IMPORTANT NOTICE

Texas Instruments and its subsidiaries (TI) reserve the right to make changes to their products or to discontinue any product or service without notice, and advise customers to obtain the latest version of relevant information to verify, before placing orders, that information being relied on is current and complete. All products are sold subject to the terms and conditions of sale supplied at the time of order acknowledgment, including those pertaining to warranty, patent infringement, and limitation of liability.

TI warrants performance of its products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are utilized to the extent TI deems necessary to support this warranty. Specific testing of all parameters of each device is not necessarily performed, except those mandated by government requirements.

Customers are responsible for their applications using TI components.

In order to minimize risks associated with the customer's applications, adequate design and operating safeguards must be provided by the customer to minimize inherent or procedural hazards.

TI assumes no liability for applications assistance or customer product design. TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right of TI covering or relating to any combination, machine, or process in which such products or services might be or are used. TI's publication of information regarding any third party's products or services does not constitute TI's approval, license, warranty or endorsement thereof.

Reproduction of information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations and notices. Representation or reproduction of this information with alteration voids all warranties provided for an associated TI product or service, is an unfair and deceptive business practice, and TI is not responsible nor liable for any such use.

Resale of TI's products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service, is an unfair and deceptive business practice, and TI is not responsible nor liable for any such use.

Also see: Standard Terms and Conditions of Sale for Semiconductor Products, www.ti.com/sc/docs/stdterms.htm

Mailing Address:

Texas Instruments
Post Office Box 655303
Dallas, Texas 75265

Copyright © 2001, Texas Instruments Incorporated
About This Manual

This manual is written to provide information about the evaluation module of the fully differential amplifier under test. Additionally, this document provides a good example of PCB design for high speed applications. The user should keep in mind the following points.

The design of the high-speed amplifier PCB is an elegant and sensitive process. Therefore, the user must approach the PCB design with care and awareness. It is recommend that the user initially review the datasheet of the device under test. It is also helpful to review the schematic and layout of the THS4141 EVM to determine the design techniques used in the evaluation board. In addition, it is recommended that the user review the application note Fully-Differential Amplifiers (literature number SLOA054B) to gain more insight about differential amplifiers. This application note reviews the differential amplifiers and presents calculations for various filters.

How to Use This Manual

- Chapter 1—Introduction and Description
- Chapter 2—Using the THS4141 EVM
- Chapter 3—General High-Speed Amplifier Design Considerations
Information About Cautions and Warnings

This book may contain cautions and warnings.

This is an example of a caution statement.
A caution statement describes a situation that could potentially damage your software or equipment.

This is an example of a warning statement.
A warning statement describes a situation that could potentially cause harm to you.

The information in a caution or a warning is provided for your protection. Please read each caution and warning carefully.

Related Documentation From Texas Instruments

- THS4141 data sheet (literature number SLOS320)
- THS4141 application report (literature number SLOA054A), Fully-Differential Amplifiers

FCC Warning

This equipment is intended for use in a laboratory test environment only. It generates, uses, and can radiate radio frequency energy and has not been tested for compliance with the limits of computing devices pursuant to subpart J of part 15 of FCC rules, which are designed to provide reasonable protection against radio frequency interference. Operation of this equipment in other environments may cause interference with radio communications, in which case the user at his own expense will be required to take whatever measures may be required to correct this interference.

Trademarks

PowerPAD is a trademark of Texas Instruments.
# Contents

## 1 Introduction and Description

1.1 Description ........................................................................................................... 1-1
1.2 Evaluation Module Features ..................................................................................... 1-2
1.3 THS4141 EVM Specifications ................................................................................... 1-3
1.4 Schematic of the Populated Circuit (Default Configuration) ................................. 1-3
1.5 THS4141 EVM Schematic ...................................................................................... 1-4
1.6 Additional Sample Schematics .................................................................................. 1-5
1.7 THS4141 EVM Layout ............................................................................................ 1-7

## 2 Using the THS4141 EVM

2.1 Required Equipment ............................................................................................... 2-1
2.2 Power Supply Setup ............................................................................................... 2-2
2.3 Input and Output Setup ........................................................................................... 2-3
2.4 Testing the EVM Setup ........................................................................................... 2-4
2.5 Power Down Verification ......................................................................................... 2-5
2.6 Measuring the Frequency Response ....................................................................... 2-5
2.7 Butterworth Filter .................................................................................................... 2-6
2.8 THS4141 EVM Bill of Materials ............................................................................. 2-7

