

Lecture 15 Interaction Picture

In the previous course we to perturbation theory about the expansion of the perturbed state in terms of the unperturbed state was covered. This was working in the Schrödinger picture which requires the inclusion of the unperturbed, uninteresting, static

There is a simpler picture, the Interaction Representation (or Dirac)

Consider a time translation operator generated by only H_0 in $H = H_0 + H_I$...

$$|\tilde{\phi}(t)\rangle^H = T^{-1}(t, t_0) |\phi(t)\rangle$$

then, now define

$$|\tilde{\phi}(t)\rangle^I = R^{-1}(t, t_0) |\phi(t)\rangle$$

where:

T generated by H

$$T = e^{-iHt}$$

R generated by H_0

$$R = e^{-iH_0 t}$$

That means

$$i\hbar \frac{\partial R}{\partial t} = H_0 R$$

which is like

$$i\hbar \frac{\partial T}{\partial t} = (H_0 + H_I) T$$

Substituting $|\phi(t)\rangle = R(t, t_0) |\tilde{\phi}(t)\rangle$ into Schrödinger equation.

and we see that the time evolution of $|\phi\rangle_I$ driven by \hat{H}_I

Schrödinger equation

$$i \frac{\partial}{\partial t} |\phi(t)\rangle_I = \hat{H}_I |\phi(t)\rangle_I$$

not the

Ans,

$$= e^{i\hat{H}_I(t-t_0)} e^{-i\hat{H}_0(t-t_0)}$$

$$\hat{D}(t) = R_+(t, t_0) \hat{D}(t_0)$$

interaction representation

We can then designate any operator as in the

$$i \frac{\partial}{\partial t} |\phi\rangle_I = R_+(t, t_0) \hat{H}_I R_-(t, t_0) |\phi(t)\rangle_I$$

operator $R_+ \rightarrow$

$$i R \frac{\partial}{\partial t} |\phi(t)\rangle_I = \hat{H}_I R |\phi(t)\rangle_I$$

Ans

~~\hat{H}_0~~

$$i \frac{\partial}{\partial t} (R |\phi(t)\rangle_I) = i R \frac{\partial}{\partial t} |\phi(t)\rangle_I + i \langle \phi(t) | \hat{H}_0 R |\phi(t)\rangle_I + i \langle \phi(t) | \hat{H}_I R |\phi(t)\rangle_I$$

$$i \frac{\partial}{\partial t} R |\phi(t)\rangle_I = (H_0 + H_I) R |\phi(t)\rangle_I$$

$$i \frac{\partial}{\partial t} |\phi(t)\rangle_S = (H_0 + H_I^S) |\phi(t)\rangle_S$$

Measurable, since $\hat{O} = R^{-1}OR$

$$\frac{d\hat{O}}{dt} = \frac{\partial R^{-1}OR}{\partial t} + R^{-1}O\frac{\partial R}{\partial t}$$

$$= \underbrace{R^{-1}H_0R}_{-R^{-1}H_0R}$$

$$= \lambda (R^{-1}H_0OR - R^{-1}OH_0R)$$

$$= \lambda (R^{-1}H_0R^T OR - R^{-1}OR^T H_0R)$$

$$= \lambda (H_0\tilde{O} - \tilde{O}H_0)$$

and

$$\frac{d\hat{O}}{dt} = \lambda [\hat{H}_0, \hat{O}]$$

operator's time evolution governed by H_0 is not dependent

This is crucial in field theory $\Rightarrow \psi(x), \psi(x), \dots$ etc can continue to have $e^{iH_0 t}$ dependence

