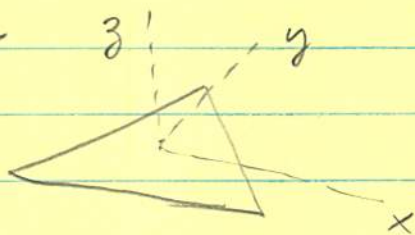


Vector Spaces

Groups have applicability in physics when they have an algebraic "playing field" to operate in.

For example -- the triangle needs to be embedded in a coordinate space



with the operations defined as transformations on x, y, z .

GROUP REPRESENTATIONS

→ vector spaces, $\vec{x} = (x, y, z)$ is an example. But, it's more general than that.

→ like the notation from Ture's book.

Again, a 19th century invention -- largely from Grassmann, a high school teacher

So, we have 2 entities

$$I. \quad \boxed{\text{Scalars}} \quad a, b, c, \dots \quad \left. \begin{array}{l} A, \oplus \\ B, \otimes \end{array} \right\} + \text{Properties} \\ \text{field, } \mathcal{F}$$

II. vectorsa vector space, V with a set of elements ξ, η, \dots having properties:

A. $\xi, \eta \in V \Rightarrow \exists$ another $\xi \oplus \eta \in V$

closure
vector sumB & C
& commutative, associative

D $\exists \phi \Rightarrow \xi \oplus \phi = \xi$
origin, inverse
D E

F. $\forall a \in \mathcal{F}$ and $\xi \in V \exists a\xi \in V$

G & associative, H $1\xi = \xi$, I distributive with respect to vector addition and J also scalar additionDEF. span: A space V is spanned by a set of vectors if every vector $\in V$ can be represented by a linear combinationA-J above define a Linear Vector Space, L III. V is unitary if \exists an operation called the scalar product, or "inner product" $(\xi, \eta) \rightarrow$ scalar-valued, real or complex

A. $(\xi, \eta) = (\eta, \xi)^* = a$

B. $(\xi, \eta \oplus \delta) = (\xi, \eta) \oplus (\xi, \delta)$

C. $(\xi, a\eta) = a(\xi, \eta)$

D. 1) $(\xi, \xi) \geq 0$ 2) $(\xi, \xi) = 0$ iff $\xi = \phi$

E. 1) $(\xi, a\eta \oplus b\delta) = a(\xi, \eta) \oplus b(\xi, \delta)$ linear

2) $(a\xi \oplus b\eta, \delta) = a^*(\xi, \delta) \oplus b^*(\eta, \delta)$ antilinear

IV also: "outer products"

NOTATION: we'll use Dirac Notation

$$\xi \leftrightarrow |\xi\rangle$$

for both linear and antilinear spaces

$$\begin{array}{ccc} \uparrow & & \uparrow \\ v & & \tilde{v} \end{array}$$

$$(\xi, \eta)$$

anti-linear in ξ linear in η

So: $|\eta\rangle \in V$ \tilde{v} is "dual" to V
 $\langle \xi | \in \tilde{V}$

If ξ and η are antilinear to one another, then

$$(\xi, \eta) = \langle \xi | \eta \rangle = \langle \eta | \xi \rangle^*$$

Useful when a Representation is chosen ... then, the vectors are Representatives.

IV. Usually - think of an ordered list

$$\xi = \{ \xi^1, \xi^2, \xi^3, \dots, \xi^n \} \quad \text{a contravariant vec.}$$

components: ordered list of scalars

So, $\xi \oplus \eta = \gamma$

i $\{ \xi^1 \oplus \eta^1, \xi^2 \oplus \eta^2, \dots \} = \{ \gamma^1, \gamma^2, \dots \}$

ii $a\xi = \{ a\xi^1, a\xi^2, \dots \}$

iii $\langle \xi | \xi \rangle = |\xi|^2 = |\xi^1|^2 + |\xi^2|^2 + \dots + |\xi^n|^2$

where $|\xi^i|^2 = \xi^{i \times} \xi^i$

think "geometry": $|\xi| = + \sqrt{\langle \xi | \xi \rangle}$ "length"

if $|\xi| = 1 \Rightarrow \xi$ is "normalized"

