

LorentzPendulum

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In[882]:= Clear["Global`*"]
```

Pendulum with a given time-dependent length $r[t]$

```
In[883]:= T = (1/2) * M * (r'[t]^2 + (r[t] * theta'[t])^2)
```

```
Out[883]:=  $\frac{1}{2} M (r'[t]^2 + r[t]^2 \theta'[t]^2)$ 
```

```
In[884]:= V = -M * g * r[t] * Cos[theta[t]]
```

```
Out[884]:=  $-g M \text{Cos}[\theta[t]] r[t]$ 
```

Make small-angle approximation

```
In[885]:= Vsmall = Normal[Series[V, {theta[t], 0, 2}]]
```

```
Out[885]:=  $-g M r[t] + \frac{1}{2} g M r[t] \theta[t]^2$ 
```

```
In[886]:= tmp = Expand[T - Vsmall]
```

```
Out[886]:=  $g M r[t] - \frac{1}{2} g M r[t] \theta[t]^2 + \frac{1}{2} M r'[t]^2 + \frac{1}{2} M r[t]^2 \theta'[t]^2$ 
```

Drop terms that contribute only constant to $\text{Integral}[L * dt]$

```
In[887]:= L = tmp - Part[tmp, 1] - Part[tmp, 3]
```

```
Out[887]:=  $-\frac{1}{2} g M r[t] \theta[t]^2 + \frac{1}{2} M r[t]^2 \theta'[t]^2$ 
```

```
In[888]:= ptheta = D[L, theta'[t]]
```

```
Out[888]:=  $M r[t]^2 \theta'[t]$ 
```

```
In[889]:= sol = Solve[ptheta == Ptheta[t], theta'[t]]
```

```
Out[889]:=  $\left\{ \left\{ \theta'[t] \rightarrow \frac{P\theta[t]}{M r[t]^2} \right\} \right\}$ 
```