Let's consider time evolution within the

interaction representation. That is, just as we had

$$|\phi(t)\rangle_S = T(t, t_0) |\phi(t_0)\rangle_S$$

we now state,

$$|\tilde{\phi}(t)\rangle = U(t, t_0) |\tilde{\phi}(t_0)\rangle$$

we know U, U^\dagger know everything, \leftarrow a unitary operator in the interaction representation

where

$$\frac{\partial}{\partial t} |\tilde{\phi}(t)\rangle = -i\tilde{H}_I |\tilde{\phi}(t)\rangle$$

$$\frac{\partial}{\partial t} U(t, t_0) |\tilde{\phi}(t_0)\rangle = -i\tilde{H}_I U(t, t_0) |\tilde{\phi}(t_0)\rangle$$

so,

or, as an operator equation (satisfying boundary conditions)

$$\frac{\partial}{\partial t} U(t, t_0) = -i\tilde{H}_I U(t, t_0)$$

Associate

$$U(t, t_0) = 1 - i \int_{t_0}^t dt_1 H_I(t_1) + (-i)^2 \int_{t_0}^t dt_1 \int_{t_1}^{t_0} dt_2 H_I(t_1) H_I(t_2) - \dots + (-i)^n \int_{t_0}^t dt_1 \int_{t_1}^{t_0} dt_2 \dots \int_{t_{n-1}}^{t_0} dt_n H_I(t_1) H_I(t_2) \dots H_I(t_n)$$

which can be continued indefinitely.

$$t_0 \leq t_1 \leq t \quad t_0 \leq t_1 \leq t \quad t_0 \leq t_2 \leq t_1$$

$$U(t, t_0) = 1 - i \int_{t_0}^t dt_1 H_I(t_1) + (-i)^2 \int_{t_0}^t dt_1 \int_{t_1}^{t_0} dt_2 H_I(t_1) H_I(t_2) U(t_2, t_0)$$

(forget time -- on interaction Rep.)

$$= 1 - i \int_{t_0}^t dt_1 \tilde{H}_I(t_1) \left[1 - i \int_{t_1}^{t_0} dt_2 \tilde{H}_I(t_2) U(t_2, t_0) \right]$$

$$U(t, t_0) = 1 - i \int_{t_0}^t dt_1 \tilde{H}_I(t_1) U(t_1, t_0)$$

To solve this, convert to an iterative approach.

with the boundary condition $U(t, t) \equiv \mathbb{1}$.

$$U(t, t_0) = 1 - i \int_{t_0}^t dt_1 \tilde{H}_I(t_1) U(t_1, t_0)$$

equation.

This can be formally written as an integral equation.

use the position operator
the Hamiltonian

$$1 - \int_t^{t_0} dt_1 \int_t^{t_1} dt_2 H(t_1) H(t_2)$$

Go back to the iterated sum.
in time has to be preserved: $H' \neq H''$
at different times may not commute \Rightarrow the ordering
which may not necessarily happen. So, the Hamiltonian

$$\neq 0 \text{ unless } [H_0, H_I] = 0$$

what about $[H_I(x), H_I(x')] = (e^{iH_0(x-t)} - e^{iH_0(x'-t)}) e^{iH_I(x-t)}$

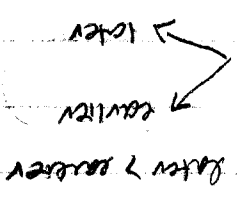
$$H_I(x) = e^{iH_0(x-t)} H_I(x-t) e^{-iH_0(x-t)}$$

Remember how the evolution operator in \hat{O}

etc.

$$U^{(1)}(t, t_0) = -i \int_{t_0}^t dt_1 H_I(t_1)$$

$$U(t, t_0) = U^{(0)}(t, t_0) + U^{(1)}(t, t_0) + \dots = \sum_{n=0}^{\infty} U^{(n)}(t, t_0)$$



later
earlier
 $H_I(x_1) H_I(x_2)$

Left to Right - decreasing time order

the n^{th} order term

$$U^{(n)}(t_0) = (-i)^n \int_{t_0}^t dt_1 \int_{t_1}^{t_0} dt_2 \dots \int_{t_{n-1}}^{t_1} dt_n \dots H_I(x_1) H_I(x_2) \dots H_I(x_n)$$

$$= (-i)^n \int_{t_0}^t dt_1 \int_{t_1}^{t_0} dt_2 \dots \int_{t_{n-1}}^{t_1} dt_n \dots H_I(x_1) H_I(x_2) \dots H_I(x_n)$$