## 3 General High-Speed Amplifier Design Considerations ................................. 3-1
Figures

1–1 Schematic of the Populated Circuit on the EVM (Default Configuration) .................. 1-3
1–2 Schematic ......................................................... 1-4
1–3 Fully-Differential In/Fully-Differential Out, Without Transformer ....................... 1-5
1–4 Fully-Differential In/Fully-Differential Out, Utilizing Transformer ..................... 1-5
1–5 VICR Level Shifter .............................. 1-6
1–6 Butterworth Filter With Multiple Feedback ............................................. 1-6
1–7 Top Layer (Silkscreen) ........................................................................ 1-7
1–8 Top (Layer 1) (Signals) ................................................................. 1-7
1–9 Internal Plane (Layer 2) (Ground Plane) ............................................... 1-8
1–10 Internal Plane (Layer 3) (+ VCC Plane) ................................................... 1-8
1–11 Bottom (Layer 4) (Ground and Signal) .................................................. 1-9
2–1 Power Supply Connection ............................................................. 2-2
2–2 Signal Connections ................................................................. 2-3
2–3 Driver 1 Output Signal ................................................................. 2-4
2–4 Multiple Feedback Filter Circuit .......................................................... 2-6
2–5 Gain vs Phase ................................................................. 2-7

Tables

2–1 THS4141 EVM Bill of Materials .......................................................... 2-7
The Texas Instruments THS4141 evaluation module (EVM) helps designers evaluate the performance of the THS4141 operational amplifier. Also, this EVM is a good example of high-speed PCB design.

This document details the Texas Instruments THS4141 high-speed operational amplifier evaluation module (EVM). It includes a list of EVM features, a brief description of the module illustrated with a series of schematic diagrams, EVM specifications, details on connecting and using the EVM, and a discussion of high-speed amplifier design considerations.

This EVM enables the user to implement various circuits to clarify the available configurations presented by the schematic of the EVM. In addition, the schematic of the default circuit has been added to depict the components mounted on the EVM when it is received by the customer. This configuration correlates to the single input/differential output signal.

Other sample circuits are presented to show how the user can implement other circuit configurations such as differential input/differential output signal, transformer utilization on the input and output terminals, VICR level shifter, and Butterworth filter with multiple feedback. The user may be able to create and implement circuit configurations in addition to those presented in this document using the THS4141 EVM.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.1 Description</td>
<td>1-2</td>
</tr>
<tr>
<td>1.2 Evaluation Module Features</td>
<td>1-2</td>
</tr>
<tr>
<td>1.3 THS4141 EVM Specification</td>
<td>1-3</td>
</tr>
<tr>
<td>1.4 Schematic of the Populated Circuit (Default Configuration)</td>
<td>1-3</td>
</tr>
<tr>
<td>1.5 THS4141 EVM Schematic</td>
<td>1-4</td>
</tr>
<tr>
<td>1.6 Additional Sample Schematics</td>
<td>1-5</td>
</tr>
<tr>
<td>1.7 THS4141 EVM Layout</td>
<td>1-7</td>
</tr>
</tbody>
</table>
1.1 Description

The THS4141 EVM is a good example of PCB design and layout for high-speed operational amplifier applications. It is a complete circuit for the high-speed operational amplifier. The EVM is made of the THS4141 high-speed operational amplifier, a number of passive components, and various features and footprints that enable the user to experiment, test, and verify various operational amplifier circuit implementations. The board measures 4.5 inches in length by 2.5 inches in width. Initially, this board is populated for a single-ended input amplifier (see Figure 1-2 for populated circuits). The outputs ($V_{O+}$ and $V_{O-}$) can be tested differentially or single ended. Gain is set to one and can be changed by changing the ratios of the feedback and gain resistors (see the device datasheet for recommended resistor values). The user may populate various footprints on the evaluation module board to verify filter designs or perform other experiments. Each input is terminated with a $50$-$\Omega$ resistor to provide correct line-impedance matching.