```
In[890]:= H = (ptheta * theta'[t] - L) /. sol[[1]]
```

```
Out[890]:=  $\frac{P\theta[t]^2}{2 M r[t]^2} + \frac{1}{2} g M r[t] \theta[t]^2$ 
```

Use theorem: $dH/dt = \text{partial } dH/ \text{partial } dt$

In[891]:= $dHdt = D[H, r[t]] * drdt$

Out[891]=
$$drdt \left(-\frac{P\theta[t]^2}{M r[t]^3} + \frac{1}{2} g M \theta[t]^2 \right)$$

In[892]:= $dHdr = dHdt / drdt$

Out[892]=
$$-\frac{P\theta[t]^2}{M r[t]^3} + \frac{1}{2} g M \theta[t]^2$$

In[893]:= $KE = \text{Part}[H, 1]$

Out[893]=
$$\frac{P\theta[t]^2}{2 M r[t]^2}$$

In[894]:= $PE = \text{Part}[H, 2]$

Out[894]=
$$\frac{1}{2} g M r[t] \theta[t]^2$$

For slowly varying $r[t]$, KE and PE both average to $HH/2$ (where $HH=H$)

In[895]:= $sol1 = \text{Solve}[KE == HH/2, P\theta[t]]$

Out[895]=
$$\left\{ \left\{ P\theta[t] \rightarrow -\sqrt{HH} \sqrt{M} r[t] \right\}, \left\{ P\theta[t] \rightarrow \sqrt{HH} \sqrt{M} r[t] \right\} \right\}$$

In[896]:= $sol2 = \text{Solve}[PE == HH/2, \theta[t]]$

Out[896]=
$$\left\{ \left\{ \theta[t] \rightarrow -\frac{\sqrt{HH}}{\sqrt{g} \sqrt{M} \sqrt{r[t]}} \right\}, \left\{ \theta[t] \rightarrow \frac{\sqrt{HH}}{\sqrt{g} \sqrt{M} \sqrt{r[t]}} \right\} \right\}$$

In[897]:= $dHHdr = ((dHdr /. sol1[[1]]) /. sol2[[1]]) /. r[t] \rightarrow r$

Out[897]=
$$-\frac{HH}{2 r}$$

Easy to solve $d(HH)/dr = -HH/(2*r)$

In[898]:= $DSolve[HH'[r] == (-1/2) * HH[r] / r, HH[r], r]$

Out[898]=
$$\left\{ \left\{ HH[r] \rightarrow \frac{C[1]}{\sqrt{r}} \right\} \right\}$$

HH varies as $1/\text{Sqrt}[r]$; so PE varies as $1/\text{Sqrt}[r]$, so θ^2 varies as $r^{-3/2}$;

so amplitude in θ varies as $r^{-3/4}$. Hence horizontal displacement $x=r*\theta$

varies as $r^{1/4}$.

Explicit example: let r vary linearly with time.

In[899]:= **Hexample** = **H** /. **r[t] → v * t**

Out[899]= $\frac{P\theta[t]^2}{2 M t^2 v^2} + \frac{1}{2} g M t v \theta[t]^2$

In[900]:= **Clear**[**thetadot**]

In[901]:= **sol** = **Solve**[**thetadot** == **D**[**Hexample**, **Ptheta[t]**], **Ptheta[t]**]

Out[901]= $\{\{P\theta[t] \rightarrow M t^2 \text{thetadot } v^2\}\}$