II. Scalar product

$$\langle \xi | \eta \rangle = \sum_{i=1}^n \xi_i^+ \eta^i \quad (= (\xi, \eta))$$

where $\xi_i^+ = \xi^{i \times}$

VI. Einstein summation convention:

$$\sum_{i=1}^n \xi_i^+ \eta^i \equiv \xi_i^+ \eta^i$$

VII. Orthogonality

$$\langle \xi | \eta \rangle = 0 \Rightarrow \xi \neq \eta \text{ are orthogonal}$$

more notation:

We can have sets of vectors

$$\vec{\phi}_i$$

$$\uparrow$$

index labels different vectors

$$\vec{\phi}_1 = \alpha$$

$$\vec{\phi}_2 = \beta$$

$$\vdots \uparrow$$

each a vector

with components

So, we could have

$$\vec{\phi}_{ij}$$

vector \nearrow component \nwarrow

OR

$$|\phi_{(i)}^j\rangle$$

component \leftarrow

vector .. will use "()" if not obvious

VIII. Linear independence of a set of vectors

$$|\phi_{(i)}\rangle a^i = 0 \Rightarrow a^i = 0 \text{ for all } i.$$

Without proof:

- for d -dimensional V , no more than d linearly independent vectors spanning V
- It is possible to form a mutually orthogonal set of vectors spanning V which are L.I.
- no such set is unique.

eg.

The most familiar vector set: \hat{E}_3

$$\hat{i} = \{1, 0, 0\} \quad \hat{j} = \{0, 1, 0\} \quad \hat{k} = \{0, 0, 1\}$$

They are mutually orthogonal $\langle i | j \rangle = 0$ etc

In my notation $|\hat{e}_{(i)}\rangle$:

$$|\hat{e}_{(1)}\rangle = \hat{i} = \{1, 0, 0\}$$

$$|\hat{e}_{(2)}\rangle = \hat{j}$$

$$|\hat{e}_{(3)}\rangle = \hat{k}$$

so,

$$|\hat{e}_{(1)}\rangle = \{e_{(1)}^1, e_{(1)}^2, e_{(1)}^3\} = \{1, 0, 0\}$$

get it?

Orthonormality - conveniently, one statement

$$\langle \hat{e}^{(j)} | \hat{e}_{(i)} \rangle = \delta^j_i = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

Let $|\eta_1\rangle, |\eta_2\rangle, \dots, |\eta_d\rangle$ be a set of L.I. vectors in V_d and $|\xi\rangle$ be an arbitrary vector in V_d

$|\xi\rangle$ has a unique representation as a linear combination of $|\eta_i\rangle$

$$|\xi\rangle = |\eta_{(i)}\rangle c^i$$

↑
the "basis set"

We can determine the c^i :

$$\begin{aligned} \langle \eta^{(j)} | \xi \rangle &= \langle \eta^{(j)} | \eta^{(i)} \rangle c^i \\ &= \delta_{ij} c^i = \boxed{c^j = \langle \eta^{(j)} | \xi \rangle} \end{aligned}$$

$$\text{So, } |\xi\rangle = |\eta^{(i)}\rangle \underbrace{\langle \eta^{(i)} | \xi \rangle}_{\text{geometrical notion of projecting } \vec{\xi} \text{ along } \vec{\eta} \text{'s}}$$

Within the particular η basis, the components of ξ are:

$$\langle \eta^{(i)} | \xi \rangle = \xi^i = c^i$$

$$|\xi\rangle_{\eta} = \{ \xi^1, \xi^2, \dots, \xi^d \} = \{ \langle \eta^{(1)} | \xi \rangle, \langle \eta^{(2)} | \xi \rangle, \dots \}$$

So, we could write

$$|\xi\rangle = |\eta^{(i)}\rangle \xi^i$$

If we had a different basis - a change of coordinate system - $|\xi\rangle$ can be represented by it as well

$$|\xi\rangle = |e_n\rangle d^n = |e_n\rangle \xi^{n'}$$

To calculate the components again, project

$$\langle e^m | \xi \rangle = \langle e^m | e_k \rangle \xi^k = \delta_m^k \xi^k = \xi^m \quad (1)$$