1.2 Evaluation Module Features

THS4141 high-speed operational amplifier EVM features include:

- Voltage supply operation range: 5-V to $\pm15$-V operation (see the device data sheet)
- Single and differential input and output capability
- Nominal $50$-$\Omega$ input and output termination resistors. They can be configured according to the application requirement.
- $V_{OCM}$ direct input control (see schematic and the device data sheet)
- $V_{OCM}$ pin can be controlled via transformer center-tap (see schematic)
- Shutdown pin control, JU1 (if applicable to the device, see the device data sheet)
- Input and output transformer footprints for changing single-ended signals to differential signals
- Footprint for high-precision, balanced feedback and gain resistors (0.01% or better)
- Footprints for low-pass filter implementation (see application note SLOA054A)
- Footprints for antialiasing filter implementation (see application note SLOA054A)
- Differential probe terminals on input and output nodes for differential probe insertion
- Various GND and signal test points on the PCB
- Circuit schematic printed on the back of the EVM
- A good example of high-speed amplifier PCB design and layout
1.3 THS4141 EVM Specifications

Supply voltage range, \(\pm V_{CC}\) . . . 5 V to \(\pm 15\) V (see the device data sheet)
Supply current, \(I_{CC}\) . . . . . . . . . . . . . . . . . . (see the device data sheet)
Output drive, \(I_O, V_{CC} = \pm 15\) . . . . . . . . . . . . (see the device data sheet)

For complete THS4141 amplifier IC specifications, parameter measurement information, and additional application information, see the THS4141 data sheet, TI literature number SLOS320.

1.4 Schematic of the Populated Circuit (Default Configuration)

For verification of jumper locations and other bypass components, see the complete EVM schematic in Figure 1–2.

Figure 1–1. Schematic of the Populated Circuit on the EVM (Default Configuration)

---

Note: Default populated footprints on the EVM from the input nodes to the output terminals  Gain = 1
1.5 THS4141 EVM Schematic

*Figure 1–2. Schematic*
1.6 Additional Sample Schematics

For verification of jumper locations and other bypass components, see the complete EVM schematic in Figure 1–2.

**Figure 1–3. Fully-Differential In/Fully-Differential Out, Without Transformer**

![Figure 1–3. Fully-Differential In/Fully-Differential Out, Without Transformer](image)

*Note:* Fully-differential in / fully-differential out signal path. See the Texas Instruments February 2001 Analog Applications Journal for the information on the termination resistors.

**Figure 1–4. Fully-Differential In/Fully-Differential Out, Utilizing Transformer**

![Figure 1–4. Fully-Differential In/Fully-Differential Out, Utilizing Transformer](image)

*Note:* Utilizing the input and output transformers to create a fully-differential signal input/ differential or single output and isolate the amplifier from the rest of the front-end and back-end circuits.
Additional Sample Schematics

Figure 1–5. VICR Level Shifter

Note: Shifting the VICR within the specified range in the data sheet via RPU1 and RPU2 if the VICR is out of the specified range. See the Application section of the data sheet for the THS4141 for more information.

Figure 1–6. Butterworth Filter With Multiple Feedback.

Note: Butterworth filter implemented with multiple feedback architecture
1.7 THS4141 EVM Layout

Figure 1–7. Top Layer (Silkscreen)

Figure 1–8. Top (Layer 1) (Signals)
Figure 1–9. Internal Plane (Layer 2) (Ground Plane)

Figure 1–10. Internal Plane (Layer 3) (± V_{CC} Plane)
Figure 1-11. Bottom (Layer 4) (Ground and Signal)
It is recommended that the user perform the following exercises to learn the usage of the EVM. This practice helps the user learn about the various terminals on the EVM and their function. In addition, it suggests the components and equipment needed to operate the EVM.

<table>
<thead>
<tr>
<th>Topic</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>2.1 Required Equipment</td>
<td>2–2</td>
</tr>
<tr>
<td>2.2 Power Supply Setup</td>
<td>2–2</td>
</tr>
<tr>
<td>2.3 Input and Output Setup</td>
<td>2–3</td>
</tr>
<tr>
<td>2.4 Testing the EVM Setup</td>
<td>2–4</td>
</tr>
<tr>
<td>2.5 Power Down Verification</td>
<td>2–5</td>
</tr>
<tr>
<td>2.6 Measuring the Frequency Response</td>
<td>2–5</td>
</tr>
<tr>
<td>2.7 Butterworth Filter</td>
<td>2–6</td>
</tr>
<tr>
<td>2.8 THS4141 EVM Bill of Materials</td>
<td>2–7</td>
</tr>
</tbody>
</table>
2.1 Required Equipment

- One double-output dc power supply (±5 V, 100 mA output minimum)
- Two dc current meters with resolution to 1 mA and capable of the maximum current the dc power supply can supply. If available, set the current limit on the dc power supply to 100 mA.
  