SM order

There is a trick to change this situation having a unique time & space integration limit - a new ordering

operation

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$$P[\theta(x_1)\theta(x_2) - \theta(x_2)\theta(x_1)] \equiv$$

product of operators arranged
L to R in decreasing time
order w/out regard to
commutation relations

"chronological ordering"

for example

$$P[\theta(x)\theta(x')] = \theta(x)\theta(x') \quad t > t'$$

$$\theta(x)\theta(x') \quad t > t'$$

$L > E$

$$P[\theta(x)\theta(x')\theta(x'')] = \theta(x)\theta(x')\theta(x'') \quad t > t' > t''$$

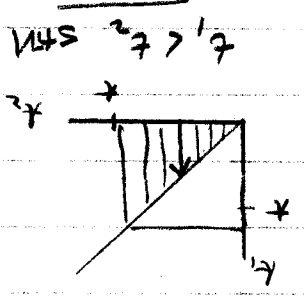
etc

→ This is the same as the 1st term on RHS

$$\int_{t_1}^{t_0} dt_1 \int_{t_2}^{t_0} dt_2 H_1(t_1) H_2(t_2)$$

Now change names of labels.

Same area.



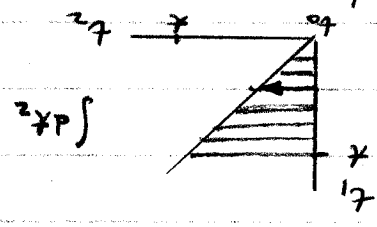
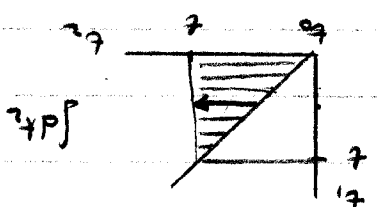
$$\int_t^{t_0} dt_2 \int_{t_2}^{t_0} dt_1 H_1(t_2) H_2(t_1)$$

change the order of integration

look at 2nd term on RHS...

$$t_2 < t_1$$

$$+ \int_t^{t_0} dt_1 \int_{t_1}^{t_0} dt_2 H_1(t_2) H_2(t_1)$$



$$\int_{t_1}^{t_0} dt_1 \int_{t_1}^{t_0} dt_2 H_1(t_1) H_2(t_2)$$

$$= \int_t^{t_0} dt_1 \int_t^{t_0} dt_2 H_1(t_1) H_2(t_2)$$

Consider them,

$$P[\theta(x)\theta(y)] = \theta(x)\theta(y) \text{ if } t > t'$$

$L > E$

SD

$$\int_t^{t_0} dx_1 \int_t^{t_0} dx_2 P [H_I(t_1) H_I(t_2)] = 2 \int_t^{t_0} dx_1 \int_t^{t_0} dx_2 H_I(t_1) H_I(t_2) \quad (12)$$

SD

$t_1 > t_2$ period.

and SD

$$U(t, t_0) = \sum_n \frac{(-i)^n}{n!} \int_t^{t_0} dx_1 \int_t^{t_0} dx_2 \dots \int_t^{t_0} dx_n P [H_I(t_1) \dots H_I(t_n)]$$

$$= \sum_n \frac{(-i)^n}{n!} \int dx_1 \int dx_2 \dots \int dx_n P [2I_I(x_1) 2I_I(x_2) \dots 2I_I(x_n)]$$

The physical interest is on them: $t_0 \rightarrow -\infty$ $t \rightarrow \infty$

and the time evolution operator which is

introduced to do that is

$$S \equiv \lim_{\substack{t_0 \rightarrow -\infty \\ t \rightarrow \infty}} U(t, t_0)$$

called the "S Matrix"

$$S = \sum_{n=0}^{\infty} \frac{(-i)^n}{n!} \int dx_1 \int dx_2 \dots \int dx_n P [2I_I(x_1) \dots 2I_I(x_n)]$$

The physical significance is the following:

If a system is in state $|\psi(t_0)\rangle$ at $t = t_0$
 The probability that it will evolve to system $|\psi(t)\rangle$ at $t = t_1$