As before $|\xi\rangle = |e_k\rangle \langle e^k | \xi \rangle = |e_k\rangle \xi^k$

Same vectn, different representations

$$\begin{aligned} |\xi\rangle &= |\eta_i\rangle \langle \eta^i | \xi \rangle & (1) &= |e_k\rangle \xi^k \\ &= |\eta_i\rangle \langle \eta^i | e_\ell \rangle \xi^{\ell'} & (2) & \end{aligned}$$

Expand one basis in the other

$$\begin{aligned} |\eta^{(i)}\rangle &= |e_{(n)}\rangle a_{(i)}^n \quad \text{or} \\ &= |e_{(n)}\rangle n_{(i)}^n \quad (3) \end{aligned}$$

or

$$\langle \eta^{(i)} | = \langle e^{(n)} | n_n^{(i)} \quad (4)$$

From (1) $|e_{(k)}\rangle \xi^k = |\eta_{(i)}\rangle \langle e^{(n)} | n_n^{(i)} |e_{(\ell)}\rangle \xi^{\ell'}$

$$\begin{aligned} |e_{(k)}\rangle \xi^k &= |\eta_{(i)}\rangle \langle \eta^{(i)} | \xi \rangle \\ &= |\eta_{(i)}\rangle \langle e^{(n)} | n_n^{(i)} |e_{(\ell)}\rangle \xi^{\ell'} \\ &= |\eta_{(i)}\rangle \langle e^{(n)} | e_{(\ell)} \rangle n_n^{(i)} \xi^{\ell'} \\ &= |\eta_{(i)}\rangle \delta_{\ell}^n \xi^{\ell'} n_n^{(i)} \\ &= |\eta_{(i)}\rangle n_{\ell}^{(i)} \xi^{\ell'} \end{aligned}$$

But

$$|e_{(n)}\rangle \xi^{k'} = |e_{(n)}\rangle \underbrace{n_{(i)}^n n_{\ell}^{(i)}}_{\text{must be } \delta_{\ell}^n} \xi^{\ell'}$$

$$|e_{(n)}\rangle \xi^{k'} = |e_{(n)}\rangle \xi^{n'}$$

← Σ in effect,
no indices are
dummy

$$\sum_i n_{(i)}^n n_{\ell}^{(i)} \leftarrow \text{components,}$$

↑
vector

$$= \frac{\delta_{\ell}^n}{\langle \eta^{(i)} | \eta^{(i)} \rangle} \leftarrow \text{normalized}$$

for generality

This is the condition for Completeness or Closure of the basis set $|\eta_{(i)}\rangle$

Two Basis Sets: $|\eta_i\rangle$ and $|\delta_j\rangle$

$$|\eta_{(i)}\rangle = |\delta_{(j)}\rangle \eta_{(i)}^j \quad |\delta_{(j)}\rangle = |\eta_{(k)}\rangle \delta_{(j)}^k \quad \textcircled{1}$$

$$= |\delta_{(j)}\rangle N_{ij}^j \quad = |\eta_{(k)}\rangle G_{kj}^k$$

$$|\eta_{(i)}\rangle = |\eta_{(k)}\rangle G_{kj}^k N_{ij}^j$$

Put in the Σ

$$\begin{aligned} |\eta^{(i)}\rangle &= \sum_h \sum_j |\eta^{(h)}\rangle G^h_j N^j_i \\ &= \sum_h |\eta^{(h)}\rangle \sum_j G^h_j N^j_i \end{aligned}$$

$\sum_j G^h_j N^j_i = \delta^h_i$ ← need this to be δ^h_i
 notice this looks like matrix multiplication

$$GN = I \quad \text{or} \quad G = N^{-1} \quad N = G^{-1}$$

notation!

$$\begin{array}{c} M^i_j \\ \uparrow \\ \text{row} \\ \uparrow \\ \text{column} \end{array}$$

and the transpose

$$M^T_{ij} = M^j_i$$

Had this been the duals -

$$\langle \eta^{(i)} | = \sum_j (G^j_i)^* \langle \eta^{(j)} |$$

indices aren't right!