  Note: Some power supplies incorporate current meters which may be applicable to this test.
- 50-Ω source impedance function generator (1 MHz, 10 V_{PP} sine wave)
- Oscilloscope (50-MHz bandwidth minimum, 50-Ω input impedance).

2.2 Power Supply Setup

1) Set the dc power supply to ±5 V.
2) Make sure the dc power supply is turned off before proceeding to the next step.
3) Connect the positive (+) terminal of the power supply to the positive (+) terminal of the current meter number 1.
4) Connect the negative (–) terminal of the current meter number 1 to the V_{CC+} of the EVM (J7).
5) Connect the common ground terminal of the power supply to the ground GND on the EVM (J9).
6) Connect the negative (–) terminal of the power supply to the negative (–) terminal of the second current meter.
7) Connect the positive (+) terminal of the current meter number 2 to the V_{CC–} of the EVM (J8).

Figure 2-1. Power Supply Connection

Figures are not drawn to scale.
2.3 Input and Output Setup

1) Ensure that JU3, JU4, and JU1 are not installed (open circuit).

2) Set the function generator to generate a 1 MHz, ±0.5 V (1 Vpp) sine wave with no dc offset.

3) Turn off the function generator before proceeding to the next step.

4) Using a BNC-to-SMA cable, connect the function generator to J1 (V_in+) on the EVM.

5) Using a BNC-to-SMA cable, connect the oscilloscope to J3 (V_out−) on the EVM.

6) Using a BNC-to-SMA cable, connect the oscilloscope to J4 (V_out+) on the EVM. Set the oscilloscope to 0.5 V/division and a time-base of 0.2 μs/division.

Note: The oscilloscope must be set to use a 50-Ω input impedance for proper results.

Figure 2–2. Signal Connections

Note: Figures are not drawn to scale.
2.4 Testing the EVM Setup

1) Turn on the dc power supply.

2) Verify that both the +5 V (current meter 1) and the –5 V (current meter 2) currents are below 20 mA.

**Caution:**

Currents above 20 mA indicate a possible short or a wrong resistor value on the PCB. Do not proceed until this situation is corrected.

3) Turn on the function generator.

4) Verify the oscilloscope is showing two 1 MHz sine waves with amplitude of ±0.125 V. The dc offset of the signal must be below 50 mV.

Note: $V_{OUT+}$ and $V_{OUT-}$ should be 180 degrees out of phase. The internal attenuation of the scope should be set to 6 dB for a gain of one. Otherwise, the output will show a *gain of one-half* due to the voltage division occurring at the 50-Ω termination resistor.

Use Figure 3 as a reference for the input and output signals.

*Figure 2–3. Driver 1 Output Signal*
2.5 Power Down Verification

This EVM is used to evaluate devices with and without the shutdown function. Therefore, this step is only applicable if the device has a shutdown function. Please see the data sheet for power-down verification.

1) Insert the jumper JU1 to power down the device. The current consumption (dc current meters) should drop to less than 1.5 mA. Remember to discount the current flow through the 10-kΩ pullup resistor on the EVM when calculating the device current consumption in the shutdown mode.

2) Turn off the power supply and disconnect the wiring.

3) Turn off the function generator and disconnect the wiring.

4) Basic operation of the operational amplifier and its EVM is complete.

2.6 Measuring the Frequency Response

This EVM is designed to easily interface with network analyzers. Jumpers J3 and J4 facilitate the use and insertion of the differential probes at the input and output nodes. It is important to consider the following steps to ensure optimal performance in terms of bandwidth, phase margin, gain, and peaking.

1) Connect the power supply according to the power supply set up (section 2.2).

2) Use proper load values. Loads directly affect the performance of the differential operational amplifier (the suggested value is 200 Ω differentially, 100 Ω on each output node).

Caution:
Incorrect connections cause excessive current flow and may damage the device.

3) Place the GND connection of the probe as close as possible to the output nodes. Use the GND holes on the EVM. The GND holes create a shorter route to the GND plane and output nodes.

4) Place the probe at the input nodes, set the power level of the network analyzer to the proper level (information in the data sheet typically is produced at –20 dBm power level), and calibrate the network analyzer.

