Bulletin NS15 Revision PA Date 28 5 2010

CW46S GPS Sensor

Description

The CW46S GPS sensor is a fully integrated module that includes the CW25 GPS receiver, DC/DC converter, RS232, RS422 interface options, and active GPS antenna — all housed in a small weatherproof (IP67 rated) enclosure.

The CW25 GPS receiver, at the center of the CW46S



sensor, has been designed specifically for acquiring and tracking satellites in weak signal areas such as under dense foliage, severe urban canyons and even inside buildings.

The CW46S can acquire satellites at signal levels down to -155 dBm with network assisted ephemeris data, and track satellites down to -155 dBm. The CW46S can also autonomously acquire satellites at signal levels as low as -143 dBm

The CW46S utilizes the CW25-TIM GPS receiver inside, allowing the CW46S to act as a complete timing module capable of outputting a GPS disciplined

frequency of 10Mhz that can achieve full PRC MTIE performance in good signal areas.

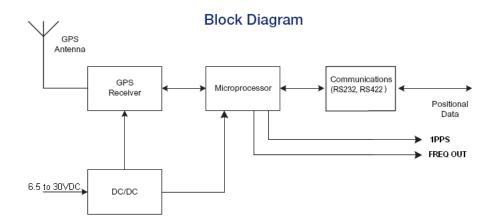
The CW46S can also continue to provide synchronization in very weak signal areas, dramatically reducing installation costs.

Features

1PPS aligned to UTC second GPS disaplined 10Mhz Wide DC Power Range IP67 Rated Waterproof Box RoHS compliant

Applications

Stratum 1 Time Source Synchronizing Wireless Networks Synchronizing Remote Switch sites





CW46S GPS SENSOR SPECIFICATIONS

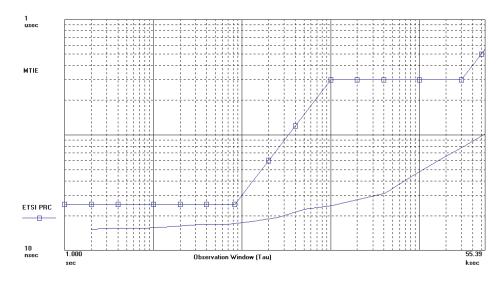
SPECIFICA ⁻	TIONS			
PhysicalMod	lule dimensions Module Rating	140mm (length) x 91mm (width) x 43mm (height) IP67		
	Supply voltage	6.5V – 30V DC (48VDC option also available)		
	Operating / Storage Temp	-30° C to $+75^{\circ}$ C / -40° C to $+85^{\circ}$ C		
	Humidity	5% to 95% non-condensing		
	Max Velocity / Altitude	515ms ⁻¹ / 18,000m		
	Max Acceleration / Jerk	4g / 1gs ⁻¹ (sustained for less than 5 seconds)		
Sensitivity	Acquisition/Tracking	-155dBm / -155dBm		
Acquisition		Cold: <45s		
Time		Warm: <38s		
		Hot: <5s		
		Re-acquisition: <0.5s (90% confidence)		
Accuracy	Position: Outdoor	<5m rms		
Accuracy	Velocity	<0.05ms ⁻¹		
	Latency	<200ms		
	Raw Measurement Accuracy	Pseudorange <0.3m rms, Carrier phase <5mm rms		
	Tracking	Code and carrier coherent		
Power	1 fix per second	0.6W typically (dependant of software build)		
Interfaces	Serial	RS232 or RS422 - Programmable Baud Rate upto 38400 default baud set to 38400		
	Protocols	NMEA 0183, Proprietary ASCII		
	1pps Timing Output	30ns rms accuracy, <5ns resolution RS422 Format		
	Frequency Output	10Mhz, Sine Wave 3.1Vp-p into 100ohms		
	Receiver Type	12 parallel channel x 32 taps up to 32 point FFT.		
		Channels, taps and FFT can be switched off to		
		minimize power or simulate simpler designs.		
General	Processor	ARM 966E-S on a 0.18 micron process at up to 120 MHz.		