DEFINE! $(M^j_i)^* \equiv M^*_j{}^i \equiv M^{+i}{}_j$

Tung
 convention
 Appendix A

So, $\langle \eta^{(i)} | = \sum_j G_j^* \langle \gamma^{(i)} |$

Form $\langle \gamma^{(h)} | \eta^{(i)} \rangle = \sum_j \underbrace{\langle \gamma^{(h)} | \gamma_{(j)} \rangle}_{\text{O.N.}} N^j_i \quad \text{①}$

component of $\gamma^{(h)}$
along $\eta^{(i)}$

$$= \sum_j \delta^h_j N^j_i = N^h_i$$

Notice $\langle \eta^{(h)} | \eta^{(i)} \rangle = \delta^h_i = \sum_j \langle \eta^{(h)} | \gamma_{(j)} \rangle N^j_i$

$$= \sum_j \langle \gamma_{(j)} | \eta^{(h)} \rangle^* N^j_i$$

$$= (N^j_h)^* N^j_i$$

$$= N^{+h}_j N^j_i = \delta^h_i$$

so: $N^+ N = I$

When the bases are orthonormal, N and G are unitary.
 $N^+ = N^{-1}$

$$|\eta^{(i)}\rangle = |\gamma_{(j)}\rangle N^j_i$$

$$|\gamma_{(i)}\rangle = |\eta^{(i)}\rangle N^{+i}_j$$

Expand an arbitrary vector

$$|\xi\rangle = |\eta^{(i)}\rangle \xi^i$$

$$= \underline{\underline{|\gamma_{(j)}\rangle}} \xi^{j'}$$

substitute

$$|\xi\rangle = \underline{\underline{|\gamma_{(j)}\rangle}} N^j_i \xi^i$$

Compare \equiv with \equiv

$$|z\rangle = |\delta_{(j)}\rangle \xi^{j'} = |\delta_{(j)}\rangle N^j_i \xi^i \Rightarrow N^j_i \xi^i = \xi^{j'}$$

$$N^{+i}_j \xi^{j'} = \xi^i$$

→ the same operation that connects the bases, also connects components of arbitrary vectors

EXAMPLE \mathbb{E}_3

$$\vec{x} = x \hat{i} + y \hat{j} + z \hat{k}$$

now, in the new language

$$|x\rangle = |\hat{e}_{(j)}\rangle x^j$$

or $|e_{(i)}\rangle = |e_{(j)}\rangle e^j_{(i)}$

				$i =$
\hat{i}	$e^1_{(1)} = 1$	$e^2_{(1)} = 0$	$e^3_{(1)} = 0$	1
\hat{j}	$e^1_{(2)} = 0$	$e^2_{(2)} = 1$	$e^3_{(2)} = 0$	2
\hat{k}	$e^1_{(3)} = 0$	$e^2_{(3)} = 0$	$e^3_{(3)} = 1$	3

which can be represented as

$$e_{(1)} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} \quad e_{(2)} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \quad e_{(3)} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$e^{(1)} = (1, 0, 0) \quad \text{etc.}$$

Project an arbitrary vector

$$\begin{aligned} \langle e^{(j)} | x \rangle &= e^{(j)}_{\ell} \langle e^{(\ell)} | x \rangle \\ &= e^{(j)}_{\ell} \langle e^{(\ell)} | e_{(k)} \rangle x^k \end{aligned}$$

$$= \delta^{\ell}_{ij} e^{(j)}_{\ell} x^i = e^{(j)}_{i} x^i$$

terms for dot product

So, for example

$$\begin{aligned} \langle e^{(1)} | x \rangle &= \hat{n} \cdot \vec{x} \\ &= e^{(1)}_1 x^1 + e^{(1)}_2 x^2 + e^{(1)}_3 x^3 \\ &= 1 \cdot x^1 + 0 \cdot x^2 + 0 \cdot x^3 = x^1 \end{aligned}$$