Note:
If a differential probe is used, verify that resistors R1a, R1b, R4b, and R4a are in place. The resistors are 0 Ω values providing the path to the differential probe terminals.

5) Place the probe at the output nodes (if a differential probe is used, insert the probe into the provided jumper), and measure the frequency response.
Note:
Transformers are used to change the single ended signals to differential signal or vice versa. On this EVM, they can be populated according to the application or the experiment. The $V_{OCM}$ pin of the device may be connected to the center-tap of the transformer, or maybe set via an external source such as $V_{ref}$ of a data converter. If the $V_{OCM}$ pin is not connected to an external source, it will be set at the center point of the power supply. For example, if ±5 sources are used, the $V_{OCM}$ level will be set to zero.

2.7 Butterworth Filter

An example of a Butterworth filter implemented with multiple feedback architecture is provided. The following circuit is implemented on the EVM board. The following figures represent the circuit configuration and the component values. The corner frequency of the filter (−3dB) is set at 1 MHz.

For verification of jumper locations and other bypass components, see the complete EVM schematic in Figure 1–2.

Figure 2–4. Multiple Feedback Filter Circuit
Figure 2–5. Gain vs Phase

Butterworth filter with multiple feedback frequency response.

2.8 THS4141 EVM Bill of Materials

Table 2–1. THS4141 EVM Bill of Materials

<table>
<thead>
<tr>
<th>Ref.</th>
<th>Description</th>
<th>Size</th>
<th>Qty.</th>
<th>Manufacturer</th>
<th>Part Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>C1, C4, C5, C6</td>
<td>Capacitor, 0.1 μF, ceramic</td>
<td>0805</td>
<td>4</td>
<td>Murata</td>
<td>GRM40–X7R104K25</td>
</tr>
<tr>
<td>C7, C8</td>
<td>Capacitor, 6.8 μF, 35 V, 20% tantalum, SM</td>
<td>7343</td>
<td>2</td>
<td>Sprague</td>
<td>293D685X9035D2T</td>
</tr>
<tr>
<td>C1A, C1B, C2, C3A, C3B</td>
<td>Open</td>
<td>0805</td>
<td>5</td>
<td></td>
<td></td>
</tr>
<tr>
<td>J1, J2, J3, J4</td>
<td>SMT_PCB_MT</td>
<td>SMA jack</td>
<td>4</td>
<td>Amphenol</td>
<td>901-144-8RFX</td>
</tr>
<tr>
<td>J6, J7, J8, J9</td>
<td>Banana jack</td>
<td></td>
<td>4</td>
<td>Newark</td>
<td>35F865</td>
</tr>
<tr>
<td>JU1, JU2, JU3, JU4</td>
<td>2 pos jumper header, 0.1 cttrs., 0.025” sq pins</td>
<td>2 pos jump</td>
<td>4</td>
<td></td>
<td></td>
</tr>
<tr>
<td>JU1, JU2</td>
<td>Shorting jumpers header, 0.1 cttrs., 0.025” sq pins</td>
<td></td>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>L1, L2</td>
<td>Inductor, 0.22 μH SM</td>
<td>0805</td>
<td>2</td>
<td>Digi-Key</td>
<td>PCD1176CT–ND</td>
</tr>
<tr>
<td>R1a, R1b, RX1, RX4, RX5</td>
<td>Resistor, 0 Ω, 1%</td>
<td>0805</td>
<td>5</td>
<td>Digi-Key</td>
<td>P0.0ACT–ND</td>
</tr>
<tr>
<td>R2a, R2b, R5, R12, R13, R14, R15, RX2, RX7, RX8, RX9</td>
<td>Open</td>
<td>0805</td>
<td>11</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
### Table 2–1. THS4141 EVM Bill of Materials (continued)

