The ICARUS read-out system

- ✓ 3D Imaging in the ICARUS LAr-TPC
- Layout, optimization and performance of front-end electronics (analogue + digital)
- Self-triggering and zero-suppression
- ✓ DAQ software, on-line display and monitoring

The ionization chamber (LAr)



 $dW = E e (v_{+} + v_{-}) dt = V_{0} i_{0} dt$ $i_{0} = e (v_{+} + v_{-}) / d \sim e v_{-} / d$ $(v_{-} \gg v_{+})$

$$Q(x) = \int i_0 dt = e (d - x) / d$$

- i_o starts as soon as the event occurs
- space resolution given by the size of the capacitor
- a charge outside the capacitor is not detected

The 3D imaging in Liquid Argon



- Yield ~ 6000 electrons / mm
- Grid transparency: $E_1/E_{drift} = E_2/E_1 > (1+\rho)/(1-\rho)$ $\rho = 2\pi r/p$ (r=wire radius)
- Wire-to-wire shielding: $\sigma = 1 + \log(\rho) p/(2\pi d)$

E₁/E_{drift} = E₂/E₁ > 1.4 σ > 92%

The induction signals





Layout of front-end electronics



ICARUS T300: ~ 27000 channels — 860 boards — 48 crates

The ICARUS T600 read-out chain



Signal UHV feed-through: 576 channels (18 connectors x 32) + HV wire biasing CAEN-V789 board: 2 Daedalus VLSI * 16 input channels (local self-trigger & zero suppression) + memory buffers + data out on VME bus



CAEN-V791 board: 32 pre-amplifiers + 4 multiplexers (8:1) + 4 FADC's (10 bits - 20 MHz) Decoupling board: HV distribution and signal input

The T600 electronic racks



The analogue board CAEN-V791



Input signals & pre-amp feedback RC

Ext. & Int. planes:

- Approx. unipolar input signal
- Width ≥ 3 *µ*s
- Short RC ("quasi-current" mode) to minimized pile-up
- Mid. Plane:
 - Bipolar signal
 - Long RC ("quasi-charge" mode) to get triangular signals





Optimization of the Analogue boards

✓ Goals (V791C & V791 Q):

- Signal P.H. ~ 12 ADC for 3 mm m.ip.
- Noise r.m.s ~ 1 ADC
- FWHM ~ 5 μs
- Action on:
 - feedback RC
 - Gain and bandwidth of "baseline restorer"

Results:



Model	Rf	Cf	Rp	Ra	R1	R2	R3	R4	Cs	Cu	Cz
V791C	10 Μ Ω	3.3 pF ±10%	1.2 k Ω	22 k Ω	100 k Ω	270 k Ω	27 k Ω	10 k Ω	39 pF	2.2 nF	1 μF
V791Q	100 Μ Ω	1 pF ±10%	$\Omega \propto \Omega$	0Ω	33 k Ω	270 k Ω	270 k Ω	33 k Ω	3.9 pF	2.2 nF	1 nF

Overall decay time constants: ~3µs (V791C) , ~30µs (V791Q)

Performance of the V791 boards



Performance of the V791C boards

Single wire waveforms (horiz. axis unit = 400 ns)



RMS noise on T600 = 1.7 ADC counts (due to difficult environment in Pavia)

Performance of the V791Q boards

Single wire waveforms (horiz. axis unit = 400 ns)



- Pulse height & shape from mid. plane wires very similar to those from collection plane wires.
- High frequency S/N also comparable.
- Low frequency minimized by shaper.



Low frequency noise visible but not dangerous! h.f. noise on T600 = 1.5 ADC counts

Events from the T600 semi-module

Drift time (1.5m)



Collection view

Wire numbering (4.5m)



Induction2 view

Wire numbering (4.5m)



Event reconstruction



- ✓ Signal fit:
 - B = baseline
 - A = amplitude
 - τ_1 = risetime
 - τ_2 = falltime
 - x₀ = peak position



- ✓ Landau parameters $(dE/dx, \xi)$ in agreement with expectation after:
 - Test pulse energy calibration
 - Free electron lifetime correction

The digital board CAEN-V789





DAEDALUS: on-line zero suppressor and local trigger enabler



Zero-Suppression Algorithm Hitfinder + TileBuilding



Daedalus:

detects signal Rising-Edge, Falling-Edge, Width... and generates a hitfound signal TriggerLogic: handles a 16 channels group and builds a data tile around the hit **Present Performance** on T300 RawData: Efficiency= 97% Collection 90% Induction 1 & 2 False Detections= 20% Studies underway for improvement of algorithm (promising...)

Event builder operating modes

External trigger:

PMT + Full Drift Imaging Analog OR

- Limited in bandwidth (≈1 Hz max rate for 1.5 ms drift). Maximum of two events pile-up before deadtime.
- External Enable:

PMT

- + Daedalus hit finding Analog OR
- Bandwidth allows up to 1k event "tiles" (25 μ s · 16 wires) per second per readout crate. Daedalus thresholds can be more tolerant without overflooding readout.
- Internal FIFO's can accept up to 128 fragments.
- Daedalus hit finding **Open Shutter:**
 - Same bandwidth as above. Useful to collect low energy events.
 - Drawback is that correlated noise bursts even at low repetition rate (few per second) would easily saturate the DAQ channel.



96 (+4 spares) units on the t600





Air tight structure (to reduce post installation servicing). Fan controlled air flow through the alu heat exchanger moderates internal temperature. A custom unit allows remote probing and control of rack status via an I2C interface.



T600 Builder Overview All communication channles are over tcp/ip sockets. Handles communications with run control to Cpu Software Task start, stop, housekeep and configure Data are pushed - flow control relies on protocol features Manager Builder DATA Head Samples 'EVM determines data destination Writer STAT Status Time according to periodic status messages Task ERRO Message sent from writers Task(s) CONF conf status Local Buffering Synchronization uses absolute time Controls tagging readout Mem Management Task hardware icab Deals with memory allocation and stats Accept connections. INIT PARAM Spawns data collection threads STAT **DEDP** PARAM Task Deals with EVM ERRO TRGP PARAM **EVEN PARAM** Manager STRT STAT STOP ERRO Writer Collect data fragments, Broadcasts configurations strip sync messages, Task Spawns control threads pthread(s) Merge data on a file Manager Handles sync Control File System WriterSoftware pthread(s) mpicasr WINI PARAM Conf Trig Contro WRIT PARAM Database EVEN PARAM configuration Controls DAQ busy STRT to storage mpicaevm STOP FVM sync

Lossless Compression Scheme



Each sample is coded on 4 bits as the difference between itself and the previous sample (throwing the 6 bits carrying daedalus output). Should the difference be outside 4-bit boundaries (< 1% of samples), a flag is raised and the full 16 bits value is then used.