In this same way

$$\langle e^{(j)} | x \rangle = e^{(j)}_{i} x^i$$

$$x^i = \begin{pmatrix} x^1 \\ x^2 \\ x^3 \end{pmatrix}$$

$$= (1, 0, 0) \begin{pmatrix} x^1 \\ x^2 \\ x^3 \end{pmatrix} = x^1$$

This easily extends to arbitrary vectors $\vec{y} \cdot \vec{x}$

$$\begin{aligned}\langle y | x \rangle &= y_j \langle e^{(j)} | e_{(i)} \rangle x^i \\ &= \delta^j_i y_j x^i = y_i x^i \Rightarrow\end{aligned}$$

$$(y_1, y_2, y_3) \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}$$

SUBSPACES

Consider an n -dimensional vector space, V_n .

It consists of all linear combinations of n -linearly independent vectors — each spans V_n .

Choose a subset $m < n$ — and another set of L.I. vectors spans $V_m \in V_n$

The set which is orthogonal to those in V_m creates another V_m^\perp which is $(n-m)$ dimensional

V_n is decomposed $V_n = V_m \oplus V_m^\perp$

VIII Generally, two arbitrary spaces can be combined into a direct sum:

$$V_{n+m} = \underbrace{V_n^a \oplus V_m^b}_{\text{subspaces}}$$

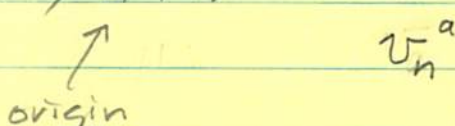
which has properties

A. vectors combine as:

$$|\xi\rangle = |\eta(a)\rangle \oplus |\eta(b)\rangle$$

B. elements of $|\xi\rangle$ ($|\eta(a)\rangle; |\eta(b)\rangle$)
another set from the
(subspaces) can combine

$$\begin{aligned} & (|\eta(a)\rangle; |\eta(b)\rangle) \oplus (|\delta(a)\rangle; |\delta(b)\rangle) \\ &= (|\eta(a)\rangle \oplus |\delta(a)\rangle; |\eta(b)\rangle \oplus |\delta(b)\rangle) \end{aligned}$$

notice $(|\eta(a)\rangle; |\phi\rangle) \rightarrow$ isomorphic to V_n^a

 origin

We can also form a direct product space

$$V_{n,m} = V_n^a \otimes V_m^b$$

with properties:

A. $|\xi\rangle \in V_{n,m} = |\eta(a)\rangle \otimes |\eta(b)\rangle$

B. $(c |\eta(a)\rangle \otimes |\eta(b)\rangle) = c (|\eta(a)\rangle \otimes |\eta(b)\rangle)$

C. $\eta(a) \otimes (\xi(b) \oplus \delta(b)) = \eta(a) \otimes \xi(b) \oplus \eta(a) \otimes \delta(b)$

D. Suppose $|\alpha_{(i)}(a)\rangle$ is basis in V^a

$|\beta_{(j)}(b)\rangle$ is " " V^b

then: $|\alpha_{(i)}(a)\rangle \otimes |\beta_{(j)}(b)\rangle$ forms an
 V_n^a V_m^b $n \times m$
 dimensional
 basis set in $V_{n,m}$

Expansion: $|\xi(a)\rangle = |\alpha_{(i)}(a)\rangle a^i = |\alpha_{(i)}(a)\rangle \sum_{[\alpha], a}^i$
 $|\eta(b)\rangle = |\beta_{(j)}(b)\rangle b^j = |\beta_{(j)}(b)\rangle \sum_{[\beta], b}^j$

So product

$$|\xi(a)\rangle \otimes |\eta(b)\rangle = \sum_{i=1}^n \sum_{j=1}^m |\alpha_{(i)}(a)\rangle \otimes |\beta_{(j)}(b)\rangle \sum_{[\alpha], a}^i \sum_{[\beta], b}^j$$

↓ notation

$$|\xi(a)\eta(b)\rangle$$

For an inner product, the spaces stay separate

$$\langle \gamma(a)\varepsilon(b) | \xi(a)\eta(b) \rangle = \langle \gamma(a) | \xi(a) \rangle \langle \varepsilon(b) | \eta(b) \rangle$$

∞ sized vector spaces are important - countably
 ∞ or continuously ∞ .