<table>
<thead>
<tr>
<th>Ref.</th>
<th>Description</th>
<th>Size</th>
<th>Qty.</th>
<th>Manufacturer</th>
<th>Part Number</th>
</tr>
</thead>
<tbody>
<tr>
<td>R3a, R3b</td>
<td>Resistor, 374 Ω, 1%</td>
<td>0805</td>
<td>2</td>
<td>Digi-Key</td>
<td>P374CTR-ND</td>
</tr>
<tr>
<td>R4a, R4b</td>
<td>Resistor, 0 Ω, 1%</td>
<td>1206</td>
<td>2</td>
<td>Digi-Key</td>
<td>P0.0ECT-ND</td>
</tr>
<tr>
<td>R6a, R6b</td>
<td>Resistor, 402 Ω, 1%</td>
<td>0805</td>
<td>2</td>
<td>Digi-Key</td>
<td>P402CTR-ND</td>
</tr>
<tr>
<td>R11</td>
<td>Resistor, 10 kΩ, 1%</td>
<td>0805</td>
<td>1</td>
<td>Digi-Key</td>
<td>P10.KCTR-ND</td>
</tr>
<tr>
<td>R10, RX3, RX6</td>
<td>Resistor, 49.9 Ω, 1%</td>
<td>1206</td>
<td>3</td>
<td>Digi-Key</td>
<td>P49.9FTR-ND</td>
</tr>
<tr>
<td>R16, R7</td>
<td>Open</td>
<td>1206</td>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>R36aA, R36aB, R36bA, R36bB</td>
<td>High precision resistor</td>
<td>0805</td>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>RPU1, RPU2</td>
<td>Open</td>
<td>0805</td>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>RX0</td>
<td>Resistor, 24.9 Ω, 1%</td>
<td>0805</td>
<td>1</td>
<td>Digi-Key</td>
<td>P24.9CTR-ND</td>
</tr>
<tr>
<td>T1, T2</td>
<td>Open</td>
<td>MC KK81</td>
<td>2</td>
<td></td>
<td></td>
</tr>
<tr>
<td>TP1, TP2, TP3</td>
<td>Test point 2</td>
<td>TP .025</td>
<td>3</td>
<td>Farnell</td>
<td>240-345</td>
</tr>
<tr>
<td>TP4, TP5, TP6, TP7</td>
<td>Test point 2</td>
<td>TP .025</td>
<td>4</td>
<td>Farnell</td>
<td>240-333</td>
</tr>
<tr>
<td>U1</td>
<td>IC, THS4141</td>
<td>8 Pin DGN</td>
<td>1</td>
<td>Texas Instruments</td>
<td>THS4141CDGN</td>
</tr>
</tbody>
</table>
General High-Speed Amplifier Design Considerations

The THS4141 EVM layout has been designed for use with high-speed signals and can be used as an example when designing PCBs incorporating the THS4141. Careful attention has been given to component selection, grounding, power supply bypassing, and signal path layout. Disregarding these basic design considerations could result in less than optimum performance of the THS4141 high-speed operational amplifier.

Surface-mount components were selected because of the extremely low lead inductance associated with this technology. This helps minimize both stray inductance and capacitance. Also, because surface-mount components are physically small, the layout can be very compact.

Tantalum power supply bypass capacitors at the power input pads help supply currents needed for rapid, large signal changes at the amplifier output. The 0.1-μF power supply bypass capacitors were placed as close as possible to the IC power input pins in order to minimize the return path impedance. This improves high frequency bypassing and reduces harmonic distortion.

A proper ground plane on both sides of the PCB should be used with high-speed circuit design. This provides low-inductive ground connections for return current paths. In the area of the amplifier input pins, however, the ground plane should be removed to minimize stray capacitance and reduce ground plane noise coupling into these pins. This is especially important for the inverting pin while the amplifier is operating in the noninverting mode. Because the voltage at this pin swings directly with the noninverting input voltage, any stray capacitance would allow currents to flow into the ground plane. This could cause possible gain error and/or oscillation. Capacitance variations at the amplifier input pin of greater than 1 pF can significantly affect the response of the amplifier.

In general, it is best to keep signal lines as short and as straight as possible. Incorporation of microstrip or stripline techniques is also recommended when signal lines are greater than 1 inch in length. These traces must be designed with a characteristic impedance of either 50 Ω or 75 Ω, as required by the application. Such a signal line must also be properly terminated with an appropriate resistor.
Finally, proper termination of all inputs and outputs must be incorporated into the layout. Unterminated lines, such as coaxial cable, can appear to be a reactive load to the amplifier. By terminating a transmission line with its characteristic impedance, the amplifier’s load then appears to be purely resistive, and reflections are absorbed at each end of the line. Another advantage of using an output termination resistor is that capacitive loads are isolated from the amplifier output. This isolation helps minimize the reduction in the amplifier’s phase-margin and improves the amplifier stability resulting in reduced peaking and settling times.