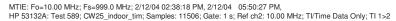
CW46S GPS MTIE PERFORMANCE

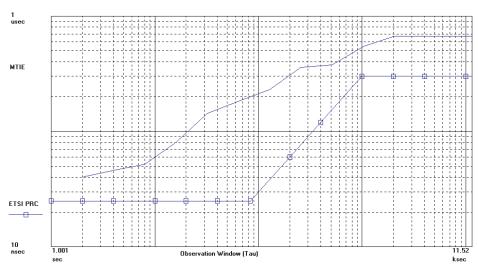
The graph below demonstrates the MTIE performance of the CW46S output frequency relative to a Cesium atomic clock, with the CW46S operating with a clear view of the sky.





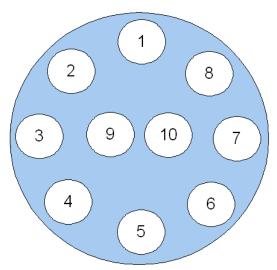
The graph below demonstrates the ability of the CW46S to continue to provide a GPS disciplined output frequency with the GPS aerial located completely inside a building (the degradation of MTIE performance is due to the effects of signal multi-path)







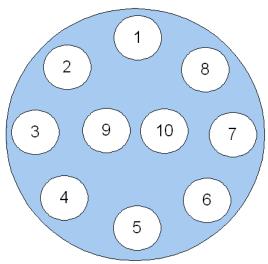
CW46S-RS232 Pin-Out



View: Looking into CW46S Connector

Pin	Name	Description
	Name	Description
1	NC	Not Connected
2	TX	Serial Transmit (RS232) Output
3	RX	Serial Receive (RS232) Input
4	PPS+	1 Pulse Per Second Signal (RS422, Non-Inverted) output
5	PPS-	1 Pulse Per Second Signal (RS422, Inverted) output
6	10M	10Mhz Freq Output, Sine Wave ~3.1Vp-p into 100ohm
7	C Shield	Cable Shield option, Can help reduce noise on timing signals
8	NC	Not Connected
9	Vin	Voltage Supply Input; +6.5V to +30V DC to be supplied here
10	GND	Ground, Power Supply return

CW46S-RS422 Pin-Out



View: Looking into CW46S Connector

Pin	Name	Description
1	RX-	Serial Receive (RS422) Inverted Input
2	TX+	Serial Transmit (RS422) Non-Inverted Output
3	RX+	Serial Receive (RS422) Non-Inverted Input
4	PPS+	1 Pulse Per Second Signal (RS422) Non-Inverted output
5	PPS-	1 Pulse Per Second Signal (RS422) Inverted output
6	10M	10Mhz Freq Output, Sine Wave ~3.1Vp-p into 100ohm
7	C Shield	Cable Shield option, Can help reduce noise on timing signals
8	TX-	Serial Transmit (RS422) Inverted Output
9	Vin	Voltage Supply Input; +6.5V to +30V DC to be supplied here
10	GND	Ground, Power Supply return

CW46S OVERVIEW & SETUP INSTRUCTIONS



Setup Instructions

	Place the CW46M where it has a good view of the sky.
1.	Secure Cable Assembly to CW46M.
2.	Connect the Comms and Timing Signals to appropiate device(s).
3.	Apply Power Supply Voltage(6.5V to 30V DC)
4.	Data should start to stream at 38400 Baud, 8 Bits, no parity, 1 stop Bit.
5.	Wait for GPS lock.
6.	The 1PPS and 10Mhz are available and are ready for use, but the CW46 will survey its position for 10minutes, typically, after which the phase error of these signals will be further reduced.

For more information on the details of the NMEA stream see Navsync's CW25 User Manual.



CW46S-RS232Cable Assembly Drawing
55.40031 RevA



CW46S GPS Sensor

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