In[902]:= **Pth** = (**Ptheta[t]** /. **sol**[[1]]) /. **thetadot** → **theta'**[**t**]

Out[902]= $M t^2 v^2 \theta'[t]$

In[903]:= **pthetadot** = **-D**[**Hexample**, **theta[t]**]

Out[903]= $-g M t v \theta[t]$

In[904]:=

In[905]:= **zero** = **Simplify**[(**D**[**Pth**, **t**] - **pthetadot**) / (**M * v^2 * t**)]

Out[905]= $\frac{g \theta[t]}{v} + 2 \theta'[t] + t \theta''[t]$

In[906]:= **DSolve**[\{\{**zero** /. {**g** → **1**, **v** → **1**}\} == **0**, **theta**[**10**] == **1**, **theta'**[**10**] == **0**\}, **theta**[**t**], **t**]

Out[906]= $\{\{\theta[t] \rightarrow \frac{(10 \text{BesselJ}[1, 2\sqrt{t}] \text{BesselY}[0, 2\sqrt{10}] - \sqrt{10} \text{BesselJ}[1, 2\sqrt{t}] \text{BesselY}[1, 2\sqrt{10}] - 10 \text{BesselJ}[0, 2\sqrt{10}] \text{BesselY}[1, 2\sqrt{t}] + \sqrt{10} \text{BesselJ}[1, 2\sqrt{10}] \text{BesselY}[1, 2\sqrt{t}] + 10 \text{BesselJ}[2, 2\sqrt{10}] \text{BesselY}[1, 2\sqrt{t}] - 10 \text{BesselJ}[1, 2\sqrt{t}] \text{BesselY}[2, 2\sqrt{10}])}{(\sqrt{10} \sqrt{t} (\text{BesselJ}[1, 2\sqrt{10}] \text{BesselY}[0, 2\sqrt{10}] - \text{BesselJ}[0, 2\sqrt{10}] \text{BesselY}[1, 2\sqrt{10}] + \text{BesselJ}[2, 2\sqrt{10}] \text{BesselY}[1, 2\sqrt{10}] - \text{BesselJ}[1, 2\sqrt{10}] \text{BesselY}[2, 2\sqrt{10}])}\}\}$

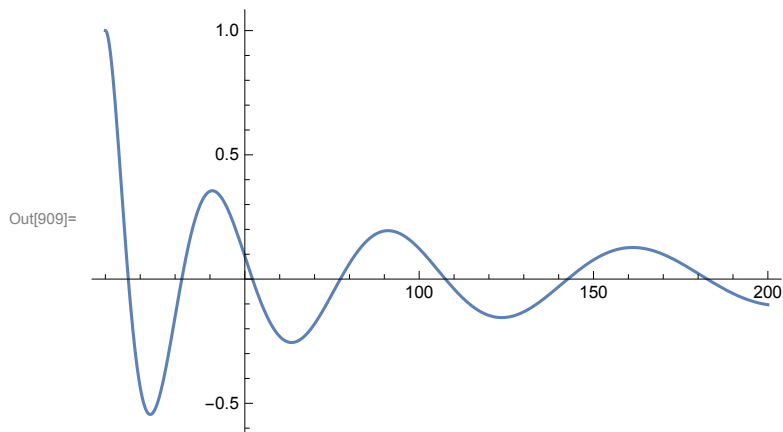
In[907]:= **th** = **Simplify**[**theta**[**t**] /. %[[1]]]

Out[907]= $\left((-10 \text{BesselJ}[0, 2\sqrt{10}] + \sqrt{10} \text{BesselJ}[1, 2\sqrt{10}] + 10 \text{BesselJ}[2, 2\sqrt{10}]) \text{BesselY}[1, 2\sqrt{t}] + \text{BesselJ}[1, 2\sqrt{t}] (10 \text{BesselY}[0, 2\sqrt{10}] - \sqrt{10} \text{BesselY}[1, 2\sqrt{10}] - 10 \text{BesselY}[2, 2\sqrt{10}]) \right) / (\sqrt{10} \sqrt{t} ((-\text{BesselJ}[0, 2\sqrt{10}] + \text{BesselJ}[2, 2\sqrt{10}]) \text{BesselY}[1, 2\sqrt{10}] + \text{BesselJ}[1, 2\sqrt{10}] (\text{BesselY}[0, 2\sqrt{10}] - \text{BesselY}[2, 2\sqrt{10}])))$

In[908]:= **thsimple** = **FullSimplify**[**th**]

Out[908]= $-10 \pi \text{BesselY}[2, 2\sqrt{10}] \text{Hypergeometric0F1}[2, -t] + \frac{1}{\sqrt{t}} 50 \pi \text{BesselY}[1, 2\sqrt{t}] \text{Hypergeometric0F1}[3, -10]$

