GRM32ER61C226KE20)

CI3  $470\mu F/16V$  bulk electrolytic

CO1 Decoupling cap - 1x0.047µF/16V ceramic capacitor (e.g. Murata LLA215R71A224MA14)

CO2  $6 \times 47 \mu F/6.3 V$  ceramic capacitor (e.g. Murata GRM31CR60J476ME19)

CO3  $10 \times 1000 \mu F/2.5 V$  Polymer (e.g. Sanyo Poscap)

RTune 4.22kohms SMT resistor (can be 1206, 0805 or 0603 size)

RTrim  $2k\Omega$  SMT resistor (can be 1206, 0805 or 0603 size, recommended tolerance of 0.1%)

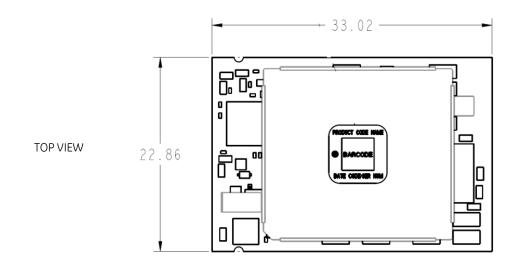
<u>Note:</u> The DATA, CLK and SMBALRT pins do not have any pull-up resistors inside the module. Typically, the PMBus master controller will have pull-up resistors as well as provide the driving source for these signals.

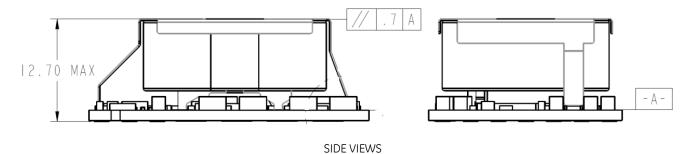
4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Mechanical Outline**

Dimensions are in millimeters and (inches).

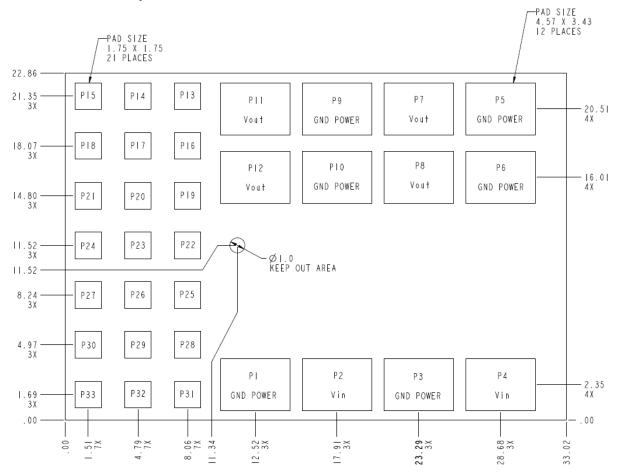
Tolerances: x.x mm  $\pm$  0.5 mm (x.xx in.  $\pm$  0.02 in.) [unless otherwise indicated] x.xx mm  $\pm$  0.25 mm (x.xxx in  $\pm$  0.010 in.)





4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Recommended Pad Layout**



# **Pinout Details**

PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	GND	15	SEQ	29	SMBALERT#
2	VIN	16	VS+	30	NC
3	GND	17	SIG_GND	31	NC
4	VIN	18	NC	32	NC
5	GND	19	PGOOD	33	NC
6	GND	20	ADDR0		
7	VOUT	21	NC		
8	VOUT	22	SYNC		
9	GND	23	ADDR1		
10	GND	24	RTUNE		
11	VOUT	25	ON/OFF		
12	VOUT	26	CLK		
13	VS-	27	NC		
14	TRIM	28	DATA		

4.5Vdc -14Vdc input; 0.6Vdc to 2.0Vdc output; 80A Output Current

# **Ordering Information**

Please contact your GE Sales Representative for pricing, availability and optional features.

### **Table 3. Device Codes**

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Sequencing	Comcodes
GDT080A0X3-SRZ	4.5 - 14Vdc	0.6 – 2.0 Vdc	80A	Negative	Yes	150037110
GDT080A0X43-SRZ	4.5 – 14Vdc	0.6 – 2.0 Vdc	80A	Positive	Yes	150044134

<sup>-</sup>Z refers to RoHS compliant parts

#### Table 4. Coding Scheme

Package Identifier	Family	Sequencing Option	Output current	Output voltage	On/Off logic	Remote Sense	Options		ROHS Compliance
G	D	T	080A0	X		3	-SR	-H	Z
P=Pico U=Micro	D=Dlynx Digital	T=with EZ Sequence	80A	programm	4 = positive No entry =	3 = Remote Sense	S = Surface Mount	Extra Ground Pins	Z = ROHS6
M=Mega G=Giga	V = DLynx Analog.	X=without sequencing		·	negative		R = Tape & Reel		

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