X. A compact space is defined by

Suppose for any vector $\xi \in V$ there is a series
 $(\eta_{(i)})$ with the property that \exists at least one $\eta_{(i)}$
 with

$$|\xi - \eta_{(i)}| < \epsilon \quad \epsilon \text{ arbitrarily small.}$$

Most prominent among such spaces:

Set of square-integrable functions of a
 real variable $L^2(a, b)$

Suppose we have 2 functions $f(x)$ and $g(x)$
 defined on $a \leq x \leq b$ for the continuous
 variable x .

• can combine them $h(x) = f(x) + g(x)$
 and get another function

• can form a scalar product

$$(f, g) \equiv \int_a^b f^*(x) g(x) dx$$

with norm $N_f = (f, f) = \int_a^b f^*(x) f(x) dx$
 $= \int_a^b |f(x)|^2 dx$

if the N_f is finite \Rightarrow "square integrable"

if $(f, g) = 0 \Rightarrow$ "orthogonal functions"

We can construct functional bases $\in \mathbb{L}^2(a, b)$
which can be countably infinite

and could be orthonormal:

$$\begin{aligned} (\eta^{(i)}, \eta^{(j)}) &= \int_a^b \eta^{(i)*}(x) \eta^{(j)}(x) dx \\ &= \delta_{ij} \end{aligned}$$

Can represent an arbitrary function

$$\xi(x) = \sum_{i=1}^{\infty} \eta^{(i)}(x) \xi_{[\eta]}^i(x) \quad \textcircled{1}$$

with coefficients, which are found by

$$\begin{aligned} \Delta &= \int_a^b \left| \xi(x) - \sum_{i=1}^n \eta^{(i)}(x) \xi_{[\eta]}^i \right|^2 dx \quad \text{drop } [\eta] \\ &= \int_a^b |\xi(x)|^2 dx - \int_a^b \sum_i \xi^*(x) \eta^{(i)}(x) \xi^i dx \\ &\quad - \int_a^b \sum_i \eta^{(i)*}(x) \xi_i^*(x) dx \\ &\quad + \int \sum \sum \eta^{(j)*}(x) \eta^{(i)}(x) \xi^{*j} \xi_i dx \end{aligned}$$

$$= N_{\xi} - \sum_i \left[(\xi, \eta^{(i)}) \xi^i + (\eta^{(i)}, \xi) \xi_i^* - \xi_i^* \xi^i \right]$$

minimize Δ $\frac{d\Delta}{d\xi^*} = 0 = (\eta^{(i)}, \xi) - \xi_i^*$

so $\xi^i = (\eta^{(i)}, \xi)$

and coefficients are seen to be the "best fit" by this condition:

$$\xi^i = \int_a^b \eta^{*(i)}(x) \xi(x) dx \quad (1)$$

XI. Completeness essentially says

$$\Delta \rightarrow 0 \text{ as } n \rightarrow \infty$$

$$\lim_{n \rightarrow \infty} \int_a^b \left| \xi - \sum_{i=1}^n \eta_{(i)} \xi^i \right|^2 dx = 0$$

A vector space with III, IV, V, X, XI are the definition of a Hilbert space.

notice

$$\begin{aligned} \xi(x) &= \sum_{i=1}^n \eta_{(i)}(x) \xi_{[n]}^i && (1) \\ &= \sum_{i=1}^n \eta_{(i)}(x) \int_a^b \eta^{*(i)}(x') \xi(x') dx' \\ &= \int_a^b \left\{ \sum_i \eta_{(i)}(x) \eta^{*(i)}(x') \right\} \xi(x') dx' \end{aligned}$$

which provides a definition of the Dirac δ function

$$\sum_{i=1}^{\infty} \eta_{(i)}(x) \eta_{(i)}^*(x') \equiv \delta(x-x')$$

and is the Closure or Completeness relation

This whole field came about from a series of lectures by Hilbert in 1925-1927, Von Neumann was his post doc, so the direct connection to formalizing quantum mechanics is clear. Richard Courant was Hilbert's student and wrote Courant and Hilbert based on these notes.