```
In[909]:= Plot[thsimple, {t, 10, 200}, PlotRange -> All]
```



```
In[910]:= max1 = FindMaximum[thsimple, {t, 10}]
```

FindMaximum::fmgz : Encountered a gradient that is effectively zero. The result returned may not be a maximum; it may be a minimum or a saddle point. >>

```
Out[910]= {1., {t -> 10.}}
```

```
In[911]:= max2 = FindMaximum[thsimple, {t, 160}]
```

```
Out[911]= {0.127069, {t -> 161.23}}
```

```
In[912]:= Solve[max2[[1]]/max1[[1]] == ((t /. max2[[2]])/(t /. max1[[2]]))^power, power]
```

Solve::ifun :

Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information. >>

```
Out[912]= {{power -> -0.742031}}
```

Close to the predicted -0.75

```
In[913]:= Hexample = H /. r[t] -> v * t
```

```
Out[913]=  $\frac{P\theta[t]^2}{2 M t^2 v^2} + \frac{1}{2} g M t v \theta[t]^2$ 
```

```
In[914]:= Clear[thetadot]
```

```
In[915]:= sol = Solve[thetadot == D[Hexample, Ptheta[t]], Ptheta[t]]
```

```
Out[915]= {{Ptheta[t] -> M t^2 thetadot v^2}}
```

```
In[916]:= Pth = (Ptheta[t] /. sol[[1]]) /. thetadot -> theta'[t]
```

```
Out[916]= M t^2 v^2 theta'[t]
```

```
In[917]:= pthetadot = -D[Hexample, theta[t]]
```

```
Out[917]= -g M t v theta[t]
```

```
In[918]=
```

In[919]:= **zero = Simplify[(D[Pth, t] - pthetadot) / (M * v^2 * t)]**

Out[919]= $\frac{g \theta[t]}{v} + 2 \theta'[t] + t \theta''[t]$

In[920]:= **DSolve[{(zero /. {g → 1, v → 1}) == 0, theta[100] == 1, theta'[100] == 0}, theta[t], t]**

Out[920]= $\left\{ \left\{ \theta[t] \rightarrow \left(10 \text{BesselJ}[1, 2 \sqrt{t}] \text{BesselY}[0, 20] - \text{BesselJ}[1, 2 \sqrt{t}] \text{BesselY}[1, 20] - 10 \text{BesselJ}[0, 20] \text{BesselY}[1, 2 \sqrt{t}] + \text{BesselJ}[1, 20] \text{BesselY}[1, 2 \sqrt{t}] + 10 \text{BesselJ}[2, 20] \text{BesselY}[1, 2 \sqrt{t}] - 10 \text{BesselJ}[1, 2 \sqrt{t}] \text{BesselY}[2, 20] \right) / \left(\sqrt{t} (\text{BesselJ}[1, 20] \text{BesselY}[0, 20] - \text{BesselJ}[0, 20] \text{BesselY}[1, 20] + \text{BesselJ}[2, 20] \text{BesselY}[1, 20] - \text{BesselJ}[1, 20] \text{BesselY}[2, 20]) \right) \right\} \right\}$

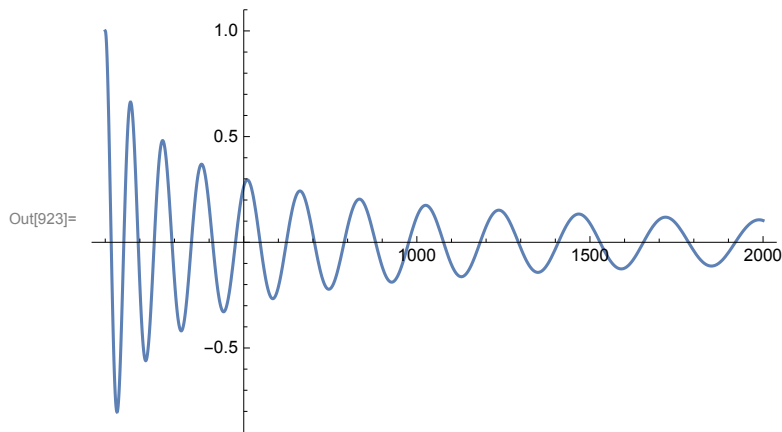
In[921]:= **th = Simplify[theta[t] /. %[[1]]]**

Out[921]= $\left((-10 \text{BesselJ}[0, 20] + \text{BesselJ}[1, 20] + 10 \text{BesselJ}[2, 20]) \text{BesselY}[1, 2 \sqrt{t}] + \text{BesselJ}[1, 2 \sqrt{t}] (10 \text{BesselY}[0, 20] - \text{BesselY}[1, 20] - 10 \text{BesselY}[2, 20]) \right) / \left(\sqrt{t} ((-\text{BesselJ}[0, 20] + \text{BesselJ}[2, 20]) \text{BesselY}[1, 20] + \text{BesselJ}[1, 20] (\text{BesselY}[0, 20] - \text{BesselY}[2, 20])) \right)$

In[922]:= **thsimple = FullSimplify[th]**

Out[922]= $\frac{1}{\sqrt{t}} 100 \pi \left(\text{BesselJ}[2, 20] \text{BesselY}[1, 2 \sqrt{t}] - \text{BesselJ}[1, 2 \sqrt{t}] \text{BesselY}[2, 20] \right)$

In[923]:= **Plot[thsimple, {t, 100, 2000}, PlotRange → All]**



In[924]:= **max1 = FindMaximum[thsimple, {t, 100}]**

FindMaximum::fmgz : Encountered a gradient that is effectively zero. The result returned may not be a maximum; it may be a minimum or a saddle point. >>

Out[924]= {1., {t → 100.}}

In[925]:= **max2 = FindMaximum[thsimple, {t, 2000}]**

Out[925]= {0.106428, {t → 1988.61}}

```
In[926]= Solve[max2[[1]]/max1[[1]] == ((t /. max2[[2]]) / (t /. max1[[2]]))^power, power]
```

Solve::ifun :

Inverse functions are being used by Solve, so some solutions may not be found; use Reduce for complete solution information. >>

```
Out[926]= {{power -> -0.749255}}
```

Even Closer to the predicted -0.75